### PROGRAMMING WITH 8085 LECTURE 2

# INTRODUCTION TO 8085 INSTRUCTIONS

#### 1. Introduction

- A microprocessor executes instructions given by the user
- Instructions should be in a language known to the microprocessor
- Microprocessor understands the language of 0's and 1's only
- This language is called Machine Language

# A Machine language program to add two numbers

00111110

00000010

00000110

00000100

10000000

;Copy value 2H in register A

;Copy value 4H in register B

;A = A + B

### Assembly Language of 8085

- It uses English like words to convey the action/meaning called as MNEMONICS
- For e.g.
  - MOV to indicate data transfer
  - ADD to add two values
  - SUB to subtract two values

# Assembly language program to add two numbers

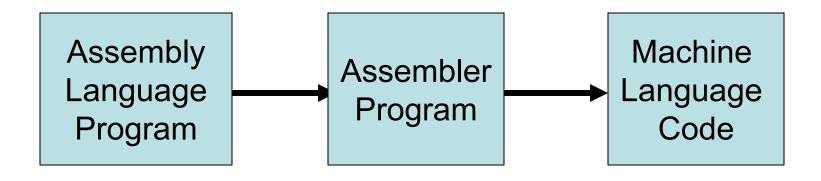
```
MVI A, 2H ;Copy value 2H in register A
MVI B, 4H ;Copy value 4H in register B
ADD B ;A = A + B
```

#### Note:

- Assembly language is specific to a given processor
- For e.g. assembly language of 8085 is different than that of Motorola 6800 microprocessor

#### Microprocessor understands Machine Language only!

- Microprocessor cannot understand a program written in Assembly language
- A program known as **Assembler** is used to convert a Assembly language program to machine language



### Low-level/High-level languages

- Machine language and Assembly language are both
  - Microprocessor specific (Machine dependent) so they are called
  - Low-level languages
- Machine independent languages are called
  - High-level languages
  - For e.g. BASIC, PASCAL,C++,C,JAVA, etc.
  - A software called **Compiler** is required to convert a high-level language program to machine code

### 2. Programming model of 8085

16-bit **Accumulator Address Bus Register Array ALU Memory Pointer** 8-bit Data **Flags** Registers Bus Instruction Decoder **Control Bus Timing and Control Unit** 

	(8-l	sit)	AC		P		CY
	(8-l	sit)					
	<b>C</b> (8-bit)						
E	E (8-bit)						
L	L (8-bit)						
Stack Pointer (SP) (16-bit)							
Program Counter (PC) (16-bit)							
							anal
	L er (S	L (8-ter (SP) (	L (8-bit) er (SP) (16-	L (8-bit) er (SP) (16-bit)	L (8-bit) er (SP) (16-bit) eter (PC) (16-bit)	L (8-bit) er (SP) (16-bit) eter (PC) (16-bit) 16-Lin	L (8-bit) er (SP) (16-bit)

#### Overview: 8085 Programming model

- 1. Six general-purpose Registers
- 2. Accumulator Register
- 3. Flag Register
- 4. Program Counter Register
- 5. Stack Pointer Register

#### 1. Six general-purpose registers

- B, C, D, E, H, L
- Can be combined as register pairs to perform 16-bit operations (BC, DE, HL)

#### 2. Accumulator – identified by name A

- This register is a part of ALU
- 8-bit data storage
- Performs arithmetic and logical operations
- Result of an operation is stored in accumulator

#### 3. Flag Register

- This is also a part of ALU
- 8085 has five flags named
  - Zero flag (Z)
  - Carry flag (CY)
  - Sign flag (S)
  - Parity flag (P)
  - Auxiliary Carry flag (AC)

- These flags are five flip-flops in flag register
- Execution of an arithmetic/logic operation can set or reset these flags
- Condition of flags (set or reset) can be tested through software instructions
- 8085 uses these flags in decision-making process

#### 4. Program Counter (PC)

- A 16-bit memory pointer register
- Used to sequence execution of program instructions
- Stores address of a memory location
  - where next instruction byte is to be fetched by the 8085
- when 8085 gets busy to fetch current instruction from memory
  - PC is incremented by one
  - PC is now pointing to the address of next instruction

#### 5. Stack Pointer Register

- a 16-bit memory pointer register
- Points to a location in Stack memory
- Beginning of the stack is defined by loading a 16-bit address in stack pointer register

#### 3.Instruction Set of 8085

- Consists of
  - 74 operation codes, e.g. MOV
  - 246 Instructions, e.g. MOV A,B
- 8085 instructions can be classified as
  - 1. Data Transfer (Copy)
  - 2. Arithmetic
  - 3. Logical and Bit manipulation
  - 4. Branch
  - 5. Machine Control

### 1. Data Transfer (Copy) Operations

## Copying data from a source to destination refers to data transfer function.

- 1. Load a 8-bit number in a Register
- 2. Copy from Register to Register
- 3. Copy between Register and Memory
- **4. Copy** between Input/Output Port and Accumulator
- 5. Load a 16-bit number in a Register pair
- Copy between Register pair and Stack memory

# Example Data Transfer (Copy) Operations / Instructions

- Load a 8-bit number 4F in register B
- 2. Copy from Register B to Register A
- Load a 16-bit number
   2050 in Register pair HL
- **4. Copy** from Register B to Memory Address 2050
- 5. Copy between Input/Output Port and Accumulator

MVI B, 4FH

**MOV A,B** 

**LXI H, 2050H** 

MOV M,B

OUT 01H IN 07H

# Data Transfer (Copy) Operations

- 6. 1 byte instruction.

  Processor stops executing and enters wait state.
- 7. 1 byte instruction. No operation. Generally used to increase processing time or substitute in place of instruction.

HLT

**NOP** 

### 2. Arithmetic Operations

- 1. Addition of two 8-bit numbers
- 2. Subtraction of two 8-bit numbers
- 3. Increment/ Decrement a 8-bit number

# Example Arithmetic Operations / Instructions

 Add a 8-bit number 32H to Accumulator

2. Add contents of Register B to Accumulator

3. Subtract a 8-bit number 32H from Accumulator

4. Subtract contents of RegisterC from Accumulator

5. Increment the contents of Register D by 1

**6. Decrement** the contents of Register E by 1

**ADI 32H** 

**ADD B** 

**SUI 32H** 

SUB C

**INR D** 

DCR E

# 3. Logical & Bit Manipulation Operations

- 1. AND two 8-bit numbers
- 2. OR two 8-bit numbers
- 3. Exclusive-OR two 8-bit numbers
- 4. Compare two 8-bit numbers
- 5. Complement
- 6. Rotate Left/Right Accumulator bits

# Example Logical & Bit Manipulation Operations / Instructions

 Logically AND Register H with Accumulator ANA H

2. Logically **OR** Register L with Accumulator

**ORAL** 

3. Logically **XOR** Register B with Accumulator

**XRA B** 

**4. Compare** contents of Register C with Accumulator

CMP C

5. Complement Accumulator

CMA

6. Rotate Accumulator Left

RAL

### 4. Branching Operations

These operations are used to control the flow of program execution

#### 1.Jumps

- Conditional jumps
- Unconditional jumps

#### 2.Call & Return

- Conditional Call & Return
- Unconditional Call & Return

# Example Branching Operations / Instructions

- **1. Jump** to a 16-bit Address 2080H if Carry flag is SET. This is conditional jump. **JNC**, **JZ**,**JNZ**,**JP**,**JM**,**JPE**,**JPO**
- 2. Unconditional Jump

  3 byte instruction. 2<sup>nd</sup> and 3<sup>rd</sup> byte specify 16 bit memory address.
- 3. Call a subroutine with its 16-bit Address
- 4.Return back from the Call
- **5. Call** a subroutine with its 16-bit Address if Carry flag is **RESET**
- 6. Return if Zero flag is SET

**JC 2080H** 

**JMP 2050H** 

CALL 3050H RET CNC 3050H RZ