

Step response of discrete time systems

Similar to the continuous time case, transient response of a digital control system can also be characterized by the following.

1. Rise time (t_r): Time required for the unit step response to rise from 0% to 100% of its final value in case of underdamped system or 10% to 90% of its final value in case of overdamped system.
2. Delay time (t_d): Time required for the the unit step response to reach 50% of its final value.

3. Peak time (t_p): Time at which maximum peak occurs.
4. Peak overshoot (M_p): The difference between the maximum peak and the steady state value of the unit step response.
5. Settling time (t_s): Time required for the unit step response to reach and stay within 2% or 5% of its steady state value.

However since the output response is discrete the calculated performance measures may be slightly different from the actual values. Figure 2 illustrates this. The output has a maximum value c_{\max} whereas the maximum value of the discrete output is $c \max$ which is always less than or equal to c_{\max} . If the sampling period is small enough compared to the oscillations of the response then this difference will be small otherwise $c \max$ may be completely erroneous.

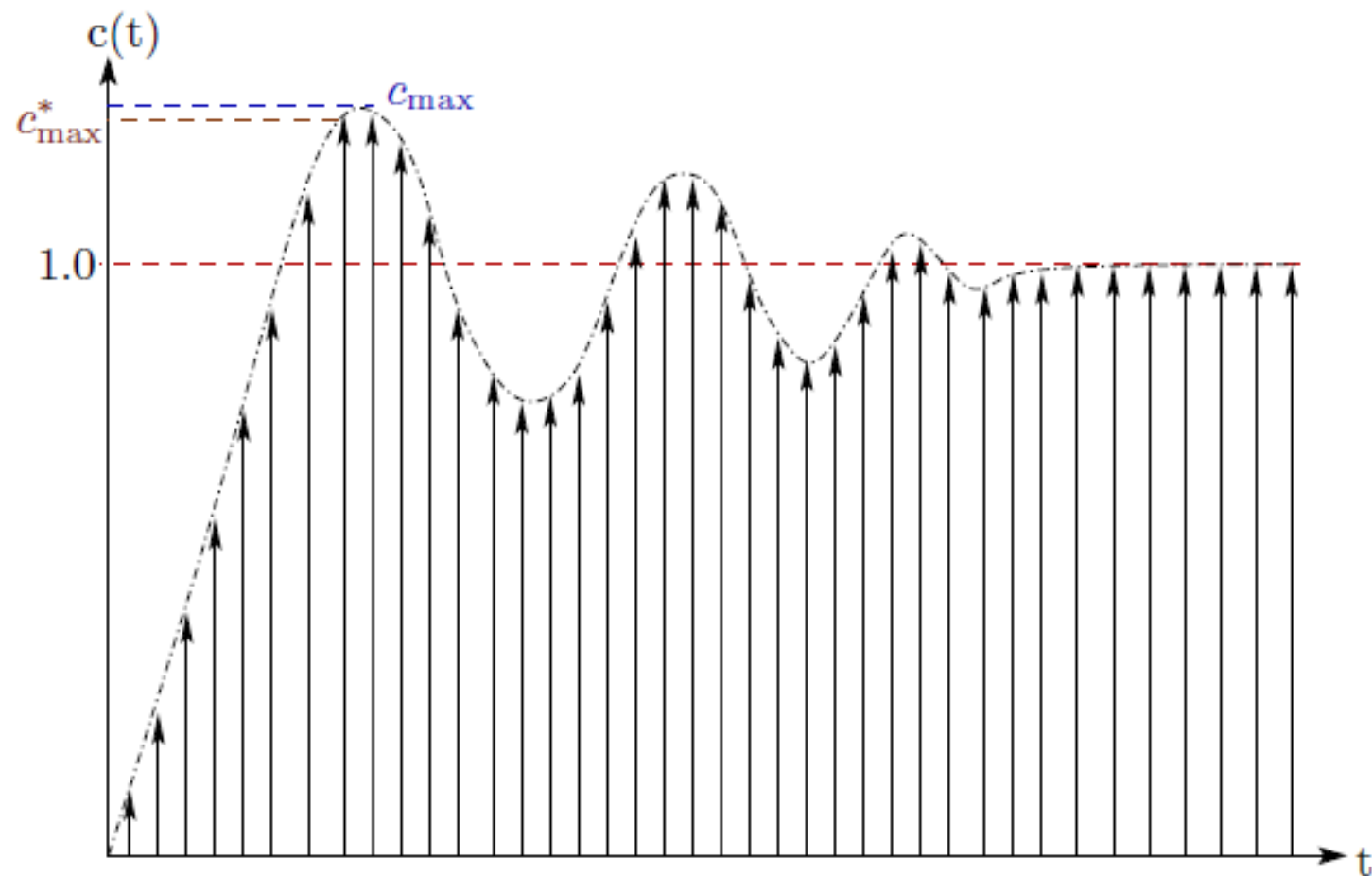


Figure : Unit step response of a discrete time system

signal energy and energy spectral
density

Let $f(t)$ be an electric potential in Volt applied across a resistance of $R = 1$ ohm. The total energy dissipated in such a resistance is given by

$$E = \int_{-\infty}^{\infty} \{f^2(t)/R\} dt.$$

Since the resistance value is unity the dissipated energy may be also be referred to as *normalized energy*. In what follows we shall refer to it simply as the dissipated energy, with the implicit assumption that it is the energy dissipated into a resistance of 1 ohm.

We recall Parseval's theorem which states that if a function $f(t)$ is generally complex and if $F(j\omega)$ is the Fourier transform of $f(t)$ then

$$\int_{-\infty}^{\infty} |f(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |F(j\omega)|^2 d\omega.$$

The energy in the resistance may therefore be written in the form

$$E = \int_{-\infty}^{\infty} f^2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |F(j\omega)|^2 d\omega.$$

The function $|F(j\omega)|^2$ is called the *energy spectral density*, or simply the energy density, of $f(t)$. It is attributed the special symbol $\varepsilon_{ff}(\omega)$, that is,

$$\varepsilon_{ff}(\omega) \triangleq |F(j\omega)|^2.$$

We note that its integral is equal to 2π times the signal energy

$$E = \frac{1}{2\pi} \int_{-\infty}^{\infty} \varepsilon_{ff}(\omega) d\omega$$

hence the name 'spectral density'.

Given two signals $f_1(t)$ and $f_2(t)$, where $f_1(t)$ represent a current source and $f_2(t)$ the voltage that the current source produces across a resistance R of 1 ohm, we have

$$E = \int_{-\infty}^{\infty} f_1(t) f_2(t) dt.$$

Parseval's or Rayleigh's theorem is written

$$\int_{-\infty}^{\infty} f_1(t) f_2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} F_1(-j\omega) F_2(j\omega) d\omega.$$

If $f_1(t)$ and $f_2(t)$ are real

$$F_1(-j\omega) = F_1^*(j\omega), \quad F_2(-j\omega) = F_2^*(j\omega).$$

The *normalized cross-energy* or simply *cross-energy* is therefore given by

$$E_{f_1 f_2} = \int_{-\infty}^{\infty} f_1(t) f_2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} F_1^*(j\omega) F_2(j\omega) d\omega.$$

The function

$$\varepsilon_{f_1 f_2}(\omega) \triangleq F_1^*(j\omega) F_2(j\omega)$$

is called the *cross-energy spectral density*. The cross energy of the two signals is then given by

$$E = \frac{1}{2\pi} \int_{-\infty}^{\infty} \varepsilon_{f_1 f_2}(\omega) d\omega.$$