UNIT III

LOAD FLOW ANALYSIS

FAST DECOUPLED METHOD

> J₂ & J₃ of Jacobian matrix are zero

$$\begin{bmatrix} \Delta P \\ \Delta Q \end{bmatrix} = \begin{pmatrix} J_1 & 0 \\ 0 & J_4 \end{pmatrix} \begin{bmatrix} \Delta \delta \\ \Delta |V| \end{bmatrix}$$

$$\Delta P = J_1 \Delta \delta = \begin{bmatrix} \frac{\partial P}{\partial \delta} \end{bmatrix} \Delta \delta$$

$$\Delta Q = J_4 \Delta |V| = \begin{bmatrix} \frac{\partial Q}{\partial |V|} \end{bmatrix} \Delta |V|$$

$$\frac{\Delta P}{\Delta |V_i|} = -B' \Delta \delta$$

$$\frac{\Delta Q}{\Delta |V_i|} = -B'' \Delta |V|$$

$$\Delta \delta = -\begin{bmatrix} B' \end{bmatrix}^{-1} \frac{\Delta P}{\Delta |V|}$$

$$\Delta |V| = -\begin{bmatrix} B' \end{bmatrix}^{-1} \frac{\Delta Q}{\Delta |V|}$$

$$\delta_i^{k+1} = \delta_i^k + \Delta \delta^k$$
$$\left| V_i^{k+1} \right| = \left| V_i^k \right| + \Delta \left| V_i^k \right|$$

- This method requires more iterations than NR method but less time per iteration
- It is useful for in contingency analysis

COMPARISION BETWEEN ITERATIVE METHODS

Gauss – Seidal Method

- 1. Computer memory requirement is less.
- 2. Computation time per iteration is less.
- It requires less number of arithmetic operations to complete an iteration and ease in programming.
- 4. No. of iterations are more for convergence and rate of convergence is slow (linear convergence characteristic.
- 5. No. of iterations increases with the increase of no. of buses.

NEWTON – RAPHSON METHOD

- Superior convergence because of quadratic convergence.
- ➤ It has an 1:8 iteration ratio compared to GS method.
- ➤ More accurate.
- Smaller no. of iterations and used for large size systems.

- ➤ It is faster and no. of iterations is independent of the no. of buses.
- Technique is difficult and calculations involved in each iteration are more and thus computation time per iteration is large.
- Computer memory requirement is large, as the elements of jacobian matrix are to be computed in each iteration.
- ➤ Programming logic is more complex.

FAST DECOUPLED METHOD

- It is simple and computationally efficient.
- Storage of jacobian matrix elements are 60% of NR method
- computation time per iteration is less.
- Convergence is geometric,2 to 5 iterations required for accurate solutions
- Speed for iterations is 5 times that of NR method and 2-3 times of GS method

Thank You