## One sided and Bilateral Ztransforms, ZT of some common signals and ROC

### The z-Transform: Introduction

- Why z-Transform?
  - 1. Many of signals (such as x(n)=u(n),  $x(n)=(0.5)^nu(-n)$ ,  $x(n)=\sin(n\omega)$  etc. ) do not have a DTFT.
  - 2. Advantages like Fourier transform provided:
    - Solution process reduces to a simple algebraic procedures
    - The temporal domain sequence output y(n) = x(n)\*h(n) can be represent as Y(z) = X(z)H(z)
    - Properties of systems can easily be studied and characterized in z – domain (such as stability..)
- Topics:
  - Definition of z –Transform
  - Properties of z- Transform
  - Inverse z- Transform

## Definition of the z-Transform

1. Definition: The z-transform of a discrete-time signal x(n) is defined by

$$X(z) = \sum_{n = -\infty}^{\infty} x(n)z^{-n}$$

where  $z = re^{iw}$  is a complex variable. The values of z for which the sum converges define a region in the z-plane referred to as the *region of convergence* (ROC).

2. Notationally, if x(n) has a z-transform X(z), we write

$$x(n) \stackrel{Z}{\longleftrightarrow} X(z)$$

3. The z-transform may be viewed as the DTFT or an exponentially weighted sequence. Specifically, note that with  $z = re^{iw}$ , X(z) can be looked as the DTFT of the sequence  $r^{-n}x(n)$  and ROC is determined by the range of values of r of the following right inequation.

$$X(z) = \sum_{n = -\infty}^{\infty} x(n)z^{-n} = \sum_{n = -\infty}^{\infty} [r^{-n}x(n)]e^{-jn\omega} \qquad \sum_{n = -\infty}^{\infty} |x(n)r^{-n}| < \infty$$

## ROC & z-plane

Complex z-plane

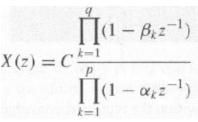
$$z = \Re(z) + jIm(z) = re^{jw}$$

Zeros and poles of X(z)

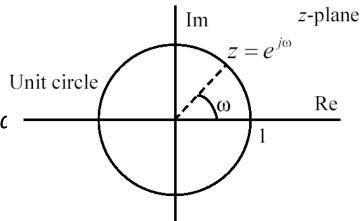
Many signals have z-transforms that are refunction of z:

$$X(z) = \frac{B(z)}{A(z)} = \frac{\sum_{k=0}^{q} b(k)z^{-k}}{\sum_{k=0}^{p} a(k)z^{-k}}$$

Factorizing it will give:



The roots of the numerator polynomial,  $\theta_{k,}$  are referred to as the zeros (o) and  $\alpha_{k}$  are referred to as poles (x). ROC of X(z) will not contain poles.



## **ROC** properties

- ROC is an annulus or disc in the z-plane centred at the origin. i.e.  $0 \le r_R < |z| < r_L \le \infty$ .
- A finite-length sequence has a z-transform with a region of convergence that includes the entire z-plane except, possibly, z = 0 and z = . The point  $\mathfrak{T} = 0$  will be included if  $\chi(n) = 0$  for n < 0, and the point z = 0 will be included if  $\chi(n) = 0$  for n > 0.
- A right-sided sequence has a z-transform with a region of convergence that is the exterior of a circle:

$$ROC: |z| > \alpha$$

 A left-sided sequence has a z-transform with a region of convergence that is the *interior* of a circle:

$$ROC: |z| < \beta$$

 The Fourier Transform of x(n) converges absolutely if and only if ROC of z-transform includes the unit circle

#### Example – Right-Sided Exponential Sequence (1)

■ Consider  $x[n]=a^nu[n]$ . Because it is nonzero only for  $n \ge 0$ , this is an example of a *right-sided* sequence.

$$X(z) = \sum_{n=-\infty}^{\infty} a^n u[n] z^{-n} = \sum_{n=0}^{\infty} (az^{-1})^n$$

For convergence of X(z), we require

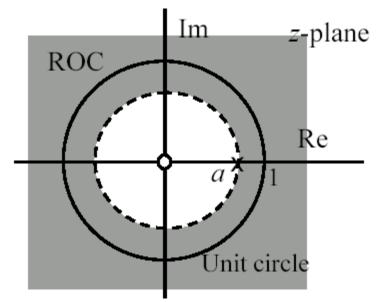
$$\sum_{n=-\infty}^{\infty} \left| az^{-1} \right|^n < \infty$$

Thus, the ROC is the range of values of z for which  $|az^{-1}| < 1$ , or equivalently, |z| > |a|. Inside the ROC, the infinite series converges to

$$X(z) = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$$
  $|z| > |a|$ 

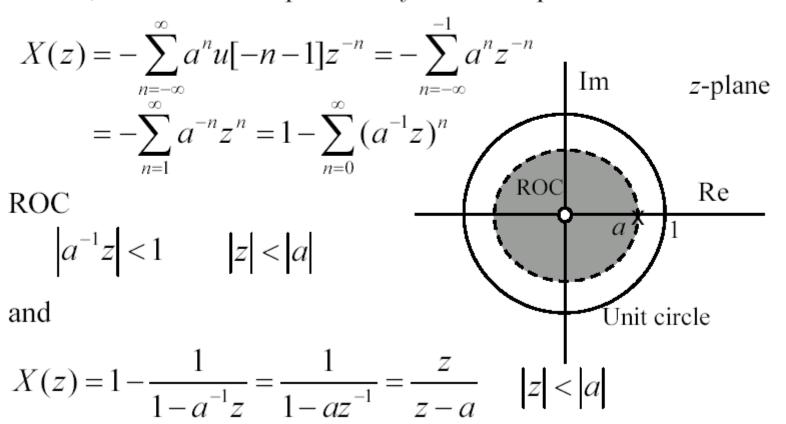
#### Example – Right-Sided Exponential Sequence (2)

- The infinite sum becomes a simple rational function of z inside the ROC.
- Such a z-transform is determined to within a constant multiplier by its zeros and its poles.
- For this example, one zero: z=0 (plotted as o); one pole: z=a (plotted as x).
- When |a|<1, the ROC includes the unit circle.



# Example – Left-Sided Exponential Sequence

■ Consider  $x[n] = -a^n u[-n-1]$ . Because it is nonzero only for  $n \le -1$ , this is an example of a *left-sided* sequence.



#### Notes on ROC

$$x[n] = a^n u[n] \iff X(z) = \frac{1}{1 - az^{-1}} = \frac{z}{z - a} \quad |z| > |a|$$

$$x[n] = -a^{-n}u[-n-1]$$

$$\longleftrightarrow X(z) = \frac{1}{1 - az^{-1}} = \frac{z}{z - a} \quad |z| < |a|$$

■ As can be seen from the two examples, the algebraic expression or pole-zero pattern does not completely specify the z-transform of a sequence; i.e., the ROC must also be specified.