Expression for Output Current



During the interval diode 'D' conducts voltage equation is given by

$$V = \frac{Ldi_O}{dt} + Ri_O + E$$

For the initial condition i.e.,

$$i_O(t) = I_{\min}$$
 at $t = 0$

The solution of the above equation is obtained along similar lines as in step-down chopper with R-L load



$$\therefore \quad i_O(t) = \frac{V - E}{R} \left(1 - e^{-\frac{R}{L}t} \right) + I_{\min} e^{-\frac{R}{L}t} \quad 0 < t < t_{OFF}$$

At $t = t_{OFF}$ $i_{(O)}(t) = I_{\max}$
$$I_{\max} = \frac{V - E}{R} \left(1 - e^{-\frac{R}{L}t_{OFF}} \right) + I_{\min} e^{-\frac{R}{L}t_{OFF}}$$

During the interval chopper is ON voltage equation is given by

$$0 = \frac{Ldi_O}{dt} + Ri_O + E$$



Redefining the time origin, at t = 0 $i_O(t) = I_{max}$ The solution for the stated initial condition is $i_O(t) = I_{max} = \frac{R}{L}t = E\left(1 + e^{-\frac{R}{L}t}\right) = 0 < t < t$

$$i_{O}(t) = I_{\max}e^{-\frac{T}{L}t} - \frac{E}{R}\left(1 - e^{-\frac{T}{L}t}\right) \qquad 0 < t < t_{ON}$$

At $t = t_{ON} \qquad i_{O}(t) = I_{\min}$
$$\therefore \quad I_{\min} = I_{\max}e^{-\frac{R}{L}t_{ON}} - \frac{E}{R}\left(1 - e^{-\frac{R}{L}t_{ON}}\right)$$



Class C Chopper



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- Class C Chopper is a combination of Class A and Class B Choppers.
- For first quadrant operation, CH₁ is ON or D₂ conducts.
- For second quadrant operation, CH₂ is ON or D₁ conducts.
- When CH₁ is ON, the load current is positive.
- The output voltage is equal to 'V' & the load receives power from the source.
- When CH_1 is turned OFF, energy stored in inductance L forces current to flow through the diode D_2 and the output voltage is zero.



- Current continues to flow in positive direction.
- When *CH*₂ is triggered, the voltage *E* forces current to flow in opposite direction through L and *CH*₂.
- The output voltage is zero.
- On turning OFF CH₂, the energy stored in the inductance drives current through diode D₁ and the supply
- Output voltage is *V*, the input current becomes negative and power flows from load to source.



- Average output voltage is positive
- Average output current can take both positive and negative values.
- Choppers CH₁ & CH₂ should not be turned ON simultaneously as it would result in short circuiting the supply.
- *Class C Chopper* can be used both for dc motor control and regenerative braking of dc motor.
- Class C Chopper can be used as a step-up or step-down chopper.





Class D Chopper





- Class D is a two quadrant chopper.
- When both CH₁ and CH₂ are triggered simultaneously, the output voltage v₀ = V and output current flows through the load.
- When CH₁ and CH₂ are turned OFF, the load current continues to flow in the same direction through load, D₁ and D₂, due to the energy stored in the inductor L.
- Output voltage $v_0 = -V$.



- Average load voltage is positive if chopper ON time is more than the OFF time
- Average output voltage becomes negative if $t_{ON} < t_{OFF}$.
- Hence the direction of load current is always positive but load voltage can be positive or negative.









Class E Chopper









- Class E is a four quadrant chopper
- When CH₁ and CH₄ are triggered, output current i₀ flows in positive direction through CH₁ and CH₄, and with output voltage v₀ = V.
- This gives the first quadrant operation.
- When both CH_1 and CH_4 are OFF, the energy stored in the inductor L drives i_0 through D_2 and D_3 in the same direction, but output voltage $v_0 = -V$.



- Therefore the chopper operates in the fourth quadrant.
- When CH₂ and CH₃ are triggered, the load current i₀ flows in opposite direction & output voltage v₀ = -V.
- Since both i_o and v_o are negative, the chopper operates in third quadrant.



- When both CH₂ and CH₃ are OFF, the load current i₀ continues to flow in the same direction D₁ and D₄ and the output voltage v₀ = V.
- Therefore the chopper operates in second quadrant as v_o is positive but i_o is negative.



Effect Of Source & Load Inductance

- The source inductance should be as small as possible to limit the transient voltage.
- Also source inductance may cause commutation problem for the chopper.
- Usually an input filter is used to overcome the problem of source inductance.



- The load ripple current is inversely proportional to load inductance and chopping frequency.
- Peak load current depends on load inductance.
- To limit the load ripple current, a smoothing inductor is connected in series with the load.

