EIC-501

UNIT-5 (Lecture-7)

The Nichols Stability Method

The Nichols Stability Method

Polar Stability Plot - Nichol Mathcad Implementation

This example makes a polar plot of a transfer function and draws one contour of constant closed-loop magnitude. To draw the plot, enter a definition for the transfer fun**G(s)**.

 $G(s) := \frac{45000}{s \cdot (s+2) \cdot (s+30)}$

The frequency range defined by the next two equations provides a logarithmic frequency scale running from 1 to 100. You can change this range by editing the definition **snfand** ω_m :

$$\mathbf{m} \coloneqq \mathbf{0} \dots \mathbf{100} \qquad \boldsymbol{\omega}_{\mathbf{m}} \coloneqq \mathbf{10}^{\mathbf{.02 \cdot m}}$$

Now enter a value for **M** to define the closed-loop magnitude contour that will be plotted.

M := 1.1

Calculate the points on the M-circle:

$$MC_{m} := \left(\frac{-M^{2}}{M^{2} - 1} + \left|\frac{M}{M^{2} - 1}\right| \cdot \exp(2 \cdot \pi \cdot j \cdot .01 \cdot m)\right)$$

The first plot show, the contour of constant closed-loop magnitude

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The first plot show, the contour of constant closed-loop magnitude, and the Nyquist of the open loop system



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Nichols chart. The phase curves for the closed-loop system are shown in color.

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$$G(\omega) := \frac{1}{j \cdot \omega \cdot (j \cdot \omega + 1) \cdot (0.2 \cdot j \cdot \omega + 1)}$$

 $M_{pw} \coloneqq 2.5$ dB $\omega_r \coloneqq 0.8$

The closed-loop phase angle at ωr is equal to -72 degrees and $\omega b = 1.33$ The closed-loop phase angle at b is equal to





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$$G(\omega) := \frac{0.64}{j \cdot \omega \cdot \left[(j \cdot \omega)^2 + j \cdot \omega + 1 \right]}$$

Phase Margin = 30 degrees

On the basis of the phase we estimate := 0.30

 $M_{pw} := 9 \quad dB \qquad M_{pw} := 2.8 \qquad \omega_r := 0.88$

From equation

$$M_{pw} = \frac{1}{2 \cdot \zeta \cdot \sqrt{1 - \zeta^2}} \qquad \zeta := 0.18$$

We are confronted with comflectings

The app arent conflict is caused by the nature of $G(j_{\omega})$ which slopes rapidally toward 180 degrees line from the 0-dB axis. The designer must use the frequency-domain-time-domain correlation with caution

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D ara 3∙ď₿ 6 dB Loop gain G, in decibels 4 ₫₿(9 dB 0 12,ďB -5-AB GM 6 dB 22 -6S. ľ2ů 150° 210° 180° -12PM -18 dB $\frac{G}{1 + G}$ Magnitude of