

# **System Function (Transfer Function)**

A transfer function  $G(s)$  is defined as the following relation between the output of the system  $Y(s)$  and the input to the system  $U(s)$ .

$$G(s) = \frac{Y(s)}{U(s)}$$

If the transfer function of a system is known then the response of the system  $Y(s)$  can be found by taking the inverse Laplace transform of  $G(s) \cdot U(s)$ . It is also important to note that a transfer function is only defined for linear time invariant systems with all initial conditions set to zero.

If the input to the system is a unit impulse ( $U(s) = 1$ ), then

$$G(s) = Y(s)$$

Therefore, the inverse Laplace transform of the Transfer function of a system is the unit impulse response of the system. This can be thought of as the response to a brief external disturbance.

# Poles & Zeros

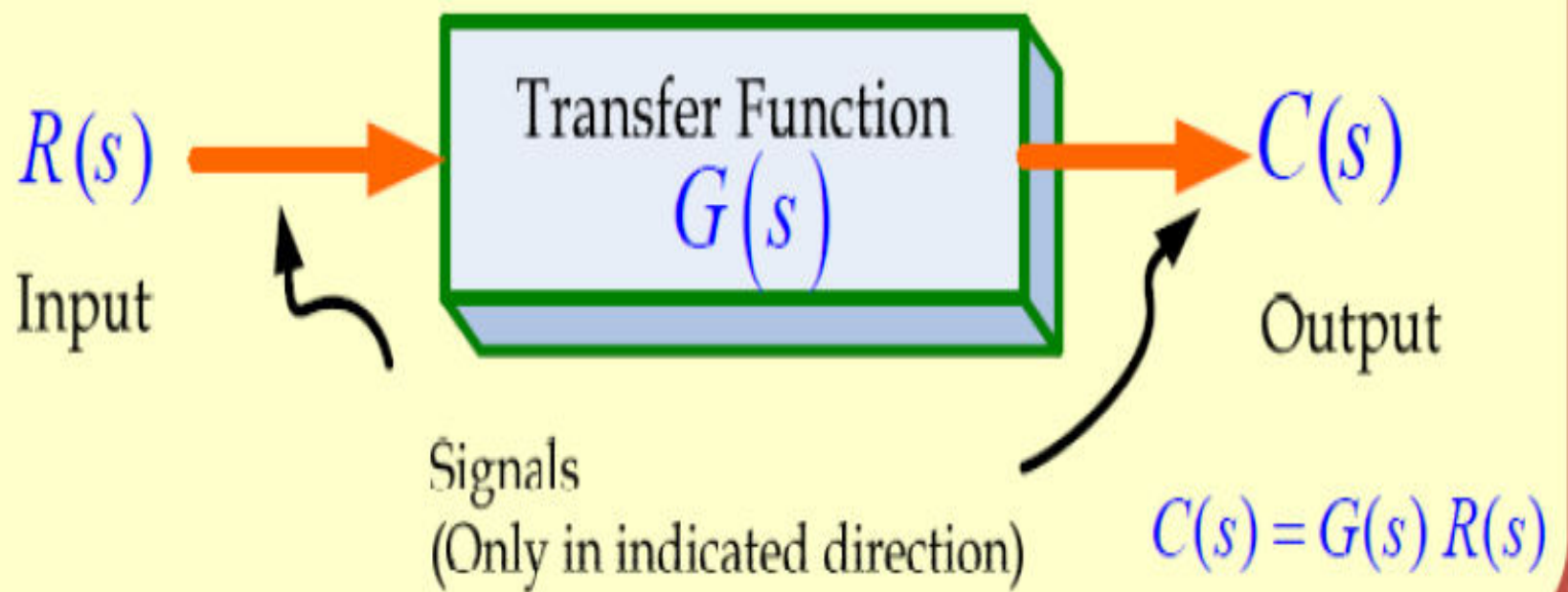
Zeros are defined as the roots of the polynomial of the numerator of a transfer function and poles are defined as the roots of the denominator of a transfer function. For the generalized transfer function

$$G(s) = \frac{(s - z_1) \cdot (s - z_2) \dots (s - z_n)}{(s - p_1) \cdot (s - p_2) \dots (s - p_n)}$$

The zeros are  $z_1, z_2, \dots, z_n$  and the poles are  $p_1, p_2, \dots, p_n$ .

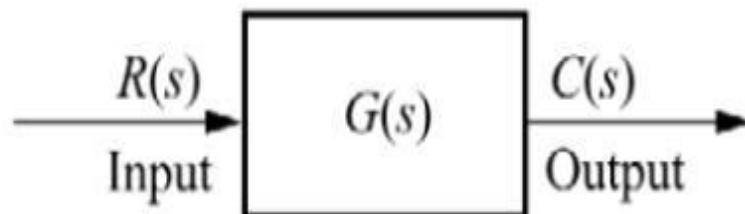
Identifying the poles and zeros of a transfer function aids in understanding the behavior of the system. For example, consider the transfer function  $F_1(s) = \frac{32}{s \cdot (s + 1) \cdot (s + 2)}$ . This function has three poles, two of which are negative integers and one of which is zero.

# Block diagram Representation

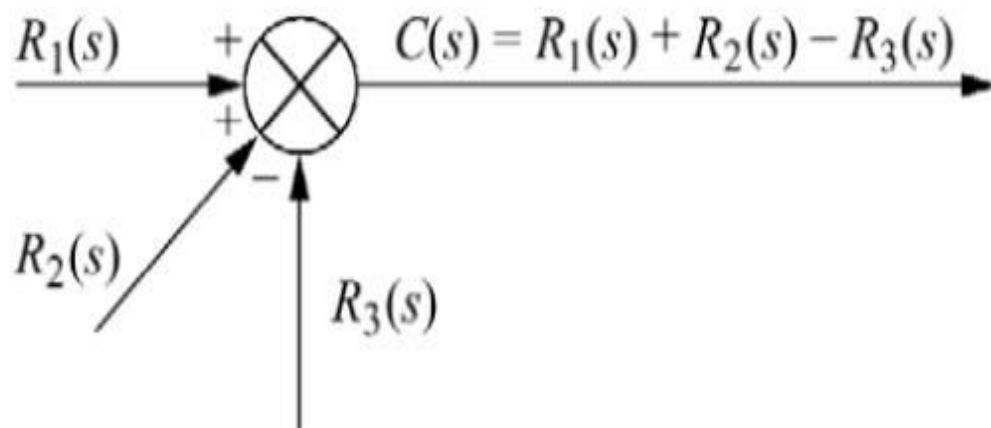




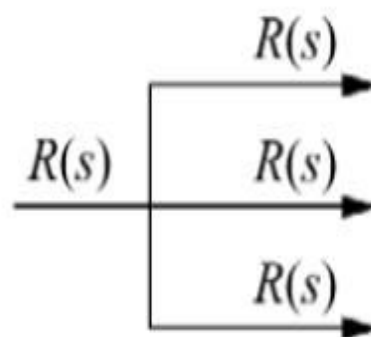
Signals  
(a)



System  
(b)



Summing junction  
(c)

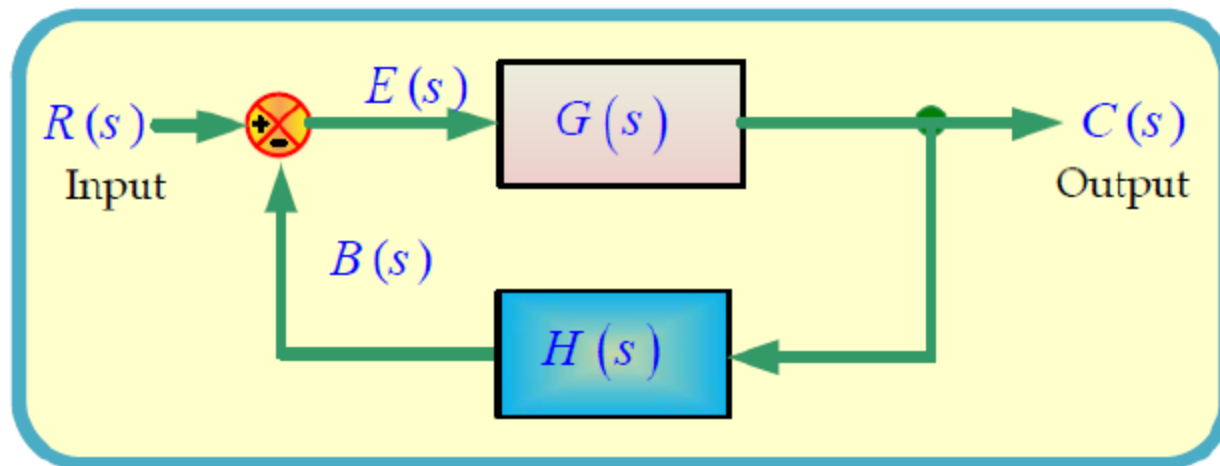


Pickoff point  
(d)



## Definitions

- $G(s)$   $\equiv$  Direct transfer function = Forward transfer function.
- $H(s)$   $\equiv$  Feedback transfer function.
- $G(s)H(s)$   $\equiv$  Open-loop transfer function.
- $C(s)/R(s)$   $\equiv$  Closed-loop transfer function = Control ratio
- $C(s)/E(s)$   $\equiv$  Feed-forward transfer function.



$$\frac{C(s)}{R(s)} = \frac{G(s)}{1 + G(s)H(s)}$$