## PRINCIPLES OF COMMUNICATIONS

UNIT-2 LECTURE-5

## Random Process: Some Examples

• A sinusoid with random phase

Consider a sinusoidal signal with random phase, defined by

 $X(t) = a\sin(\omega_0 t + \Theta)$ 

where  $\omega_0$  and a are constants, and  $\Theta$  is a random variable that is uniformly distributed over a range of 0 to  $2\pi$  (see Figure 1)

$$egin{aligned} f_{\Theta}( heta) &= rac{1}{2\pi}, 0 \leq heta \leq 2\pi \ &= 0, elsewhere \end{aligned}$$



Figure 1: A sinusoid with random phase

This means that the random variable  $\Theta$  is equally likely to have any value in the range 0 to  $2\pi$ . The autocorrelation function of X(t) is

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$$\begin{aligned} \mathsf{Rx}(\mathsf{t}) &= \mathsf{E}[\mathsf{X}(\mathsf{t} + \mathsf{T})\mathsf{X}(\mathsf{t})] \\ &= \mathsf{E}[\sin(\omega \mathsf{o}\mathsf{t} + \omega \mathsf{o}\mathsf{T}) + \Theta) \sin(\omega \mathsf{o}\mathsf{t} + \Theta)] \\ &= \frac{1}{2} \mathsf{E}[\sin(2\omega \mathsf{o}\mathsf{t} + \omega \mathsf{o}\mathsf{T} + 2\Theta)] + 2\mathsf{E}[\sin(\overline{\omega} \mathsf{o}\mathsf{T})] \\ &= \frac{1}{2} \frac{1}{2} \frac{1}{2\pi} \frac{1}{2\pi} \cos(4\pi \mathsf{f}_{\mathsf{c}}\mathsf{t} + \omega \mathsf{o}\mathsf{T} + 2\Theta)] - \cos(\omega \mathsf{o}\mathsf{T}) \, \mathsf{d}\Theta \end{aligned}$$

The first term intergrates to zero, and so we get

$$Rx(\tau) = \frac{1}{2}\cos(\omega_0\tau)$$

The autocorrelation function is plotted in Figure 2.

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to lie anywhere between zero and T seconds

3.  $t_{delay}$  is the sample value of a uniformly distributed random variable  $T_{delay}$  with a probability density function

$$f_{T_{delay}}(t_{delay}) = \frac{1}{T}, 0 \le t_{delay} \le T$$
  
= 0, elsewhere

4. In any time interval  $(n-1)T < t - t_{delay} < nT$ , where n is an interger, a 1 or a 0 is determined randomly (for example by tossing a coin: heads  $\implies 1$ , tails  $\implies 0$ 

- E[X(t)] = 0, for all t since 1 and 0 are equally likely.

- Autocorrelation function  $R_X(t_k, t_l)$  is given by  $E[X(t_k)X(t_l)]$ , where  $X(t_k)$  and  $X(t_l)$  are random variables

Case 1: when  $|t_k - t_l| > T$ .  $X(t_k)$  and  $X(t_l)$  occur in different pulse intervals and are therefore independent:

$$E[X(t_k)X(t_l)] = E[X(t_k)]E[X(t_l)] = 0, for|t_k - t_l| > T$$

Case 2: when  $|t_k - t_l| < T$ , with  $t_k = 0$  and  $t_l < t_k$ .  $X(t_k)$  and  $X(t_l)$  occur in the same pulse interval provided  $t_{delay}$  satisfies the condition  $t_{delay} < T - |t_k - t_l|$ .

$$E[X(t_k)X(t_l)|t_{delay}] = 1, t_{delay} < T - |t_k - t_l|$$
$$= 0, elsewhere$$

Averaging this result over all possible values of  $t_{delay}$ , we get

$$\begin{split} E[X(t_k)X(t_l)] &= \int_0^{T-|t_k-t_l|} f_{T_{delay}}(t_{delay}) \, dt_{delay} \\ &= \int_0^{T-|t_k-t_l|} \frac{1}{T} \, dt_{delay} \\ &= (1 - \frac{|t_k - t_l|}{T}), |t_k - t_l| < T \end{split}$$

The autocorrelation function is given by

$$R_X(\tau) = (1 - \frac{|\tau|}{T}), |\tau| < T$$
  
= 0,  $|\tau| > T$ 

This result is shown in Figure 4

