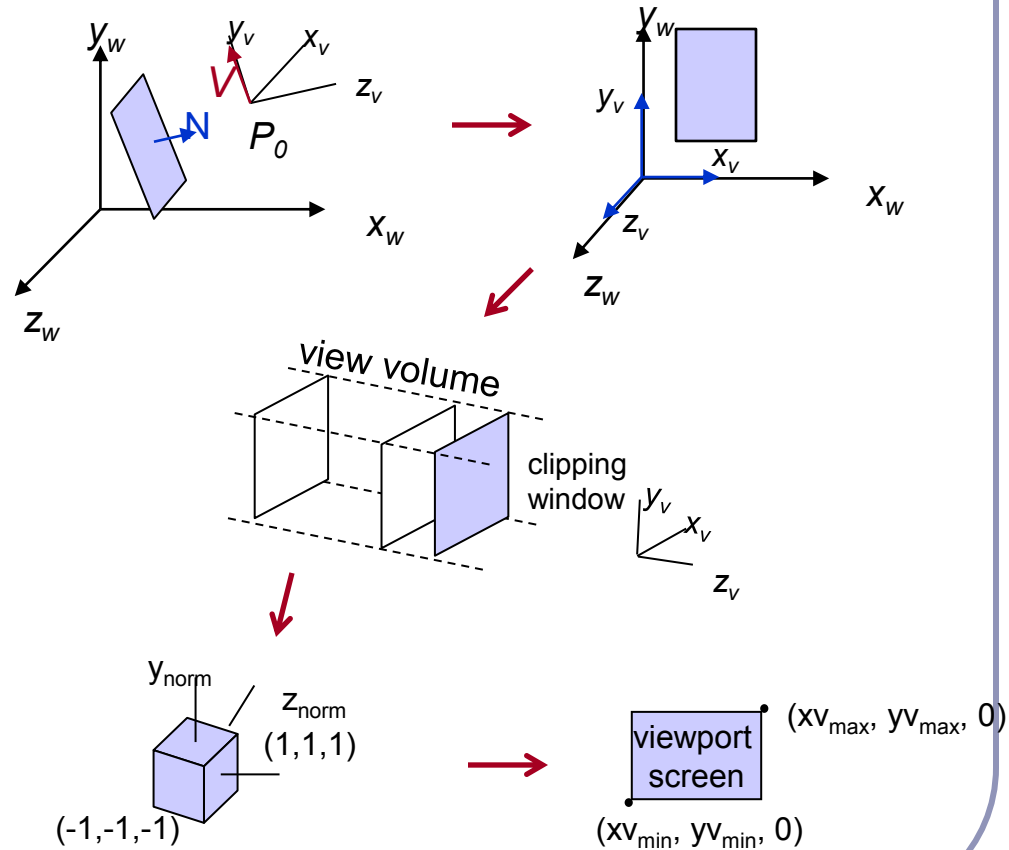
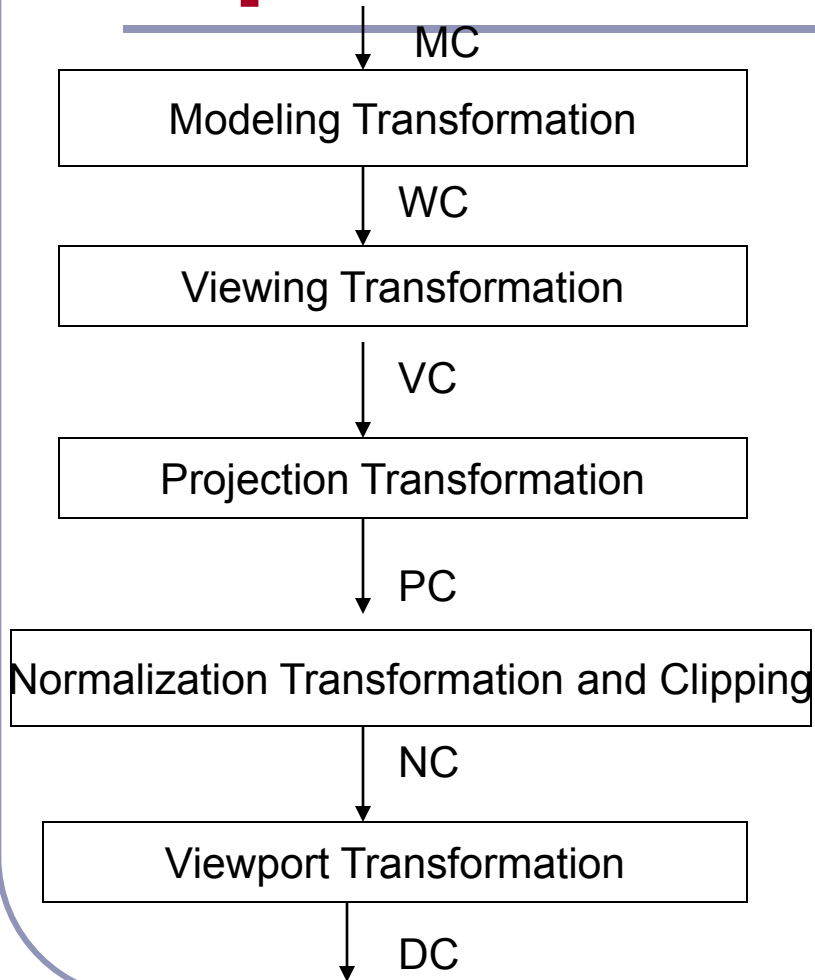


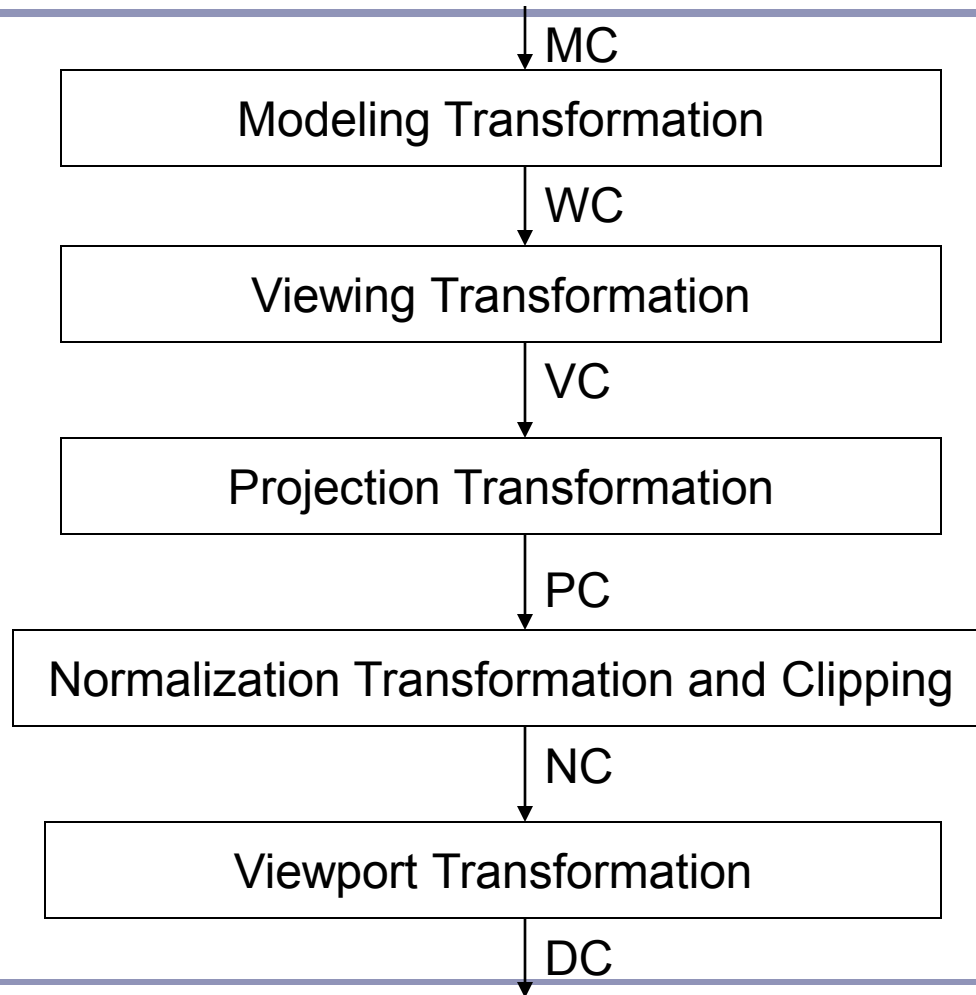
# 3D Viewing

# 3D Viewing Transformation Pipeline

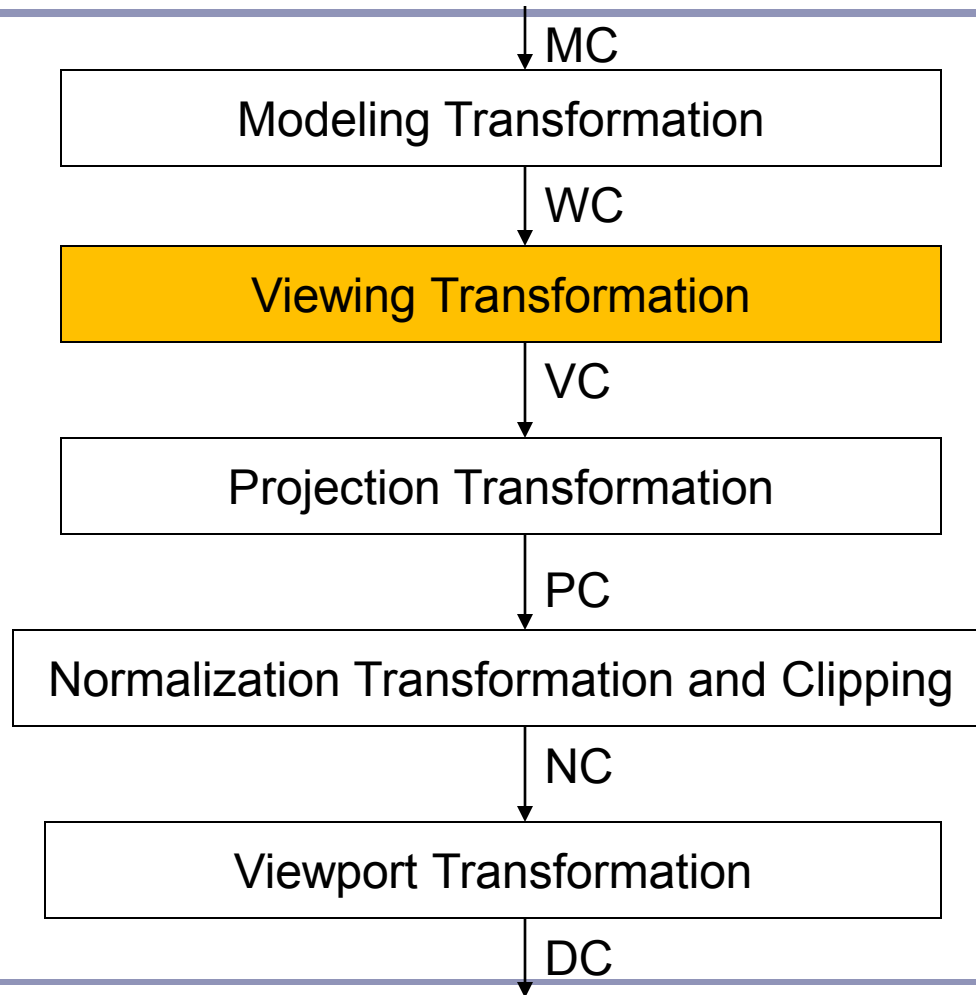


# 3D Viewing Transformation Pipeline

---

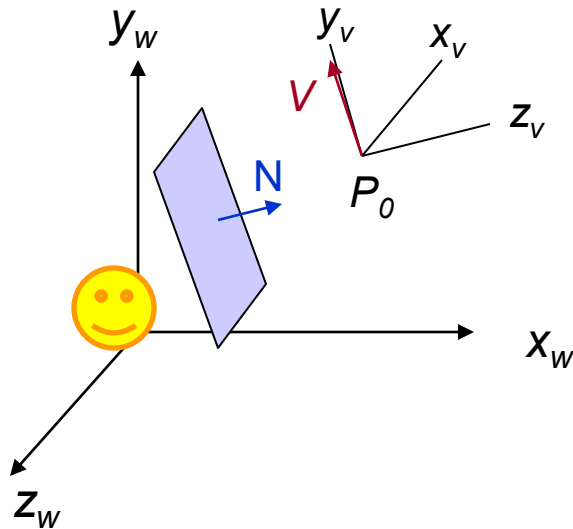


# 3D Viewing Transformation Pipeline



# 3D Viewing

---



**$V$**  view up vector

**$P_0 = (x_0, y_0, z_0)$**  view point

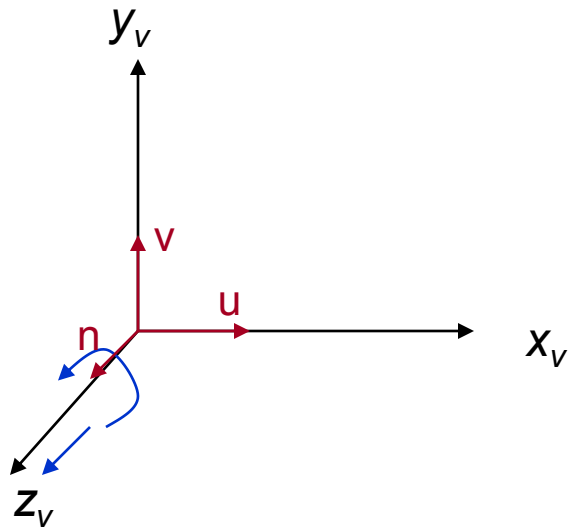
**$N$**  viewplane normal

**Viewplane is at point  $z_{vp}$  in negative  $z_v$  direction**

**$V$  is perpendicular to  $N$**

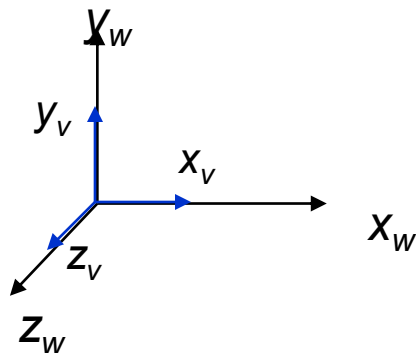
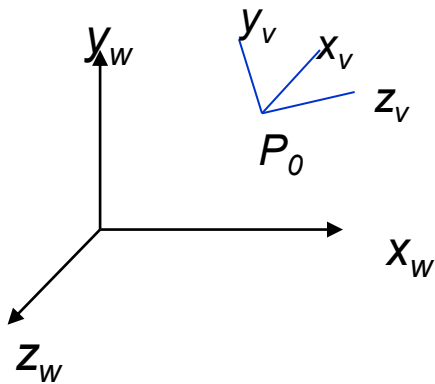
# 3D Viewing

---



$x_v y_v z_v$  is a *right-handed* viewing coordinate system

# 3D Viewing



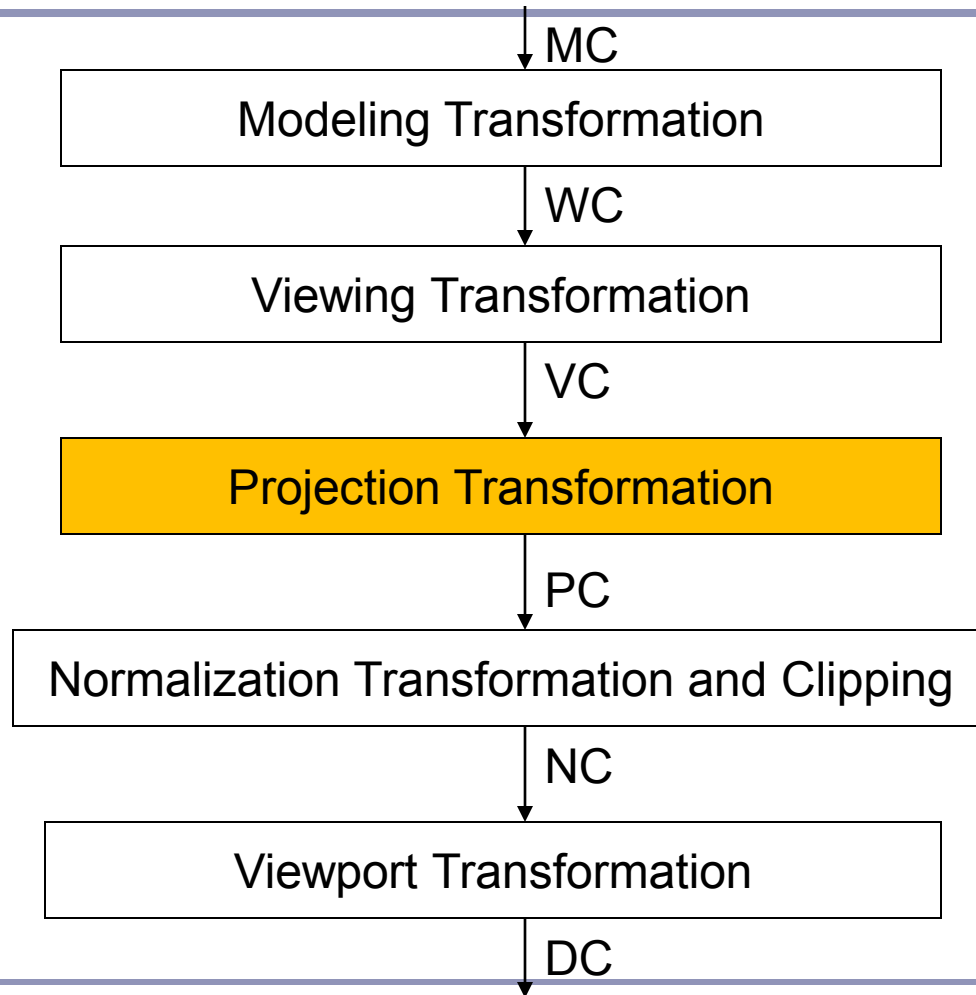
**Transformation from World to Viewing Coordinates:**

- 1. Translate viewing coordinate origin to the origin of world coordinate system**
- 2. Apply rotations to align  $x_v$   $y_v$   $z_v$  axes with  $x_w$   $y_w$   $z_w$  axes respectively**

$$M_{WC,VC} = R \cdot T$$

# 3D Viewing Transformation Pipeline

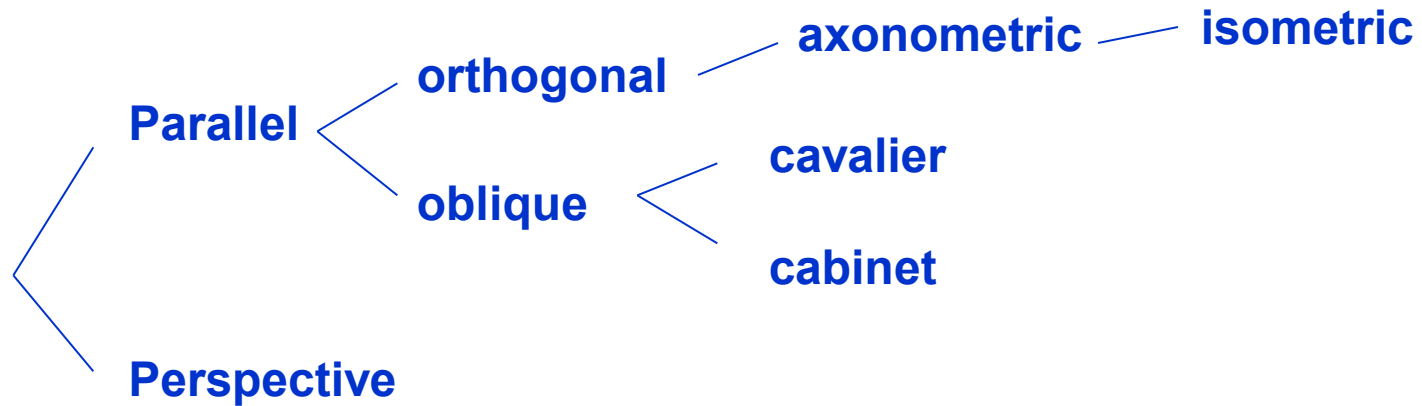
---





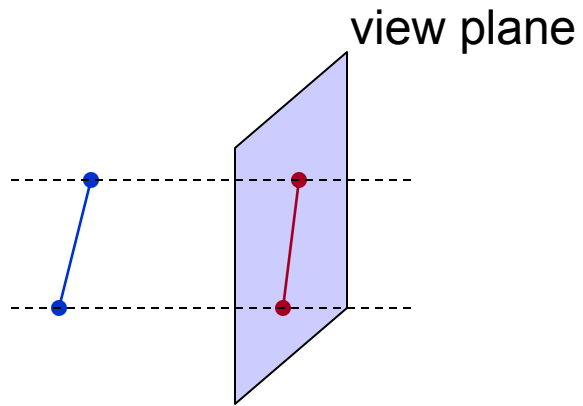
# Projections

---

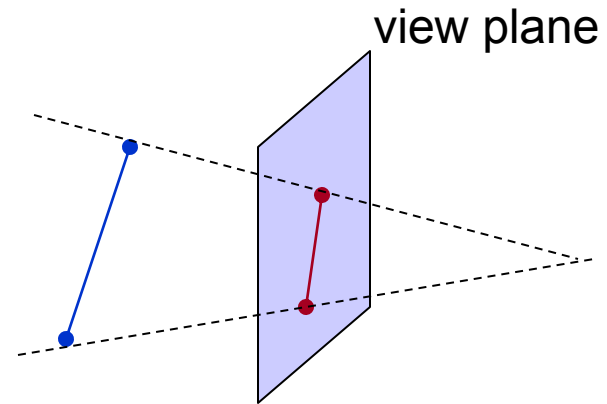


# Projections

---



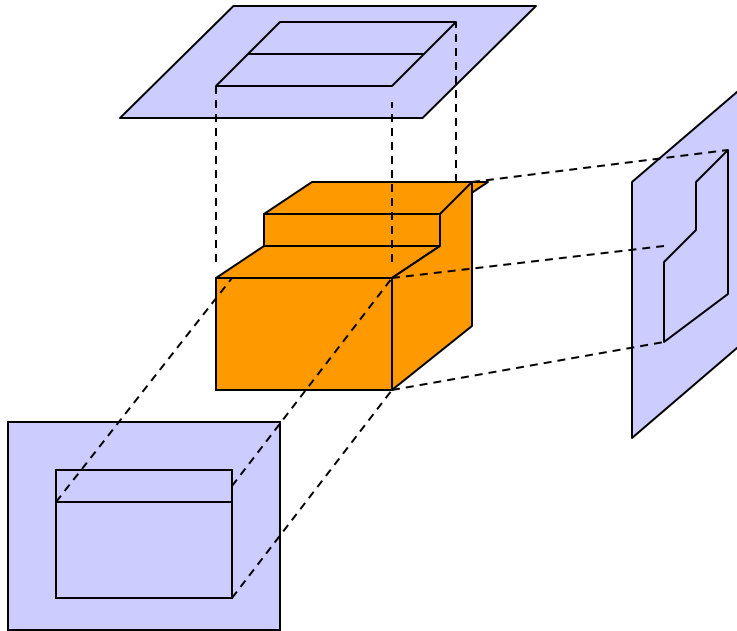
**Parallel projection**



**Perspective projection**

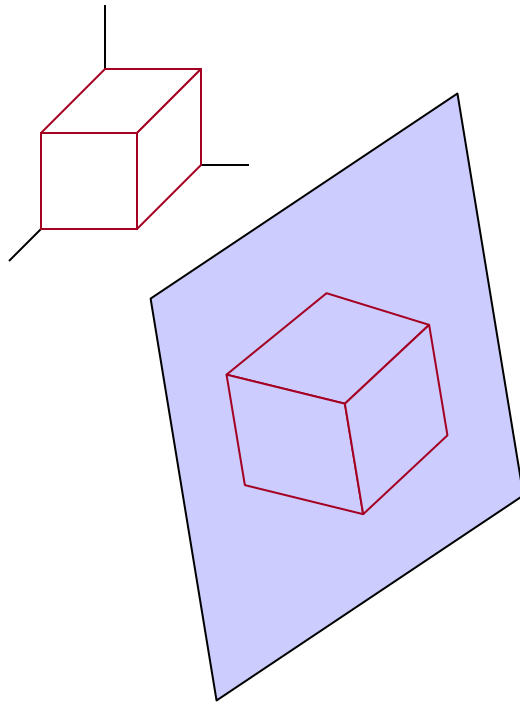
# Orthogonal Projection

---



# Orthogonal Projection

---



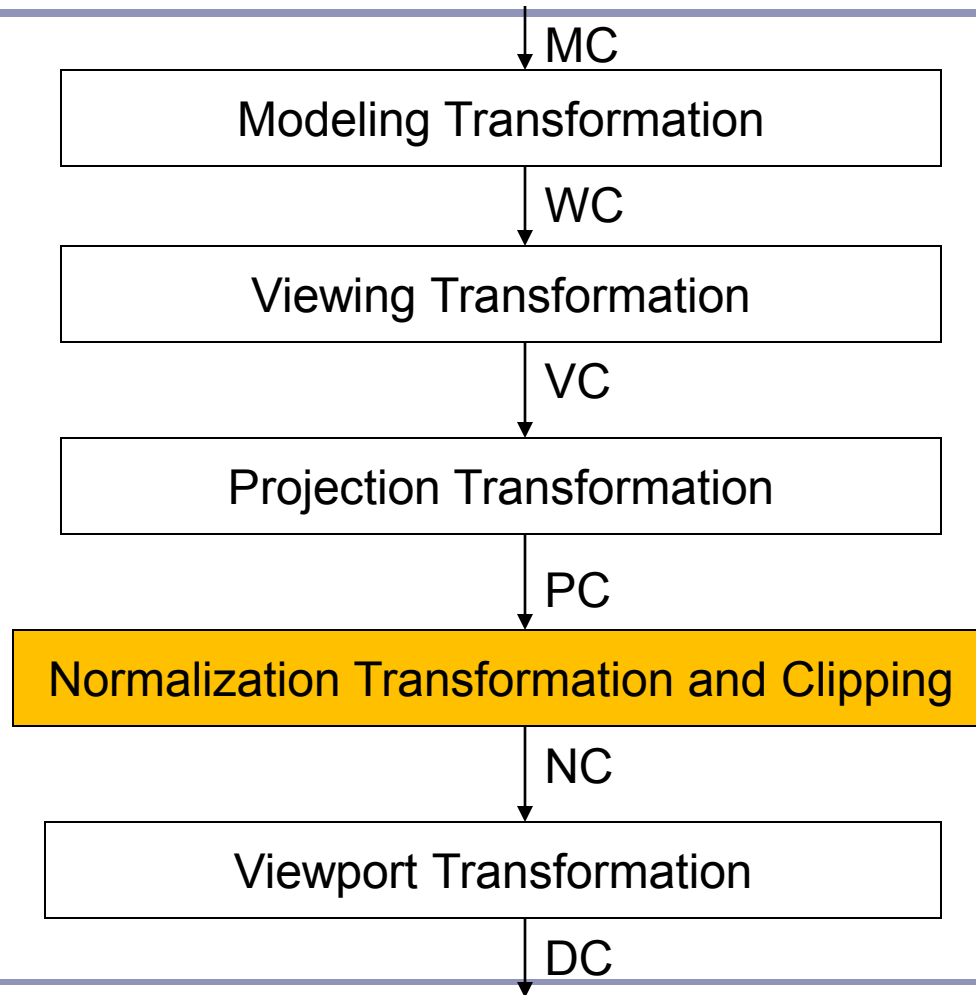
Isometric

***Axonometric:*** displays more than one face of an object

***Isometric:*** projection plane intersects each coordinate axis at the same distance from the origin

# 3D Viewing Transformation Pipeline

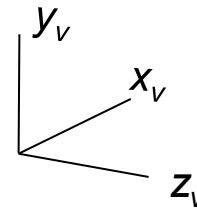
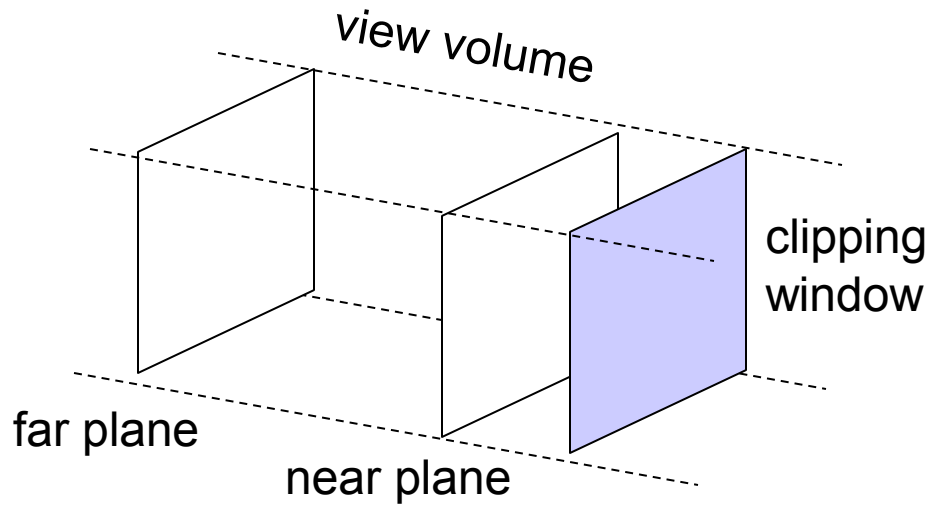
---



# Orthogonal Projection

---

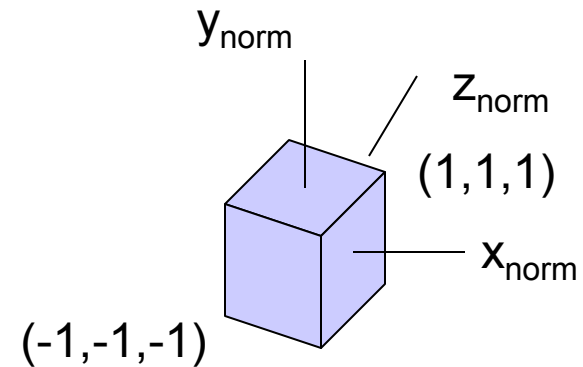
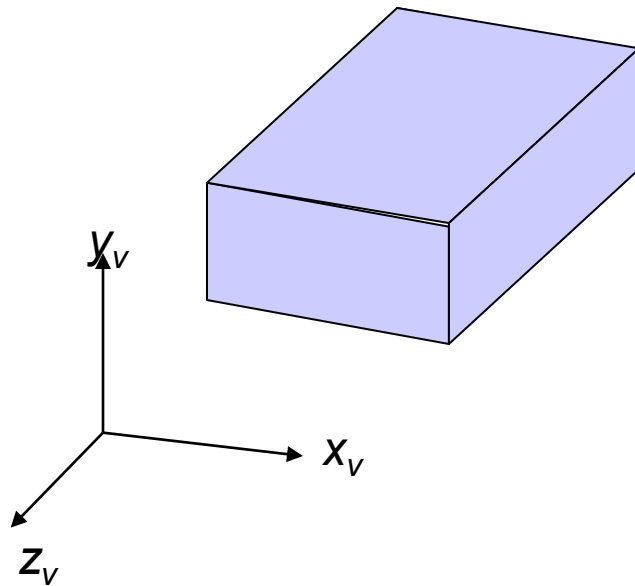
## *Clipping*



# Orthogonal Projection

---

## *Normalization*

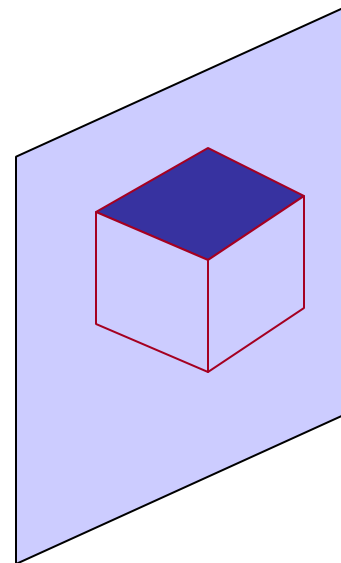
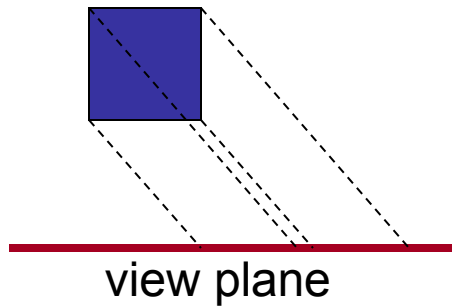


$$M_{ortho,norm} \cdot R \cdot T$$

# Oblique Projection

---

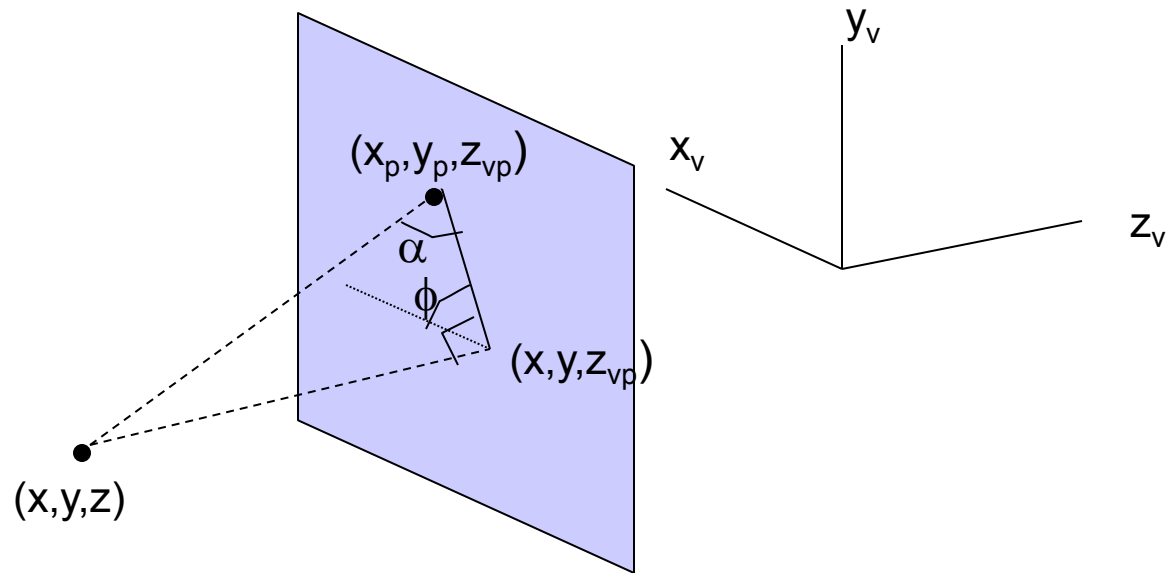
*Oblique projection: projection path is not perpendicular to the view plane*





# Oblique Projection

---

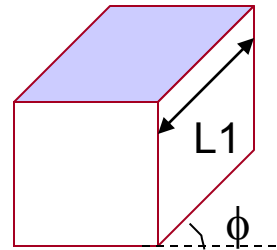
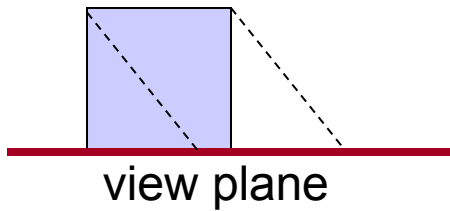


# Oblique Projection

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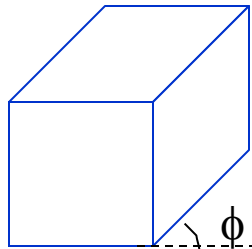
$$x_p = x + L_1 (z_{vp} - z) \cos \phi$$
$$y_p = y + L_1 (z_{vp} - z) \sin \phi$$

*shearing transformation*

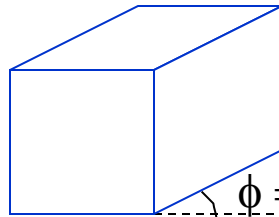


# Oblique Projection

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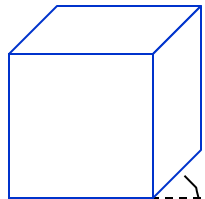


$\phi = 45^\circ$

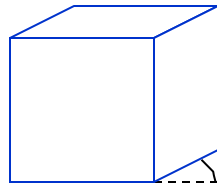


$\phi = 30^\circ$

***Cavalier Projection***



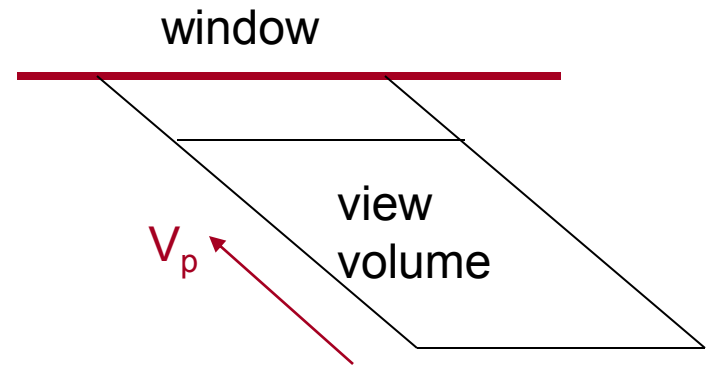
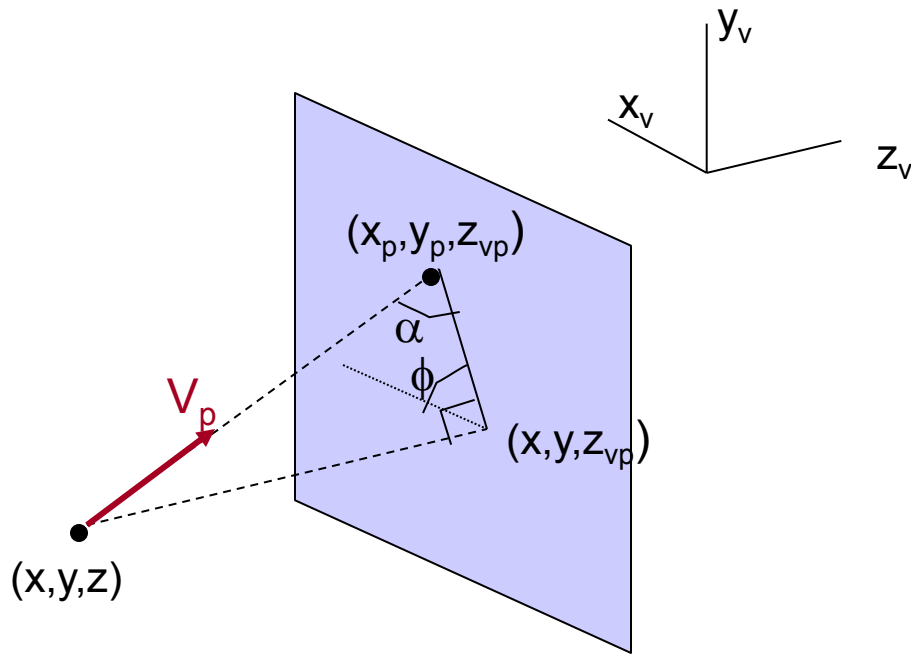
$\phi = 45^\circ$



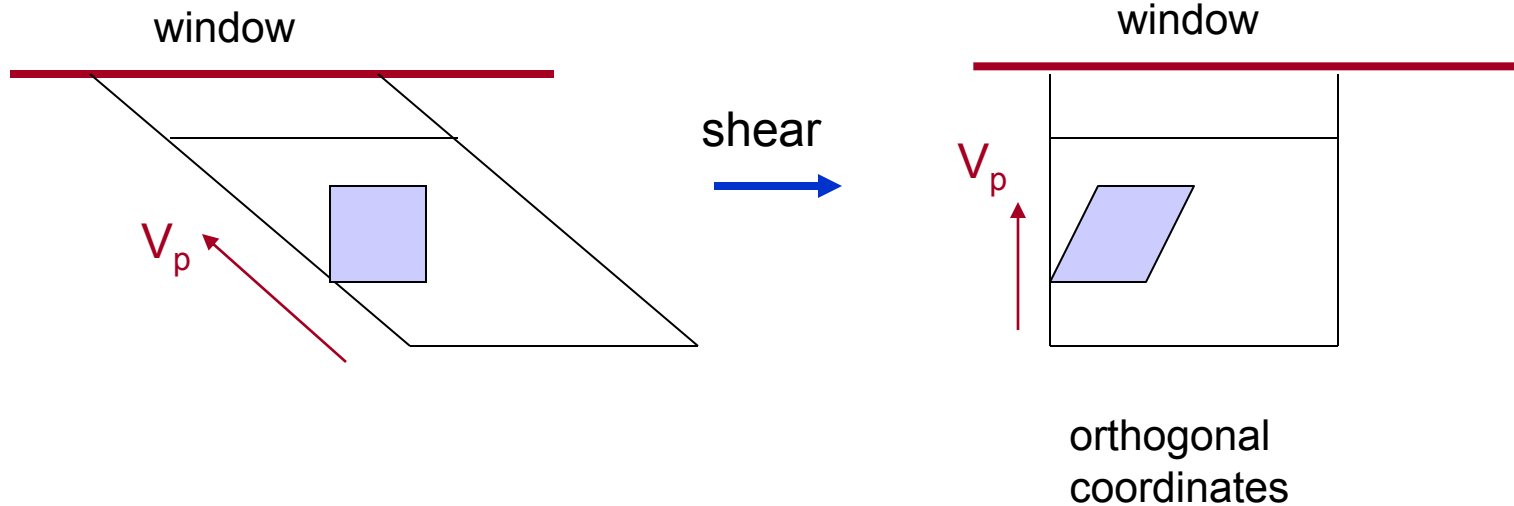
$\phi = 30^\circ$

***Cabinet Projection***

# Oblique Projection

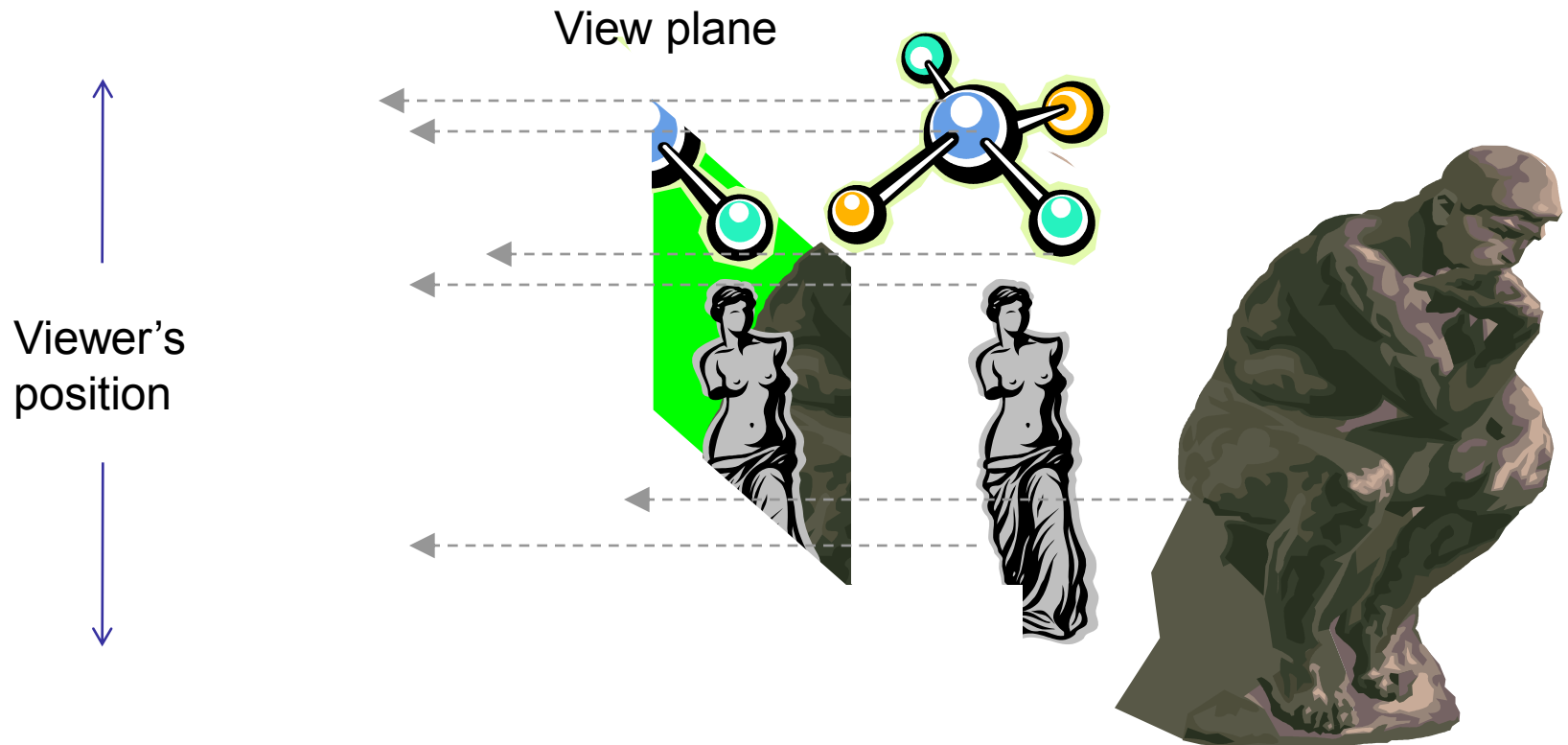


# Oblique Projection



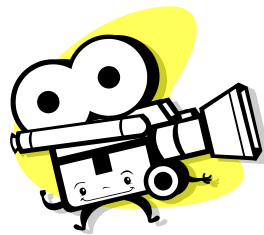
$$M_{WC,VC} \cdot \underbrace{M_{orth,norm} \cdot M_{obl}}_{M_{obl,norm}}$$

# Parallel Projection

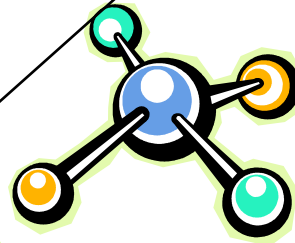
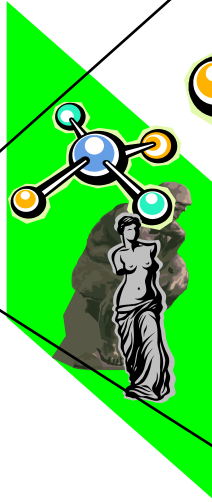


# Perspective Projection

Viewer's  
position

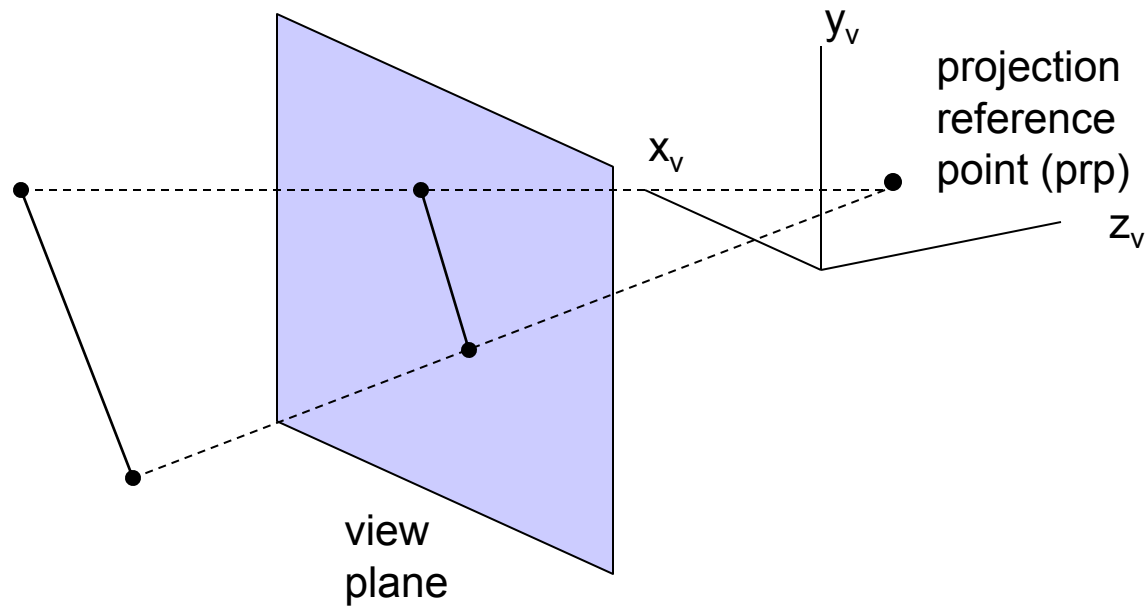


View plane



# Perspective Projection

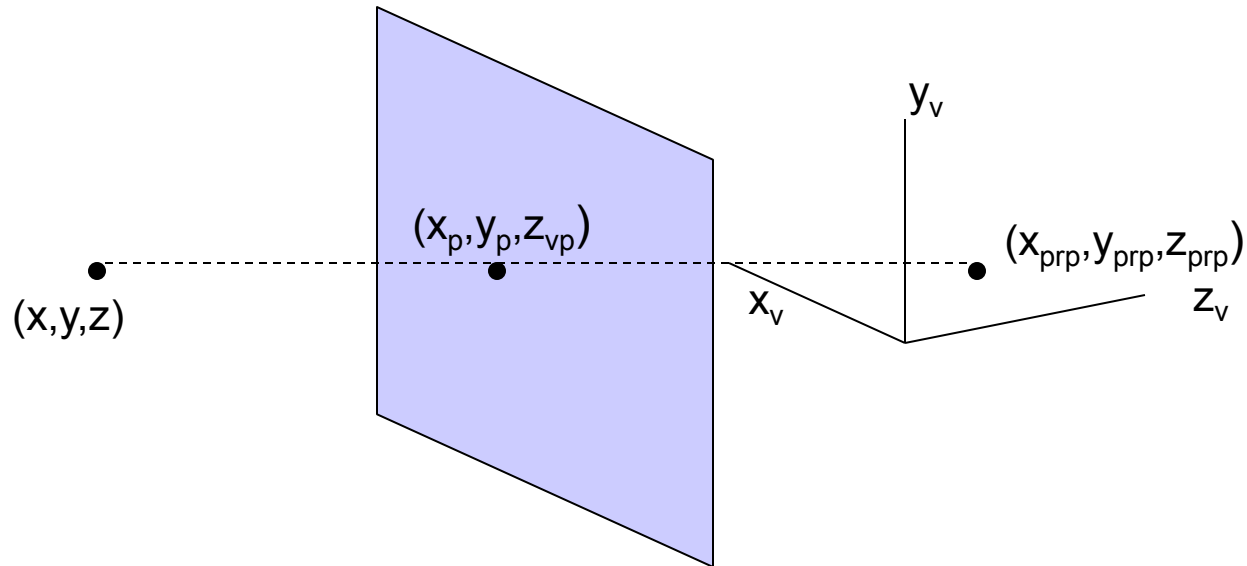
---





# Perspective Projection

---



# Perspective Projection

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At any point  $(x_p, y_p, z_p)$  along the projection line:

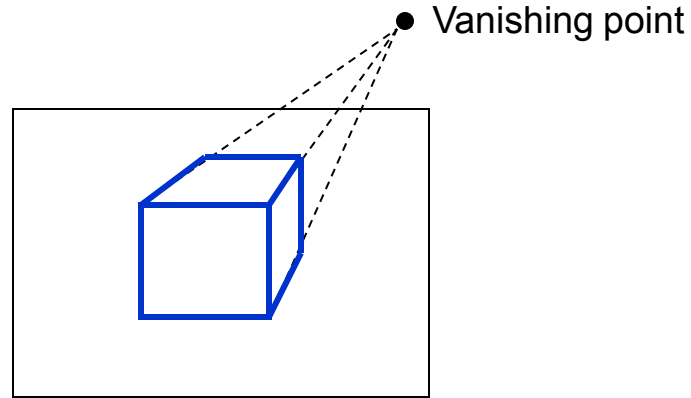
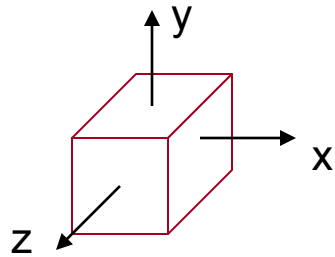
$$z_p = z_{vp}$$

$$x_p = x (z_{prp} - z_{vp}) / (z_{prp} - z) + x_{prp} (z_{vp} - z) / (z_{prp} - z)$$

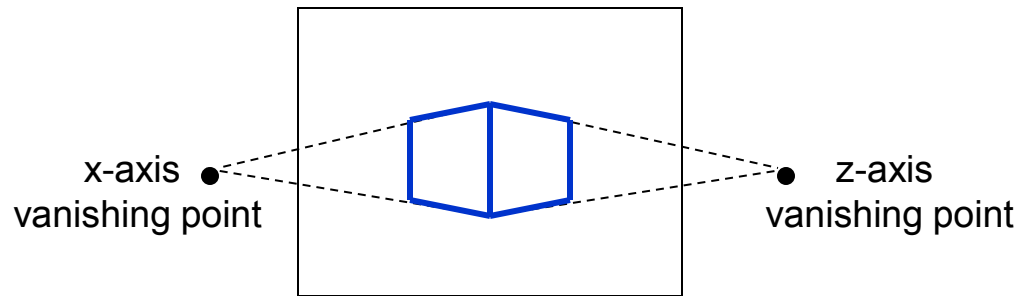
$$y_p = y (z_{prp} - z_{vp}) / (z_{prp} - z) + y_{prp} (z_{vp} - z) / (z_{prp} - z)$$

# Perspective Projection

---

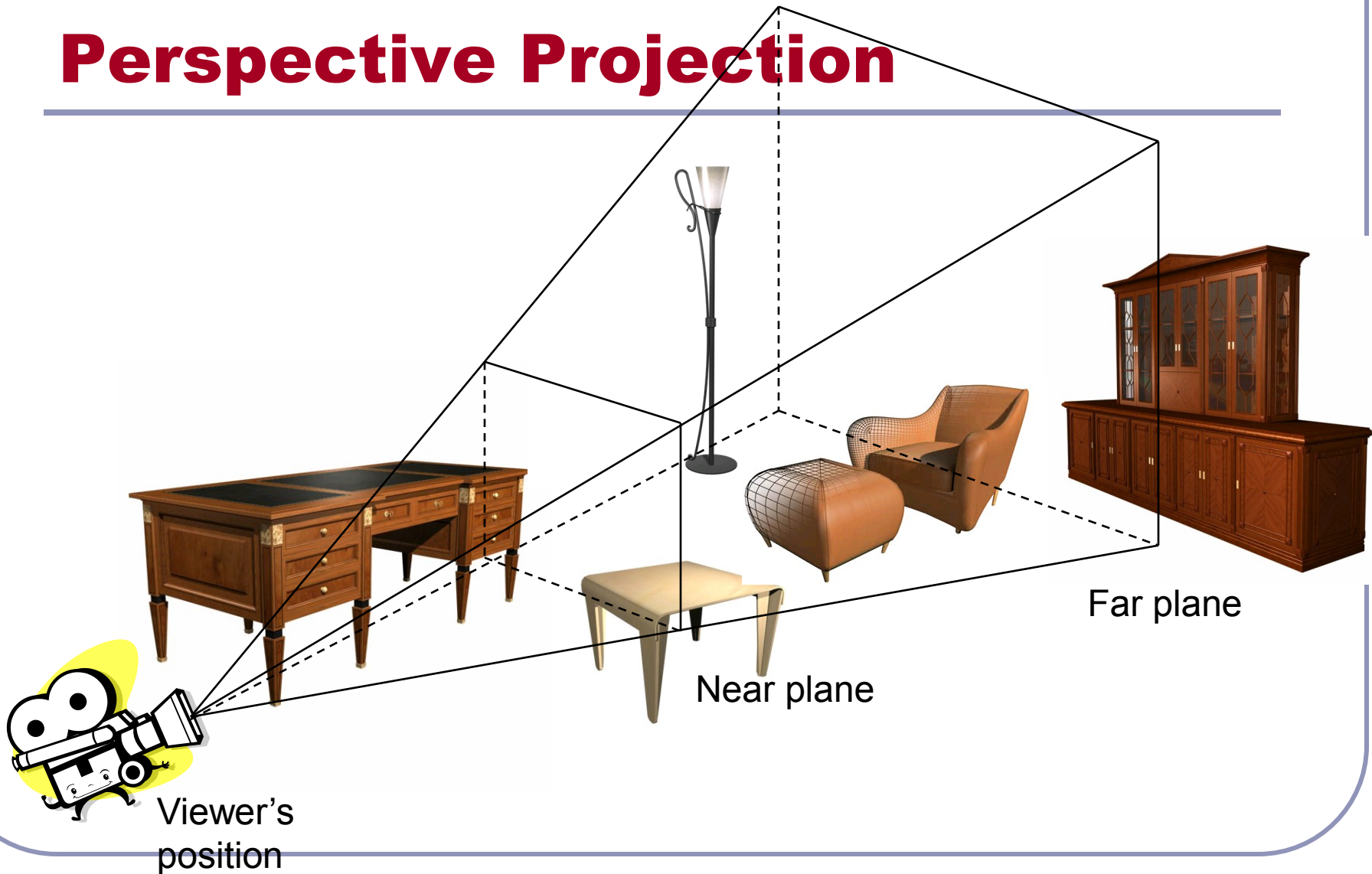


One-point perspective projection



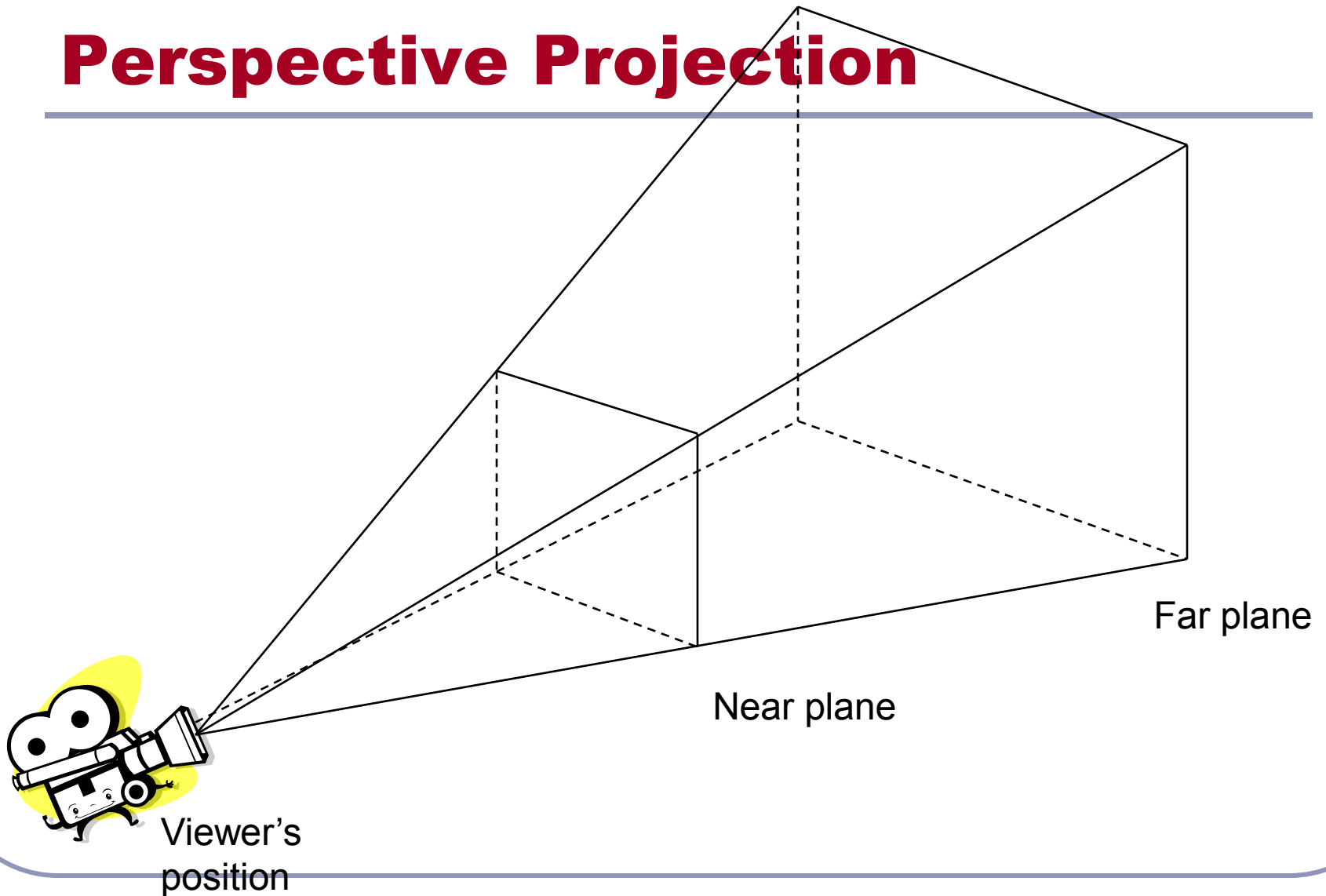
Two-point perspective projection

# Perspective Projection



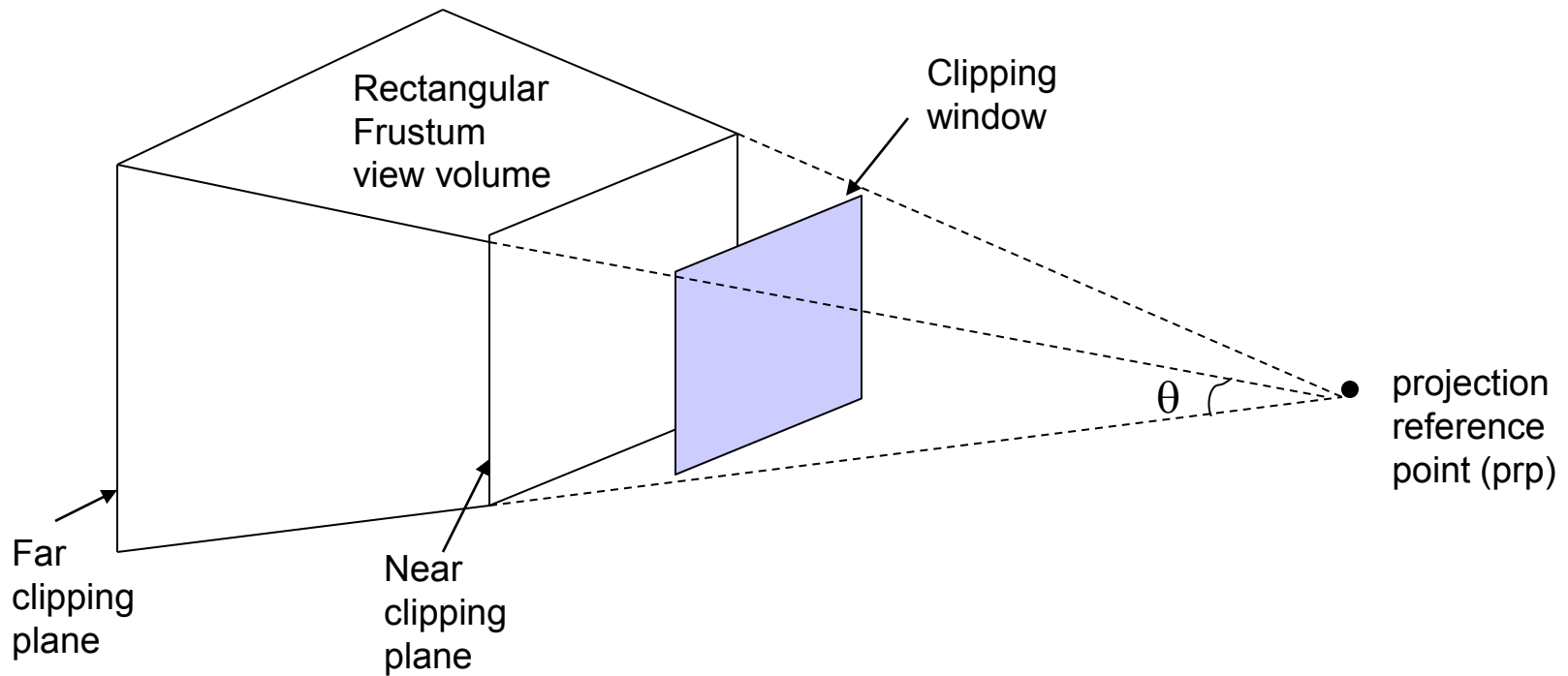
# Perspective Projection

---



# Perspective Projection

---



# Perspective Projection

---

$$P=(x, y, z, 1)$$

$$P_h=(x_h, y_h, z_h, h)$$

$$x_p = x (z_{prp}-z_{vp}) / (z_{prp}-z) + x_{prp} (z_{vp}-z) / (z_{prp}-z)$$

$$y_p = y (z_{prp}-z_{vp}) / (z_{prp}-z) + y_{prp} (z_{vp}-z) / (z_{prp}-z)$$

$$h = z_{prp}-z$$

$$x_h = x (z_{prp}-z_{vp}) + x_{prp} (z_{vp}-z)$$

$$y_p = y (z_{prp}-z_{vp}) + y_{prp} (z_{vp}-z)$$

$$x_p = x_h / h$$

$$y_p = y_h / h$$

# Perspective Projection

---

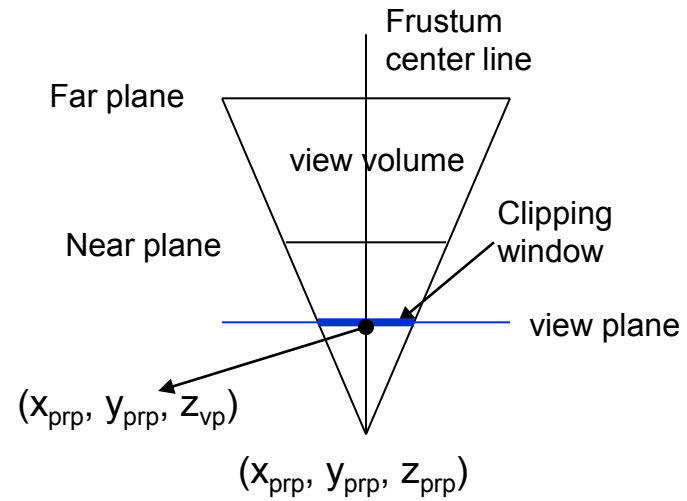
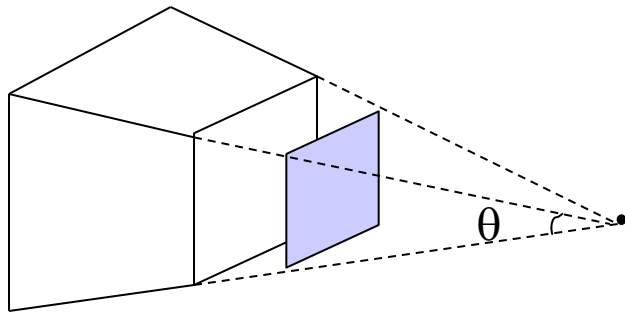
$$P_h = M_{\text{pers}} \cdot P$$

$$M_{\text{pers}} = \begin{pmatrix} z_{\text{prp}} - z_{\text{vp}} & 0 & -x_{\text{prp}} & x_{\text{prp}} z_{\text{prp}} \\ 0 & z_{\text{prp}} - z_{\text{vp}} & -y_{\text{prp}} & y_{\text{prp}} z_{\text{prp}} \\ 0 & 0 & s_z & t_z \\ 0 & 0 & -1 & z_{\text{prp}} \end{pmatrix}$$



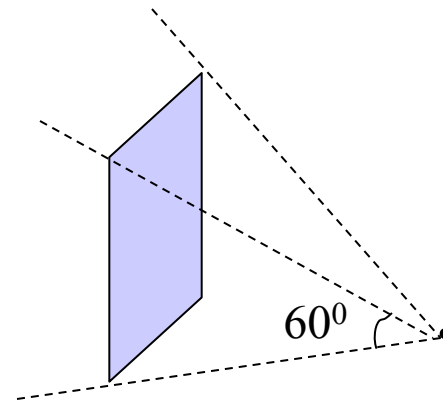
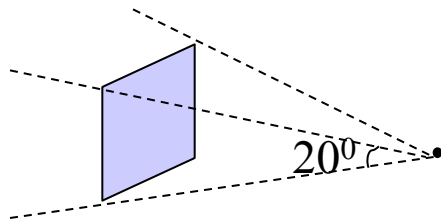
# Perspective Projection

## *Symmetric Frustum*



# Perspective Projection

---



# Perspective Projection

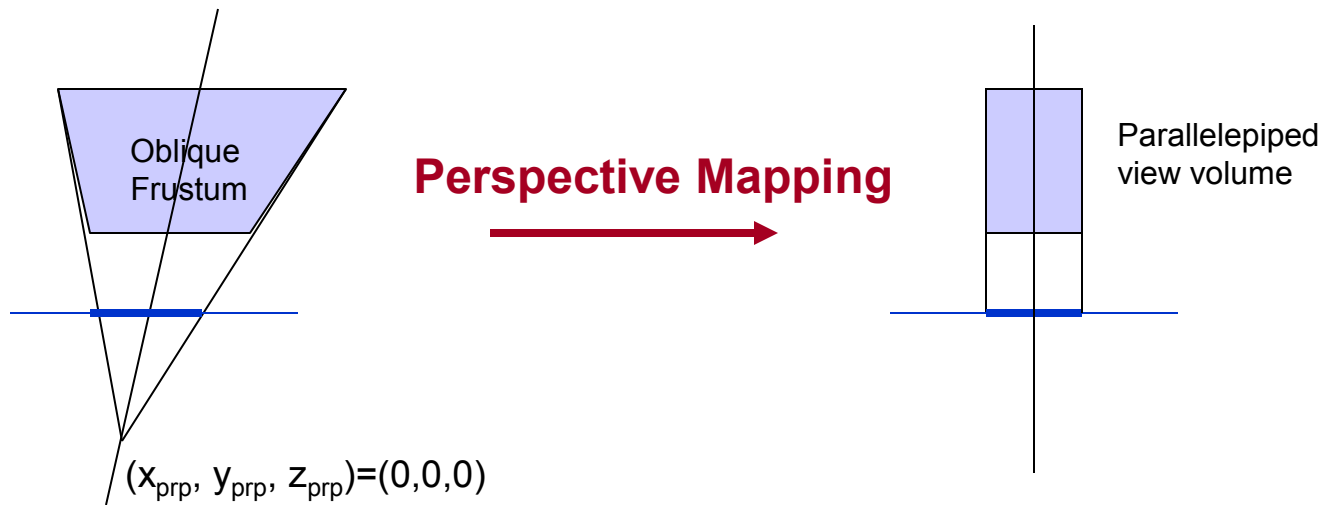
---



*Then apply normalization transformation*

# Perspective Projection

---



- 1. Transform to asymmetric frustum (z-axis shear)*
- 2. Normalize view volume*

# Perspective Projection

---

$$\mathbf{M}_{\text{shear}} = \begin{pmatrix} 1 & 0 & sh_{zx} & 0 \\ 0 & 1 & sh_{zy} & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$sh_{zx} = -(xw_{\min} + xw_{\max}) / 2 \cdot z_{\text{near}}$$

$$sh_{zy} = -(yw_{\min} + yw_{\max}) / 2 \cdot z_{\text{near}}$$

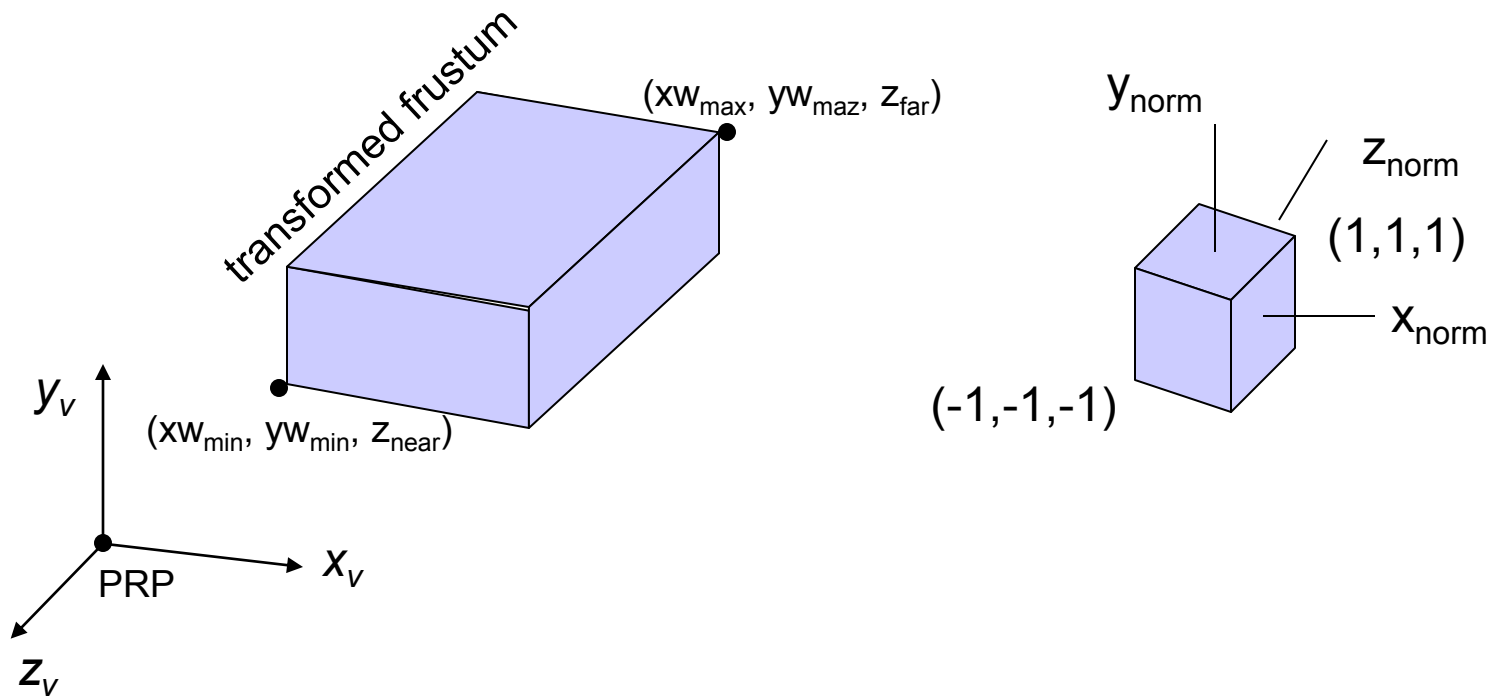
assuming that viewplane is at the position of the near plane

$$\mathbf{M}_{\text{pers}} = \begin{pmatrix} z_{\text{near}} & 0 & 0 & 0 \\ 0 & -z_{\text{near}} & 0 & 0 \\ 0 & 0 & s_z & t_z \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

$$\mathbf{M}_{\text{oblpers}} = \mathbf{M}_{\text{pers}} \cdot \mathbf{M}_{\text{shear}}$$

# Perspective Projection

## *Normalization*



# Perspective Projection

$$\mathbf{M}_{\text{normpers}} = \mathbf{M}_{\text{xyscale}} \cdot \mathbf{M}_{\text{oblpers}}$$

$$= \begin{pmatrix} -z_{\text{near}}s_x & 0 & s_x(xw_{\text{min}}+xw_{\text{max}})/2 & 0 \\ 0 & -z_{\text{near}}s_y & s_y(yw_{\text{min}}+yw_{\text{max}})/2 & 0 \\ 0 & 0 & s_z & t_z \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} -2z_{\text{near}}s_x/(xw_{\text{max}}-xw_{\text{min}}) & 0 & (xw_{\text{min}}+xw_{\text{max}})/(xw_{\text{max}}-xw_{\text{min}}) & 0 \\ 0 & -2z_{\text{near}}s_y/(yw_{\text{max}}-yw_{\text{min}}) & (yw_{\text{min}}+yw_{\text{max}})/(yw_{\text{max}}-yw_{\text{min}}) & 0 \\ 0 & 0 & (z_{\text{near}}+z_{\text{far}})/(z_{\text{near}}-z_{\text{far}}) & -2 \cdot z_{\text{near}} \cdot z_{\text{far}} / (z_{\text{near}} - z_{\text{far}}) \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

# Perspective Projection

---

For symmetric frustum with field-of-view angle  $\theta$ :

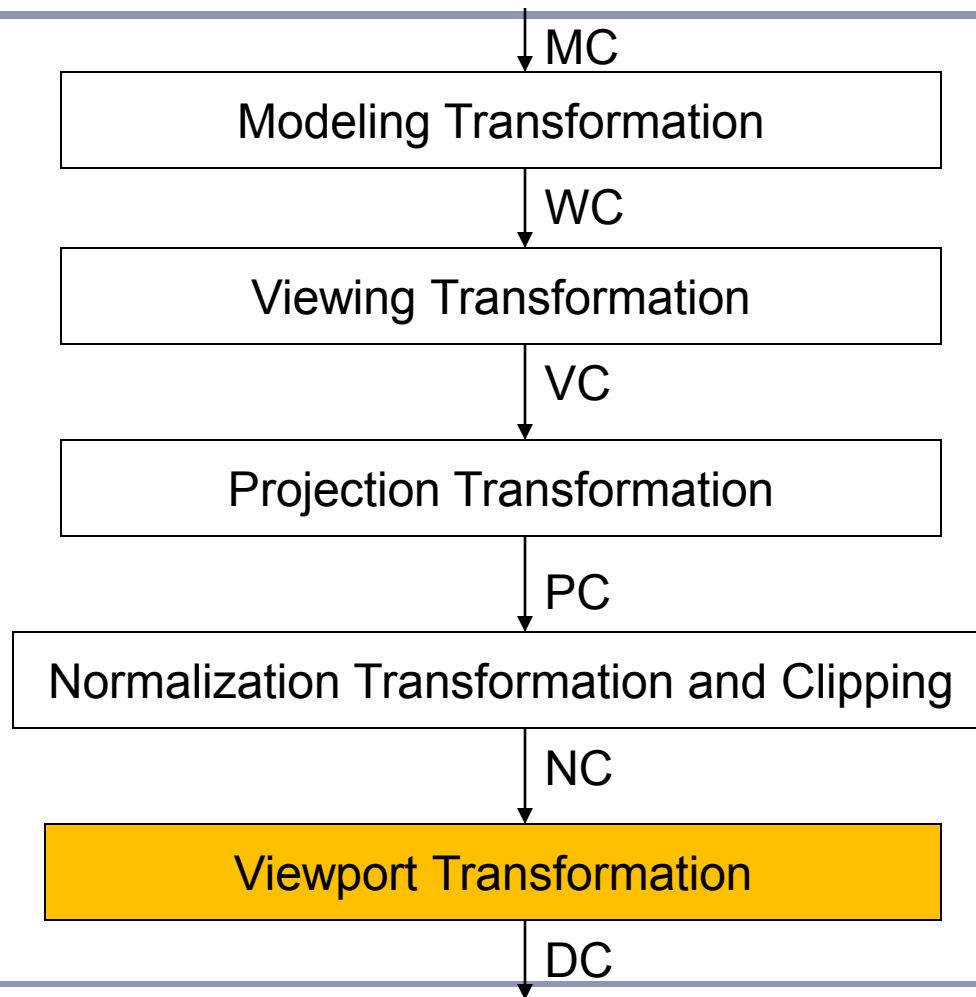
$M_{\text{normsymmpers}} =$

$$\begin{pmatrix} \cot(\theta/2)/\text{aspect} & 0 & 0 & 0 \\ 0 & \cot(\theta/2) & 0 & 0 \\ 0 & 0 & (z_{\text{near}}+z_{\text{far}})/(z_{\text{near}}-z_{\text{far}}) & -2 \cdot z_{\text{near}} \cdot z_{\text{far}} / (z_{\text{near}}-z_{\text{far}}) \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

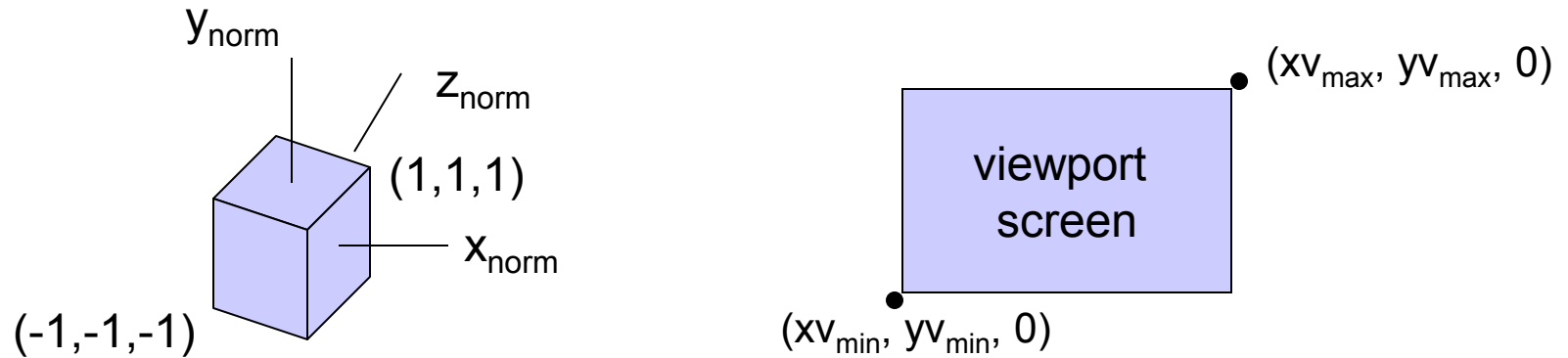
$$M_{\text{normsymmpers}} \cdot R \cdot T$$



# 3D Viewing Transformation Pipeline



# Viewport Transformation

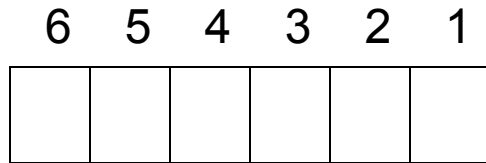


$$M_{\text{normviewvol,3Dscreen}} =$$

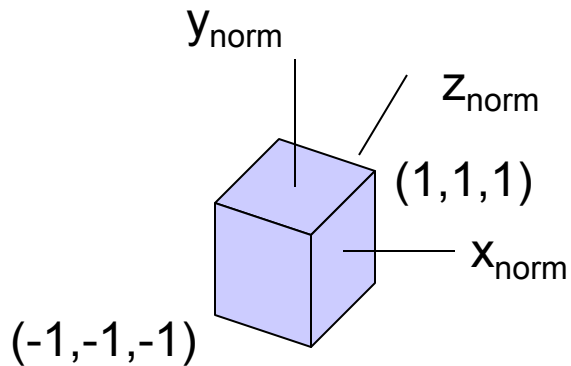
$$\begin{pmatrix} (xV_{\max} - xV_{\min})/2 & 0 & 0 & (xV_{\min} + xV_{\max})/2 \\ 0 & (yV_{\max} - yV_{\min})/2 & 0 & (yV_{\min} + yV_{\max})/2 \\ 0 & 0 & 1/2 & 1/2 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

# 3D Clipping

---



far near top bottom right left



Inside if:

$$-h \leq x_h \leq h, -h \leq y_h \leq h, -h \leq z_h \leq h$$

Use sign bits of  $h \pm x_h$ ,  $h \pm y_h$ ,  
 $h \pm z_h$  to set bit1-bit6

# Point Clipping

---

Test sign bits of  $h\pm x_h$ ,  $h\pm y_h$ ,  $h\pm z_h$

If region code is 000000 then inside  
otherwise eliminate

# Line Clipping

---

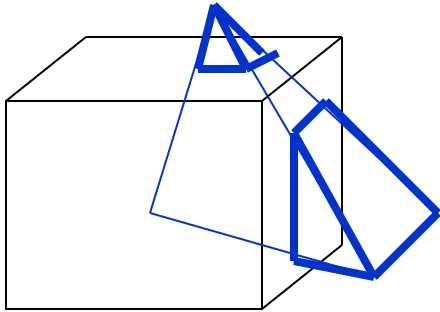
## 1. Test region codes

- if 000000 for both endpoints  $\Rightarrow$  inside
- if  $RC_1 \vee RC_2 = 000000$   $\Rightarrow$  trivially accept
- if  $RC_1 \wedge RC_2 \neq 000000$   $\Rightarrow$  trivially reject

2. If a line fails the above tests, use line equation to determine whether there is an intersection

# Polygon Clipping

---



1. Check coordinate limits of the object
    - if all limits are inside all boundaries => **save the entire object**
    - if all limits are outside any one of the boundaries => **eliminate the entire object**
  2. Otherwise process the vertices of the polygons
    - Apply 2D polygon clipping  
Clip edges to obtain new vertex list.
    - Update polygon tables to add new surfaces
- If the object consists of triangle polygons, use Sutherland-Hodgman algorithm.

# OpenGL

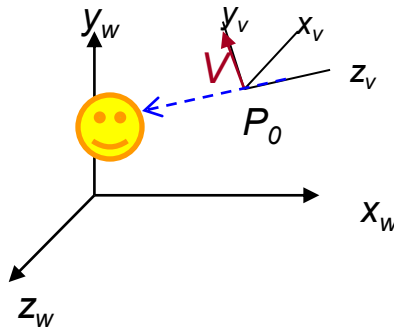
---

- **glMatrixMode (GL\_PROJECTION)**
- **gluOrtho (xwmin, xwmax, ywmin, ywmax, dnear, dfar)**  
Orthogonal projection
- **gluPerspective (theta, aspect, dnear, dfar)**
  - theta: field-of-view angle ( $0^{\circ} - 180^{\circ}$ )
  - aspect: *aspect ratio* of the clipping window (width/height)
  - dnear, dfar: positions of the near and far planes (must have positive values)
- **glFrustum (xwmin, xwmax, ywmin, ywmax, dnear, dfar)**
  - if  $xwmin = -xwmax$  and  $ywmin = -ywmax$  then symmetric view volume

# OpenGL

---

- **glMatrixMode (GL\_MODELVIEW)**
- **gluLookAt (x0, y0, z0, xref, yref, zref, Vx, Vy, Vz)**  
Designates the origin of the viewing reference frame as,
  - the world coordinate position  $P_0=(x_0, y_0, z_0)$
  - the reference position  $P_{ref}=(x_{ref}, y_{ref}, z_{ref})$  and
  - the viewup vector  $V=(V_x, V_y, V_z)$





# OpenGL

---

```
float eye_x, eye_y, eye_z;

void init (void) {
    glClearColor (1.0, 1.0, 1.0, 0.0); // Set display-window color to white.

    glMatrixMode (GL_PROJECTION);      // Set projection parameters.
    glLoadIdentity();
    gluPerspective(80.0, 1.0, 50.0, 500.0); // degree, aspect, near, far

    glMatrixMode (GL_MODELVIEW);
    eye_x = eye_y = eye_z = 60;
    gluLookAt(eye_x, eye_y, eye_z, 0,0,0, 0,1,0); // eye, look-at, view-up
}

void main (int argc, char** argv) {
    glutInit (&argc, argv); // Initialize GLUT.
    glutInitDisplayMode (GLUT_SINGLE | GLUT_RGB); // Set display mode.
    glutInitWindowPosition (50, 500); // Set top-left display-window position.
    glutInitWindowSize (400, 300); // Set display-window width and height.
    glutCreateWindow ("An Example OpenGL Program"); // Create display window.
    glViewport (0, 0, 400, 300);
    init ( ); // Execute initialization procedure.
    glutDisplayFunc (my_objects); // Send graphics to display window.
    glutReshapeFunc(reshape);
    glutKeyboardFunc(keybrd);
    glutMainLoop ( ); // Display everything and wait.
}
```