

# Concept of Z-Transform

# The z-Transform: Introduction

- Why z-Transform?
  1. Many of signals (such as  $x(n)=u(n)$ ,  $x(n) = (0.5)^n u(-n)$ ,  $x(n) = \sin(n\omega)$  etc. ) do not have a DTFT.
  2. Advantages like Fourier transform provided:
    - Solution process reduces to a simple algebraic procedures
    - The temporal domain sequence output  $y(n) = x(n)*h(n)$  can be represent as  $Y(z)= X(z)H(z)$
    - Properties of systems can easily be studied and characterized in z – domain (such as stability..)
- Topics:
  - Definition of z –Transform
  - Properties of z- Transform
  - Inverse z- Transform

# Definition of the z-Transform

1. Definition: The z-transform of a discrete-time signal  $x(n)$  is defined by

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

where  $z = re^{j\omega}$  is a complex variable. The values of  $z$  for which the sum converges define a region in the  $z$ -plane referred to as the *region of convergence* (ROC).

2. Notationally, if  $x(n)$  has a z-transform  $X(z)$ , we write

$$x(n) \xleftrightarrow{Z} X(z)$$

3. The z-transform may be viewed as the DTFT or an exponentially weighted sequence. Specifically, note that with  $z = re^{j\omega}$ ,  $X(z)$  can be looked as the DTFT of the sequence  $r^{-n}x(n)$  and ROC is determined by the range of values of  $r$  of the following right inequation.

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n} = \sum_{n=-\infty}^{\infty} [r^{-n}x(n)]e^{-jn\omega}$$

$$\sum_{n=-\infty}^{\infty} |x(n)r^{-n}| < \infty$$

# ROC & z-plane

- Complex z-plane

$$z = \text{Re}(z) + j\text{Im}(z) = re^{j\omega}$$

- Zeros and poles of  $X(z)$

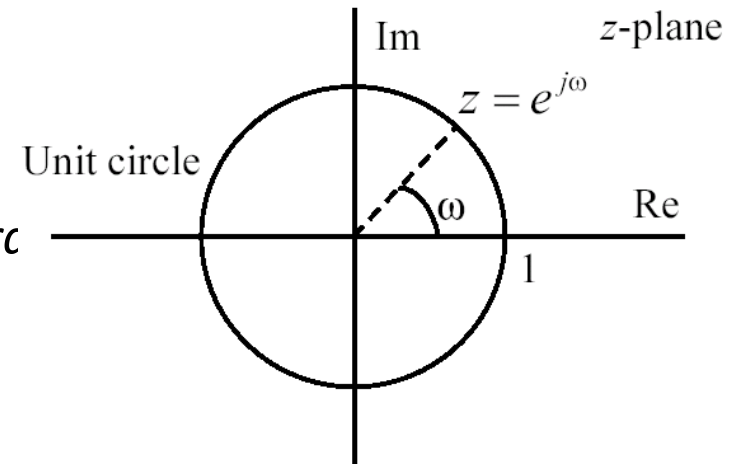
Many signals have z-transforms that are a function of  $z$ :

$$X(z) = \frac{B(z)}{A(z)} = \frac{\sum_{k=0}^q b(k)z^{-k}}{\sum_{k=0}^p a(k)z^{-k}}$$

Factorizing it will give:

$$X(z) = C \frac{\prod_{k=1}^q (1 - \beta_k z^{-1})}{\prod_{k=1}^p (1 - \alpha_k z^{-1})}$$

The roots of the numerator polynomial,  $\beta_k$ , are referred to as the zeros (o) and  $\alpha_k$  are referred to as poles (x). ROC of  $X(z)$  will not contain poles.



# ROC properties

- ROC is an annulus or disc in the z-plane centred at the origin.

i.e.

$$0 \leq r_R < |z| < r_L \leq \infty.$$

- A finite-length sequence has a z-transform with a region of convergence that includes the entire z-plane except, possibly,  $z = 0$  and  $z = \infty$ . The point  $z = \infty$  will be included if  $x(n) = 0$  for  $n < 0$ , and the point  $z = 0$  will be included if  $x(n) = 0$  for  $n > 0$ .

- A right-sided sequence has a z-transform with a region of convergence that is the *exterior* of a circle:

$$\text{ROC: } |z| > \alpha$$

- A left-sided sequence has a z-transform with a region of convergence that is the *interior* of a circle:

$$\text{ROC: } |z| < \beta$$

- The Fourier Transform of  $x(n)$  converges absolutely if and only if ROC of z-transform includes the unit circle