UNIT-5 (Lecture-2)

Time-Domain Performance Criteria Specified In The Frequency Domain

Time-Domain Performance Criteria Specified In The Frequency Domain

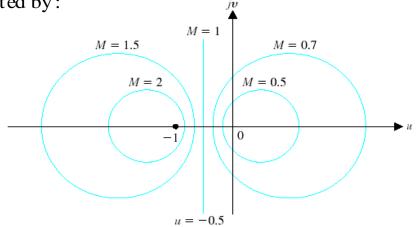
Constant M circles.

Open and closed-loop frequency responses are related by:

$$T(j\omega) = \frac{G(j\omega)}{1 + G(j\omega)}$$

$$M_{pw} = \frac{1}{2 \cdot \zeta \cdot \sqrt{1 - \zeta^2}} \qquad \zeta < 0.707$$

$$G(\omega) = u + j \cdot v$$
 $M = M(\omega)$



$$M(\omega) = \left| \frac{G(j\omega)}{1 + G(j\omega)} \right| = \left| \frac{u + jv}{1 + u + jv} \right| = \frac{\sqrt{u^2 + v^2}}{\sqrt{(1 + u)^2 + v^2}}$$

Squaring and rearrenging

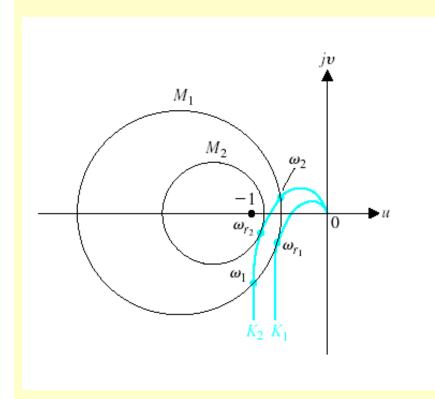
$$\left(u - \frac{M^2}{1 - M^2}\right)^2 + v^2 = \left(\frac{M}{1 - M^2}\right)^2$$
 which is the equation of a circle on u-v planwe with a center at
$$u = \frac{M^2}{1 - M^2}$$

$$v = 0$$

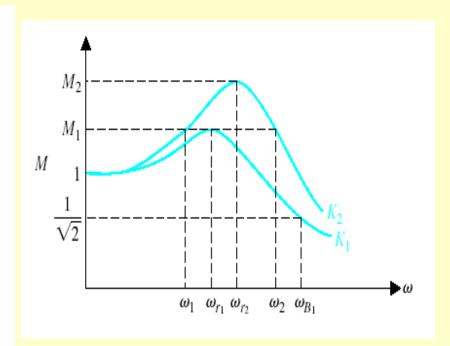
which is the equation of a

$$u = \frac{M^2}{1 - M^2} \qquad v = 0$$

Time-Domain Performance Criteria Specified In The Frequency Domain

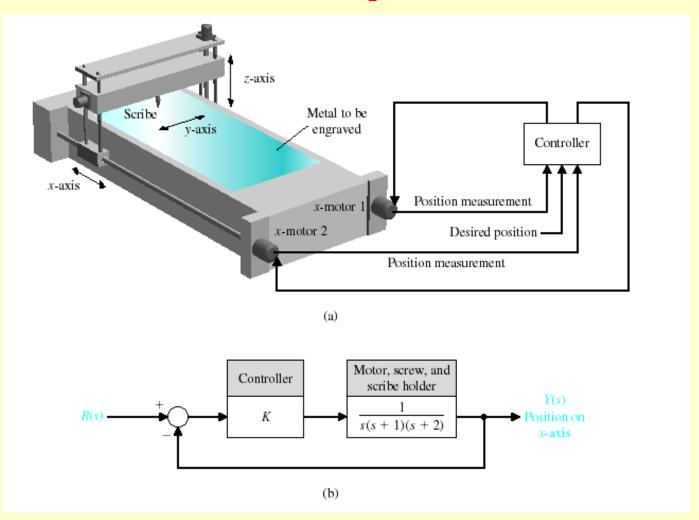


Polar plot of $G(j\omega)$ for two values of a gain $(K_2 > K_1)$.



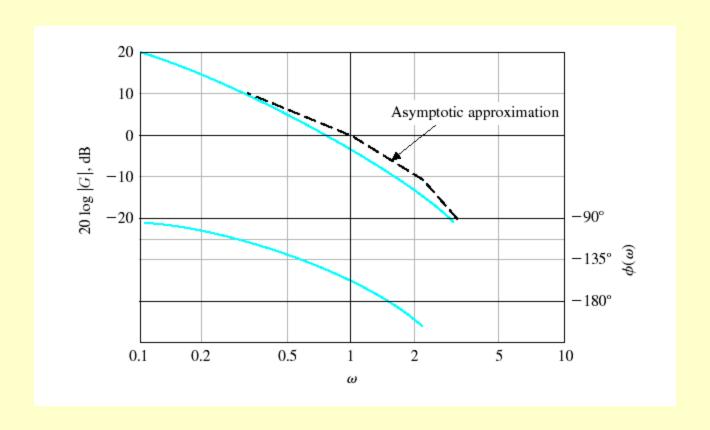
Closed-loop frequency response of $T(j\omega) = G(j\omega)/1 + G(j\omega)$. Note that $K_2 > K_1$.

Performance Specification In the Frequency Domain Example



CONTROL SYSTEM-I EIC-501

Performance Specification In the Frequency Domain Example



CONTROL SYSTEM-I EIC-501

Performance Specification In the Frequency Domain Example

