

# Lecture-1

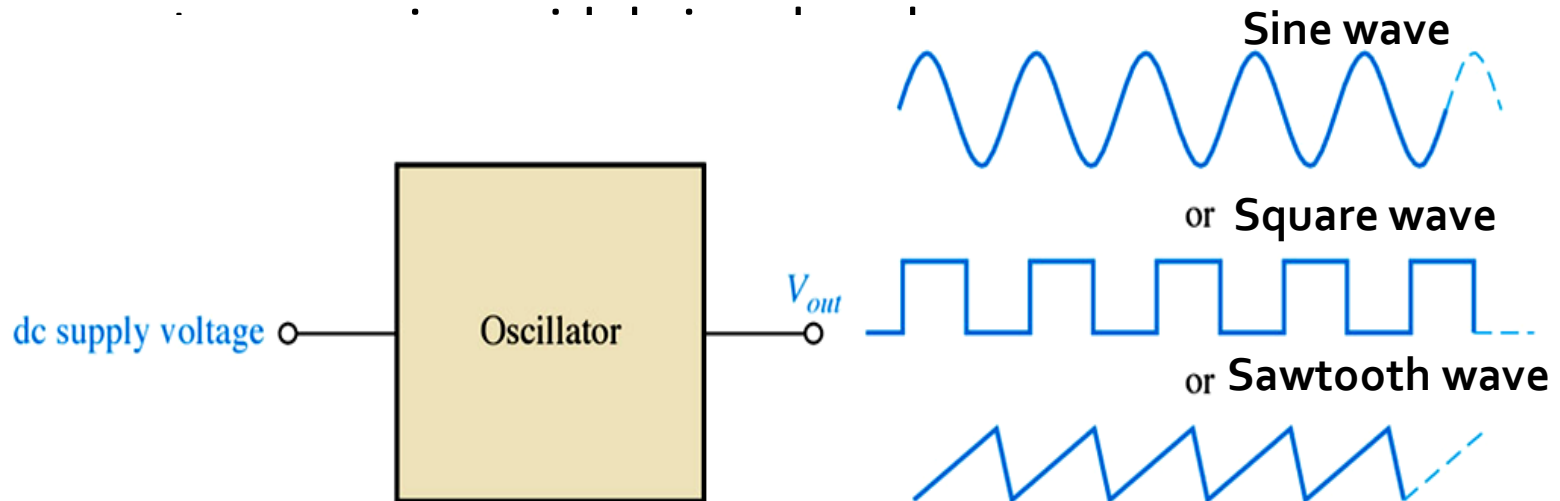
Oscillator Principal, Wein Bridge  
Oscillator

# Introduction

- Oscillator is an electronic circuit that generates a periodic waveform on its output without an external signal source. It is used to convert dc to ac.
- Oscillators are circuits that produce a continuous signal of some type without the need of an input.
- These signals serve a variety of purposes.
- Communications systems, digital systems (including computers), and test equipment make use of oscillators

# Introduction

- An oscillator is a circuit that produces a repetitive signal from a dc voltage.
- The feedback oscillator **relies on a positive feedback** of the output to **maintain the oscillations**.
- The relaxation oscillator makes use of an RC timing circuit to



# Types of oscillators

## 1. RC oscillators

- Wien Bridge
- Phase-Shift

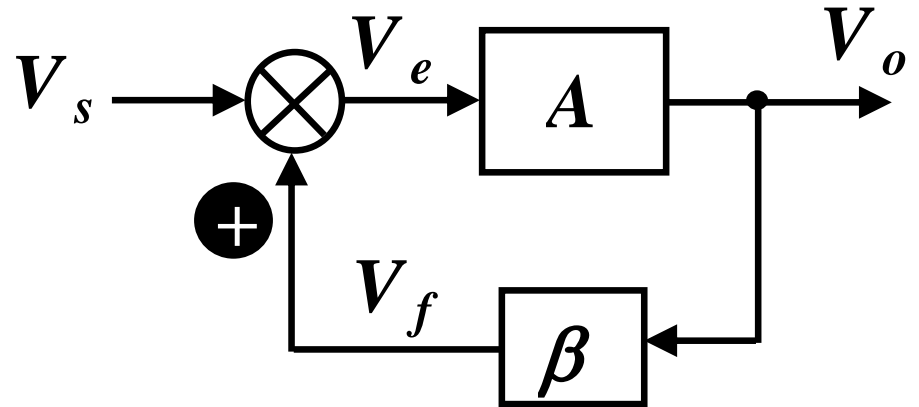
## 2. LC oscillators

- Hartley
- Colpitts
- Crystal

## 3. Unijunction / relaxation oscillators

# Basic principles for oscillation

- An oscillator is an amplifier with positive feedback.



$$V_e = V_s + V_f \quad (1)$$

$$V_f = \beta V_o \quad (2)$$

$$V_o = A V_e = A(V_s + V_f) = A(V_s + \beta V_o) \quad (3)$$

# Basic principles for oscillation

$$\begin{aligned}V_o &= AV_e \\ &= A(V_s + V_f) = A(V_s + \beta V_o)\end{aligned}$$

$$\begin{aligned}V_o &= AV_s + A\beta V_o \\ (1 - A\beta)V_o &= AV_s\end{aligned}$$

- The closed loop gain is:  $A_f \equiv \frac{V_o}{V_s} = \frac{A}{(1 - A\beta)}$

# Basic principles for oscillation

- In general  $A$  and  $\beta$  are functions of frequency and thus may be written as;

$$A_f(s) = \frac{V_o}{V_s}(s) = \frac{A(s)}{1 - A(s)\beta(s)}$$

$A(s)\beta(s)$  is known as **loop gain**

# Basic principles for oscillation

$$T(s) = A(s)\beta(s)$$

- Writing  $A_f(s)$  becomes: 
$$A_f(s) = \frac{A(s)}{1 - T(s)}$$
 the loop gain

- Replacing  $s$  with  $j\omega$ 
$$A_f(j\omega) = \frac{A(j\omega)}{1 - T(j\omega)}$$

- and 
$$T(j\omega) = A(j\omega)\beta(j\omega)$$



# Basic principles for oscillation

- At a specific frequency  $f_0$

$$T(j\omega_0) = A(j\omega_0)\beta(j\omega_0) = \mathbf{1}$$

- At this frequency, the closed loop gain;

$$A_f(j\omega_0) = \frac{A(j\omega_0)}{1 - A(j\omega_0)\beta(j\omega_0)}$$

will be infinite, i.e. the circuit will have finite output for zero input signal - oscillation

# Basic principles for oscillation

- Thus, the condition for sinusoidal oscillation of frequency  $f_0$  is;

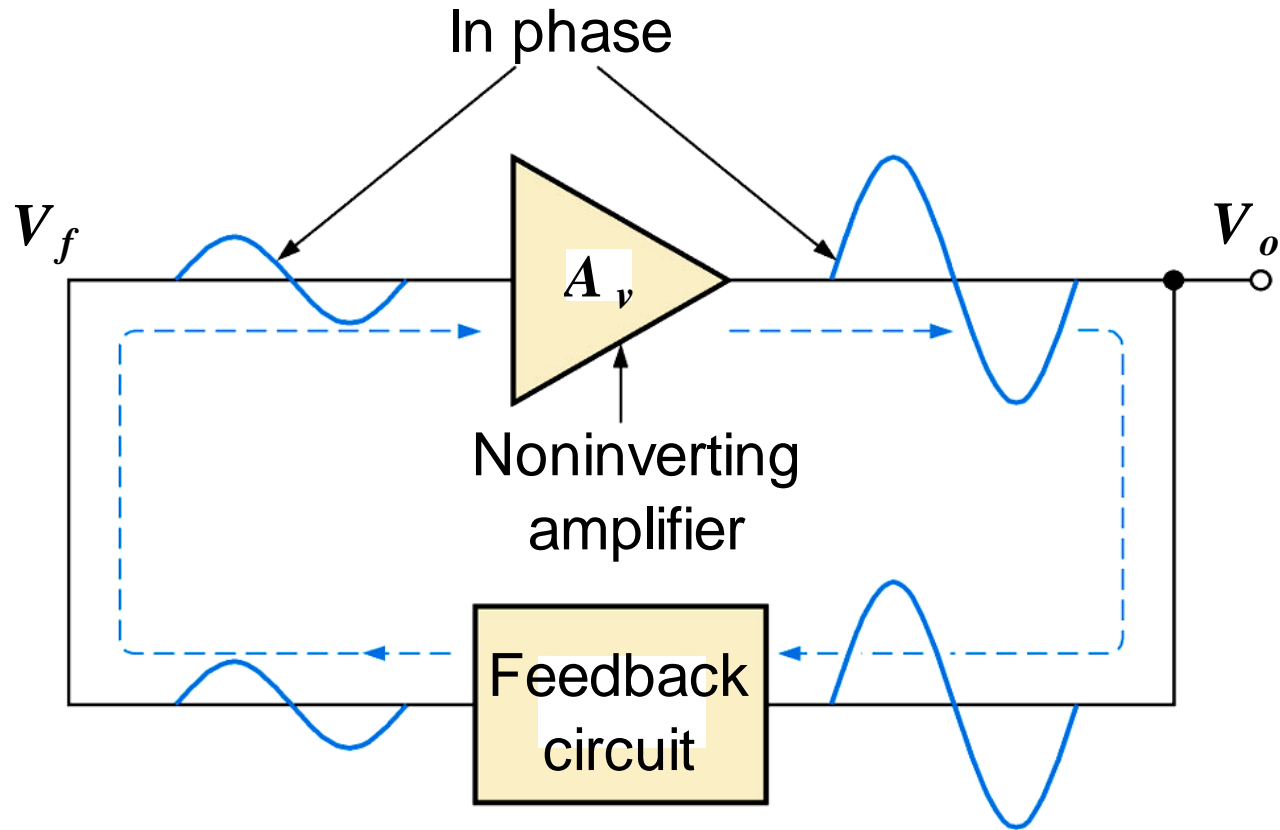
$$A(j\omega_0)\beta(j\omega_0) = \mathbf{1}$$

- This is known as **Barkhausen criterion**.
- The frequency of oscillation is solely determined by the phase characteristic of the feedback loop – the loop oscillates at the frequency for which the phase is zero.

# Basic principles for oscillation

- The feedback oscillator is widely used for generation of sine wave signals.
- The positive (in phase) feedback arrangement maintains the oscillations.
- The feedback gain must be kept to unity to keep the output from distorting.

# Basic principles for oscillation



# Design Criteria for Oscillators

1. The magnitude of the loop gain must be unity or slightly larger

$$|A\beta| = 1 \quad \text{– Barkhausen criterion}$$

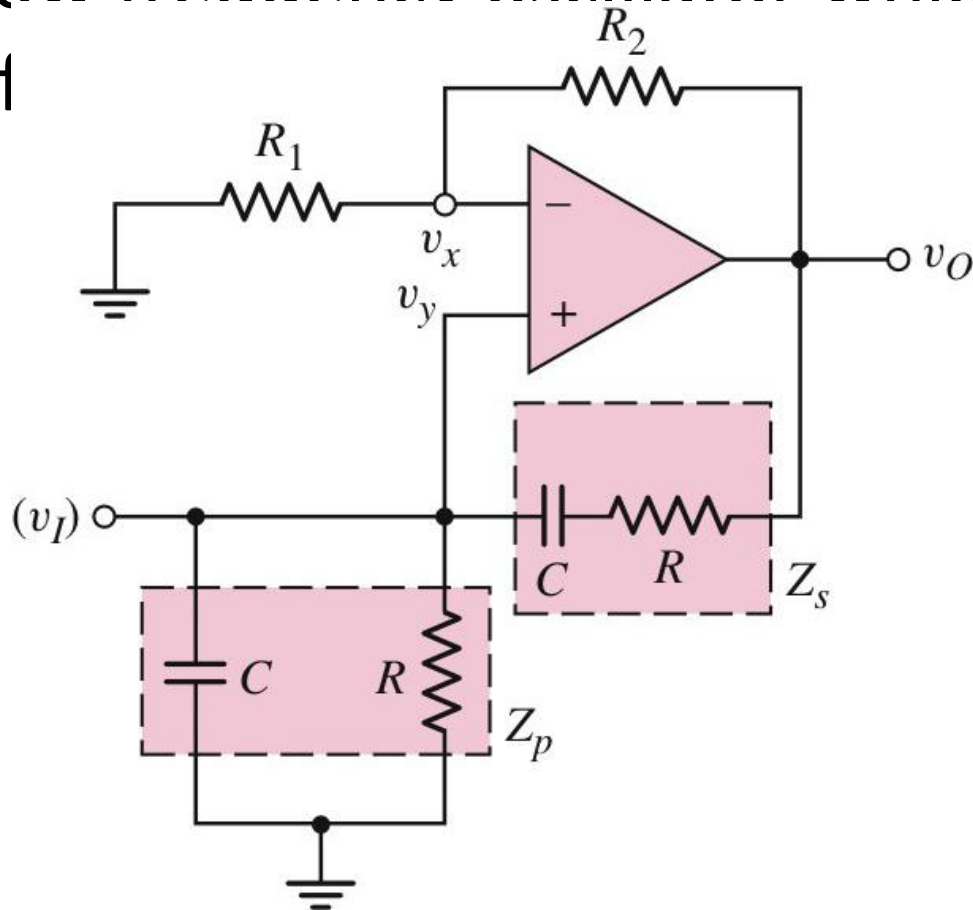
2. Total phase shift,  $\phi$  of the loop gain must be  $N \times 360^\circ$  where  $N=0, 1, 2, \dots$

# RC Oscillators

- RC feedback oscillators are generally limited to frequencies of 1 MHz or less.
- The types of RC oscillators that we will discuss are the **Wien-bridge** and the **phase-shift**

# Wien-bridge Oscillator

- It is a low frequency oscillator which ranges from a few Hz to a few kHz.



# Wien-bridge Oscillator

- The loop gain for the oscillator is;  
$$\mathbf{T}(s) = \mathbf{A}(s)\boldsymbol{\beta}(s) = \left( \mathbf{1} + \frac{\mathbf{R}_2}{\mathbf{R}_1} \right) \left( \frac{\mathbf{Z}_p}{\mathbf{Z}_p + \mathbf{Z}_s} \right)$$

- where;  $\mathbf{Z}_p = \frac{\mathbf{R}}{\mathbf{1} + s\mathbf{RC}}$

- and;  $\mathbf{Z}_s = \frac{\mathbf{1} + s\mathbf{RC}}{s\mathbf{C}}$



# Wien-bridge Oscillator

- Hence;  $T(s) = \left( 1 + \frac{R_2}{R_1} \right) \left[ \frac{1}{3 + sRC + (1/sRC)} \right]$
- Substituting for  $s$ ;  $T(j\omega) = \left( 1 + \frac{R_2}{R_1} \right) \left[ \frac{1}{3 + j\omega RC + (1/j\omega RC)} \right]$
- For oscillation frequency  $f_0$ ;  $T(j\omega_0) = \left( 1 + \frac{R_2}{R_1} \right) \left[ \frac{1}{3 + j\omega_0 RC + (1/j\omega_0 RC)} \right]$

# Wien-bridge Oscillator

- Since at the frequency of oscillation,  $T(j\omega)$  must be real (for zero phase condition), the imaginary component must be zero;

$$j\omega_0 RC + \frac{1}{j\omega_0 RC} = 0$$

- Which gives  $\omega_0 = \frac{1}{RC}$

# Wien-bridge Oscillator

- From the previous equation; 
$$T(j\omega_0) = \left(1 + \frac{R_2}{R_1}\right) \left[ \frac{1}{3 + j\omega_0 RC + (1/j\omega_0 RC)} \right]$$

- the magnitude condition is  $\frac{R_2}{R_1} = 2$

To ensure oscillation, the ratio  $R_2/R_1$  must be slightly greater than 2.

# Wien-bridge Oscillator

- With the ratio;  $\frac{R_2}{R_1} = 2$

- then;  $K \equiv 1 + \frac{R_2}{R_1} = 3$

$K = 3$  ensures the loop gain of unity – oscillation

–  $K > 3$  : growing oscillations

–  $K < 3$  : decreasing oscillations