## Rendering 3D Scenes



Model \& Camera Parameters

Rendering Pipeline
Framebuffer
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## Camera Models



## The most common model is pin-hole camera

- All captured light rays arrive along paths toward focal point without lens distortion (everything is in focus)
- Sensor response proportional to radiance

Other models consider ... Depth of field Motion blur Lens distertion


## Camera Parameters



What are the parameters of a camera?


## Camera Parameters



## Position

- Eye position (px, py, pz)

Orientation

- View direction (dx, dy, dz)
- Up direction (ux, uy, uz)

Aperture

- Field of view (xfov, yfov)

Film plane

- "Look at" point

- View plane normal


## Moving the camera



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## The Rendering Pipeline



## Rendering: Transformations



We've learned about transformations
But they are used in three ways:

- Modeling transforms
- Viewing transforms (Move the camera)
- Projection transforms (Change the type of camera)


## The Rendering Pipeline: 3-D



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## The Rendering Pipeline: 3-D



Scene graph Object geometry

Modeling Transforms

Lighting Calculations


## Result:

- All vertices of scene in shared 3-D "world" coordinate system



## Rendering: Transformations



## Modeling transforms

- Size, place, scale, and rotate objects and parts of the model w.r.t. each other
- Object coordinates -> world coordinates



## The Rendering Pipeline: 3-D




Modeling
Transforms
Lighting
Calculations
Viewing
Transform


Projection Transform

## Result:

-All geometric primitives are illuminated


## Lighting Simulation



## Lighting parameters



## Lighting Simulation



## Direct illumination

Light
Source

- Ray casting
- Polygon shading

Global illumination

- Ray tracing
- Monte Carlo methods
- Radiosity methods

More on these methods later!

Surface

Camera

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## The Rendering Pipeline: 3-D



Scene graph Object geometry

Modeling Transforms

Lighting Calculations

Viewing Transform

Clipping

Projection Transform

## Result:

- Scene vertices in 3-D "view" or "camera" coordinate system



## Rendering: Transformations

## Viewing transform

- Rotate \& translate the world to lie directly in front of the camera
- Typically place camera at origin
- Typically looking down -Z axis
- World coordinates $\Rightarrow$ view coordinates


## The Rendering Pipeline: 3-D



Scene graph
Object geometry
Modeling Transforms

Lighting Calculations

Viewing
Transform

Clipping

Projection Transform

## Result:

- Remove geometry that is out of view



## Assignment 2



## Due two and a half weeks from today

- Project description available online
- We'll discuss details in class on Monday


## The Rendering Pipeline: 3-D



Scene graph
Object geometry
Modeling Transforms

Lighting Calculations

Viewing
Transform

Clipping

Projection Transform

## Result:

-2-D screen coordinates of clipped vertices


## Rendering: Transformations



## Projection transform

- Apply perspective foreshortening
-Distant = small: the pinhole camera model
- View coordinates $\Rightarrow$ screen coordinates


## Rendering: Transformations



## Perspective Camera

## Orthographic Camera



## Rendering 3D Scenes



Model \& Camera Parameters

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## Rasterize

## Convert screen coordinates to pixel colors



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## Summary

## Geometric primitives

- Points, vectors

Operators on these primitives

- Dot product, cross product, norm


## The rendering pipeline

- Move models, illuminate, move camera, clip, project to display, rasterize

