

# PRINCIPLES OF COMMUNICATIONS

UNIT-2

LECTURE-1

## Properties of the Z-transform

1. RoC is generally a disk on the  $z$ -plane.

$$0 \leq r_R \leq |z| \leq r_L \leq \infty$$

2. Fourier Transform of  $x[n]$  converges when RoC includes the unit circle.
3. RoC does not contain any poles.
4. If  $x[n]$  is finite duration, RoC contains entire  $z$  - plane except for  $z = 0$  and  $z = \infty$ .
5. For a left handed sequence, RoC is bounded by  $|z| < \min(|a|, |b|)$ .
6. For a right handed sequence, RoC is bounded by  $|z| > \max(|a|, |b|)$ .

## Inverse Z-transform

To determine the inverse Z-transform, it is necessary to know the RoC.

- RoC decides whether a given signal is causal (exists for positive time), anticausal (exists for negative time) or both causal and anticausal (exists for both positive and negative time)

Different approaches to compute the inverse Z-transform

- **Long division method** When Z-Transform is rational, i.e. it can be expressed as the ratio of two polynomials  $P(z)$  and  $Q(z)$

$$X(z) = \frac{P(z)}{Q(z)}$$

Then, inverse Z-transform can be obtained using long division:

- Divide  $P(z)$  by  $Q(z)$ . Let this be:

$$X(z) = \sum_{i=-\infty}^{\infty} a_i z^{-i} \quad (1)$$

- The coefficients of the RHS of equation (1) correspond to the time sequence i.e. the coefficients of the quotient of the long division gives the sequence.

- **Partial Fraction method**

- the Z-Transform is decomposed into partial fractions
- the inverse Z-transform of each fraction is obtained independently
- the inverse sequences are then added

The method of adding inverse Z-transform is illustrated below.

Let,

$$\begin{aligned}
X(z) &= \frac{\sum_{k=0}^M b^k . z^{-k}}{\sum_{k=0}^N a^k . z^{-k}}, & M < N \\
&= \frac{\prod_{k=1}^M (1 - c_k . z^{-1})}{\prod_{k=1}^N (1 - d_k . z^{-1})} \\
&= \sum_{k=1}^N \frac{A_k}{(1 - d_k . z^{-1})}
\end{aligned}$$

where,

$$A_k = (1 - d_k.z^{-1})X(z)|_{z=d_k}$$

For  $s$  multiple poles at  $z = d_i$

$$X(z) = \sum_{k=0}^{M-N} B_r.z^{-1} + \sum_{k=1, k \neq i}^N \frac{A_k}{(1 - d_k.z^{-1})} + \sum_{m=1}^s \frac{C_m}{(1 - d_i.z^{-1})^m}$$