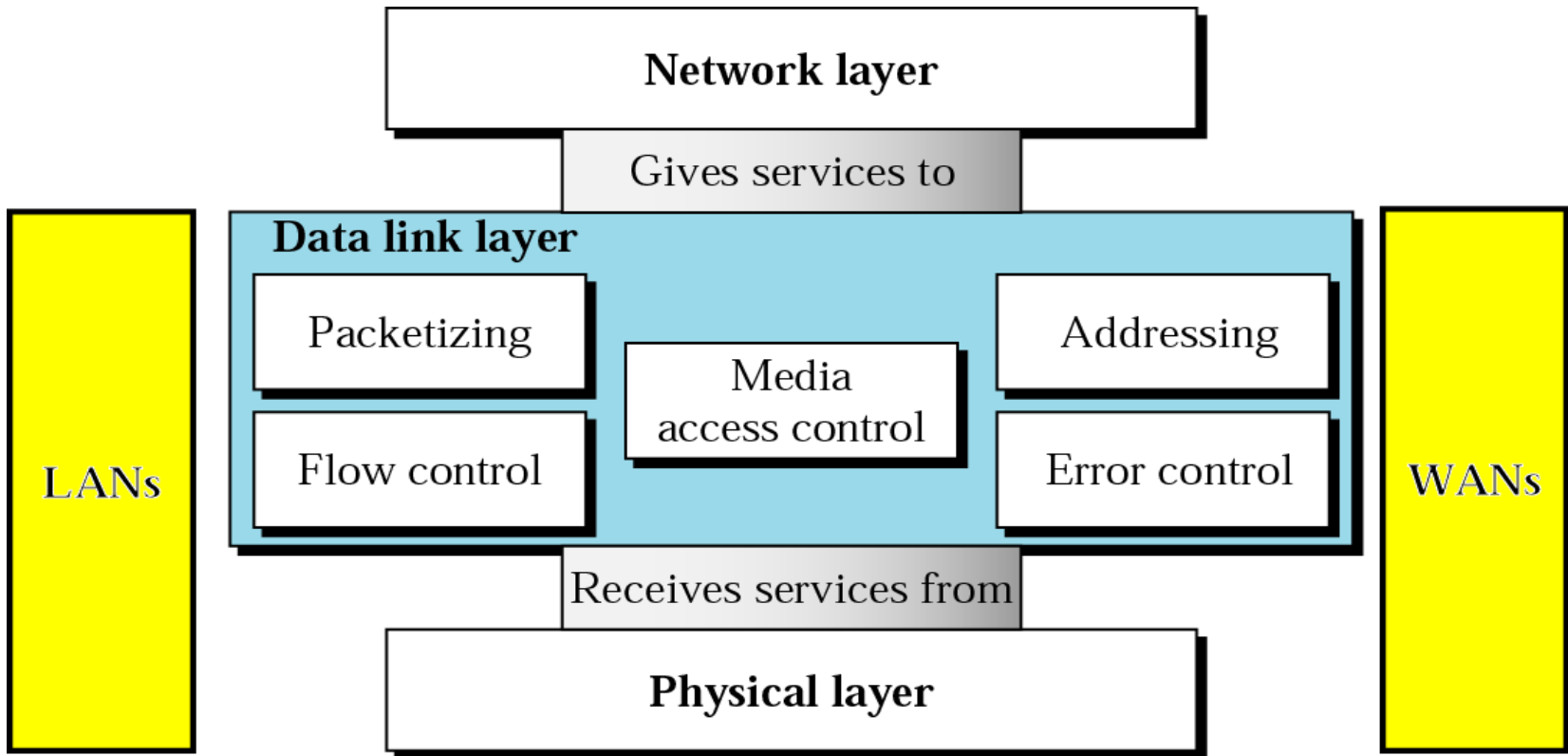


# **Data Communications and Networks Unit-2**

# Outline

- OVERVIEW
- FRAMING
- FLOW AND ERROR CONTROL
- PROTOCOLS
- NOISELESS CHANNELS
- NOISY CHANNELS
- HDLC
- ALOHA

# DATA LINK LAYER



# Overview

- The two main functions of the data link layer are **data link control** and **media access control**.
- Data link control, deals with the design and procedures for communication between two adjacent nodes: node-to-node communication.
- Media access control, or how to share the link.
- Data link control functions include **framing**, **flow and error control**, and **software implemented protocols**.

# FRAMING

- The data link layer, needs to **pack** bits into **frames**, so that each frame is distinguishable from another.
- Framing in the data link layer **separates** a message from one source to a destination, or from other messages to other destinations, by adding a **sender address** and a **destination address**.
- The whole message could be packed in **one frame**, that is **not normally** done.
- One reason is that a frame can be **very large**, making flow and error control very **inefficient**.

# Fixed-Size Framing

- In fixed-size framing, there is no need for defining the **boundaries** of the frames; the size itself can be used as a **delimiter**.
- An example of this type of framing is the ATM wide-area network, which uses frames of fixed size called cells.

# Variable-Size Framing

- In variable-size framing, we need a way to **define the end of the frame** and the **beginning of the next**.
- Two approaches were used for this purpose:
  - a character-oriented approach
  - a bit-oriented approach

# Variable-Size Framing

- **Character-Oriented Protocols**
- Data to be **carried** are **8-bit characters** from a coding system such as ASCII.
- The **header** carries the source and destination **addresses** and other **control** information,
- The **trailer** carries **error detection** or **error correction** redundant bits, are also multiples of 8 bits.
- To **separate** one frame from the next, **an 8-bit (1-byte) flag** is added at the **beginning** and the **end** of a frame
- Byte stuffing



# Variable-Size Framing

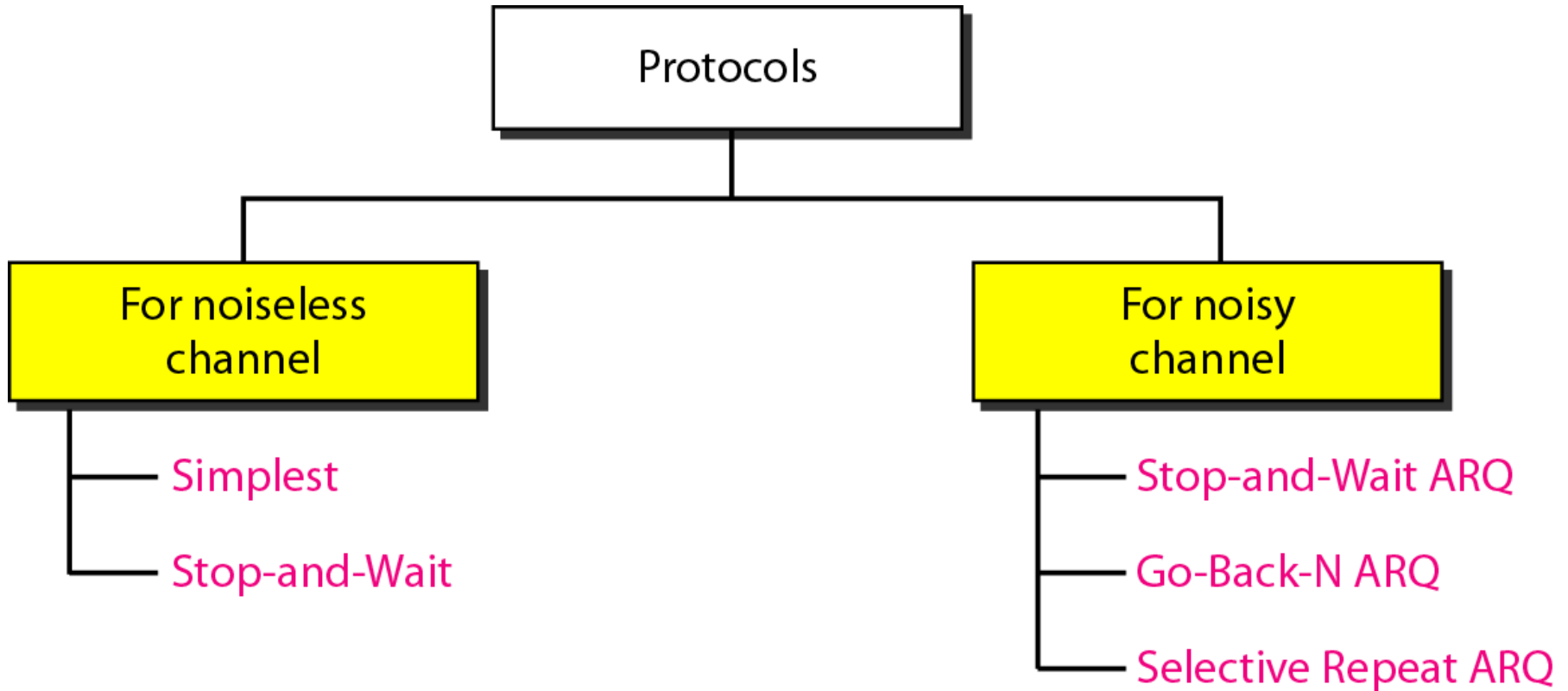
- **Bit-Oriented Protocols**

- In a bit-oriented protocol, the data section of a frame is a **sequence of bits** to be interpreted by the upper layer as text, graphic, audio, video.
- In addition to headers (and possible trailers), we still need a delimiter to separate one frame from the other.
- Most protocols use a special 8-bit pattern flag 01111110 as the delimiter to define the beginning and the end of the frame.
- Bit stuffing

# FLOW AND ERROR CONTROL

- Flow control coordinates the **amount of data** that can be **sent** before receiving an acknowledgment and is one of the most important duties of the data link layer.
- Error Control is both **error detection** and **error correction**. It allows the receiver to inform the sender of any frames **lost or damaged** in transmission and **coordinates** the **retransmission** of those frames by the sender.
- Any time an error is detected in an exchange, specified frames are **retransmitted**. This process is called **automatic repeat request (ARQ)**.

# PROTOCOLS



# PROTOCOLS

- The protocols are normally implemented in software by using one of the common programming languages.
- We divide the discussion of protocols into those that can be used for
  - noiseless (**error-free**) channels
  - noisy (**error-creating**) channels

# NOISELESS CHANNELS

- Let us first assume we have an ideal channel in which no frames are lost, duplicated, or corrupted.
- We introduce two protocols for this type of channel. The **first** is a protocol that **does not use flow control**; the second is the one **use flow control**.

# Simplest Protocol

- It is one that has no flow or error control.
- It is a unidirectional protocol in which data frames are traveling in only one direction—from the sender to receiver.
- We assume that the receiver can immediately handle any frame it receives.
- The data link layer of the receiver immediately removes the header from the frame and hands the data packet to its network layer
- The receiver can never be overwhelmed with incoming frames.

# Design

- The sender site cannot send a frame until its network layer has a data packet to send.
- The receiver site cannot deliver a data packet to its network layer until a frame arrives.
- If the protocol is implemented as a procedure, we need to introduce the idea of events in the protocol.
- The procedure at the sender site is constantly running; there is no action until there is a request from the network layer.
- The procedure at the receiver site is also constantly running, but there is no action until notification from the physical layer arrives

# Simplest Protocol

Algorithm 11.1 *Sender-site algorithm for the simplest protocol*

```
1 while (true)                // Repeat forever
2 {
3   WaitForEvent()i           // Sleep until an event occurs
4   if(Event(RequestToSend))  // There is a packet to send
5   {
6     GetData()i
7     MakeFrame()i
8     SendFrame()i           // Send the frame
9   }
10 }
```



# Simplest Protocol

Algorithm 11.2 *Receiver-site algorithm for the simplest protocol*

```
1 while(true)                                // Repeat forever
2 {
3   WaitForEvent()i                           // Sleep until an event occurs
4   if(Event(ArrivalNotification))i          //Data frame arrived
5   {
6     ReceiveFrame()i
7     ExtractData()i
8     DeliverData ()i                          //Deliver data to network layer
9   }
10 }
```

# Stop-and-Wait Protocol

- If data frames arrive at the receiver site faster than they can be processed, the frames must be stored until their use.
- To prevent the receiver from becoming overwhelmed with frames, we need to tell the sender to slow down.
- In this protocol the sender sends one frame, stops until it receives confirmation from the receiver (okay to go ahead), and then sends the next frame.

# Stop-and-Wait Protocol

Algorithm 11.3 *Sender-site algorithm for Stop-and-Wait Protocol*

```
1 while (true)                                //Repeat forever
2   canSend = true                             //Allow the first frame to go
3   {
4     WaitForEvent()i                          // Sleep until an event occurs
5     if(Event (RequestToSend) AND canSend)
6     {
7       GetData() i
8       MakeFrame();
9       SendFrame()i                            //Send the data frame
10      canSend = false;                       //cannot send until ACK arrives
11    }
12    WaitForEvent()i                          // Sleep until an event occurs
13    if(Event (ArrivalNotification) // An ACK has arrived)
14    {
15      ReceiveFrame();                          //Receive the ACK frame
16      canSend = true;
17    }
18  }
```

# Stop-and-Wait Protocol

Algorithm 11.4 Receiver-site algorithm for Stop-and-Wait Protocol

1	while (true)	<i>II Repeat forever</i>
2	{	
3	WaitForEvent();	<i>II Sleep until an event occurs</i>
4	if(Event(ArrivalNotification))	<i>IIData frame arrives</i>
5	{	
6	ReceiveFrame();	
7	ExtractData();	
8	Deliver(data);	<i>IIDeliver data to network layer</i>
9	SendFrame();	<i>II Send an ACK frame</i>
10	}	
11	}	

# NOISY CHANNELS

- **Noiseless** channels are **nonexistent**, so we need to add error control to our protocols.
- Stop-and-Wait Automatic Repeat Request protocol add a **simple error control mechanism** to the **Stop-and-Wait** Protocol.
- To detect and correct corrupted frames, we need to add **redundancy** bits to our data frame.
- When the frame arrives at the receiver site, it is checked and if it is corrupted, it is silently discarded.
- The detection of errors in this protocol is manifested by the silence of the receiver.

# NOISY CHANNELS

- We discuss three protocols in this section that use error control.
  - Stop & Wait Automatic Repeat Request
  - Go-Back-N Automatic Repeat Request
  - Selective Repeat Automatic Repeat Request

# Stop-and-Wait ARQ

- Lost frames are more **difficult** to handle than **corrupted** ones.
- The received frame could be the **correct** one, or a **duplicate**, or a **frame out of order**.
- The solution is to **number the frames**.
- When the receiver receives a data frame that is out of order, this means that frames were either **lost** or **duplicated**.

# Stop-and-Wait ARQ

- The completed and lost frames need to be resent in this protocol.
- If the receiver does not respond when there is an error, how can the sender know which frame to resend?
- To remedy this problem, the sender keeps a copy of the sent frame. At the same time, it starts a timer.
- If the timer expires and there is no ACK for the sent frame, the frame is resent, the copy is held, and the timer is restarted.



# Stop-and-Wait ARQ

- Since an ACK frame can also be **corrupted** and **lost**, it too needs **redundancy** bits and a **sequence** number.
- The **ACK** frame for this protocol has a **sequence number** field.

# Sequence Numbers

- A field is added to the data frame to hold the sequence number of that frame.
- The sequence numbers of course can wrap around. For example, if we decide that the field is  $m$  bits long, the sequence numbers start from 0, go to  $2^m - 1$ , and then are repeated.
- Let us reason out the range of sequence numbers we need. Assume we have used  $x$  as a sequence number; we only need to use  $x + 1$  after that. There is no need for  $x + 2$

# Acknowledgment Numbers

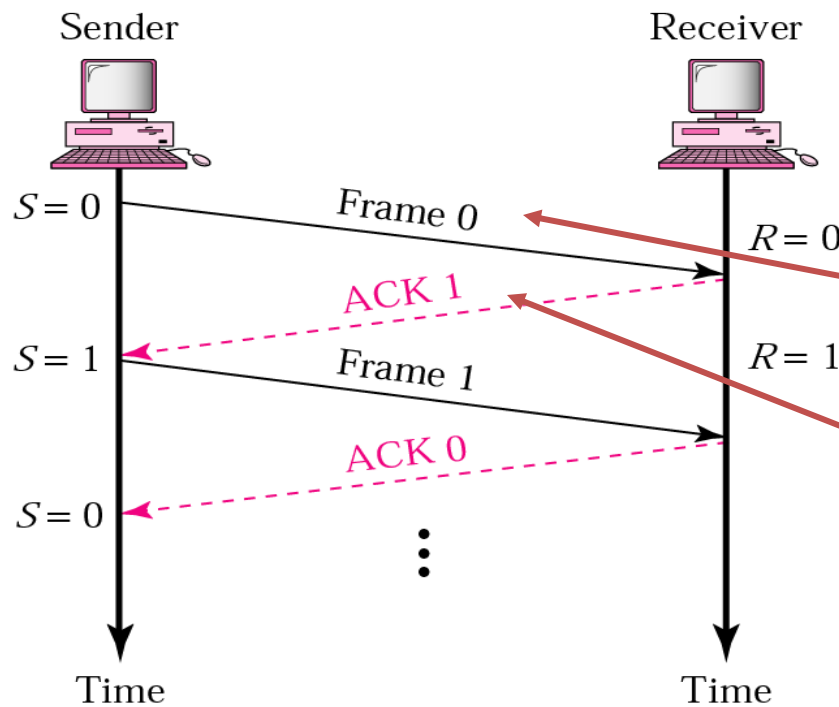
- The acknowledgment numbers always announce the sequence number of the next frame expected by the receiver.
- For example, if frame 0 has arrived safe and sound, the receiver sends an ACK frame with acknowledgment 1 (meaning frame 1 is expected next).
- If frame 1 has arrived safe and sound, the receiver sends an ACK frame with acknowledgment 0 (meaning frame 0 is expected).

# Stop-and-Wait Automatic Repeat Request(Summary)

- Simplest flow and error control mechanism
- The sending device keeps a copy of the last frame transmitted until it receives an acknowledgement
  - identification of duplicate transmission (lost or delayed ACK)
- a damaged or lost frame is treated in the same way
- timers introduced
- positive ACK sent only for frames received safe & sound

# Stop-and-Wait ARQ

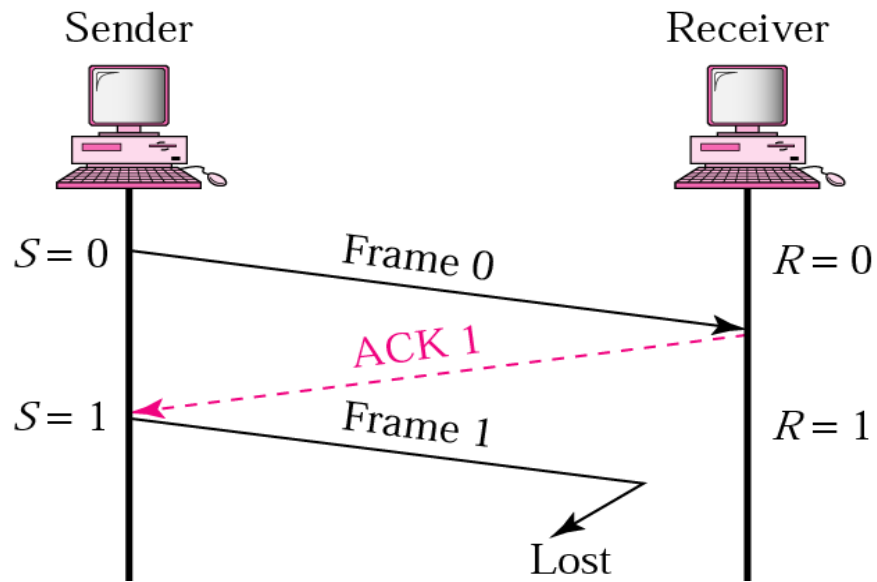
## -Normal operation-



- The sender will not send the next piece of data until it is sure that the current one is correctly received
- sequence number necessary to check for duplicated packets
- No **NACK** – when packet is corrupted – duplicate **ACKs** instead

# Stop-and-Wait ARQ

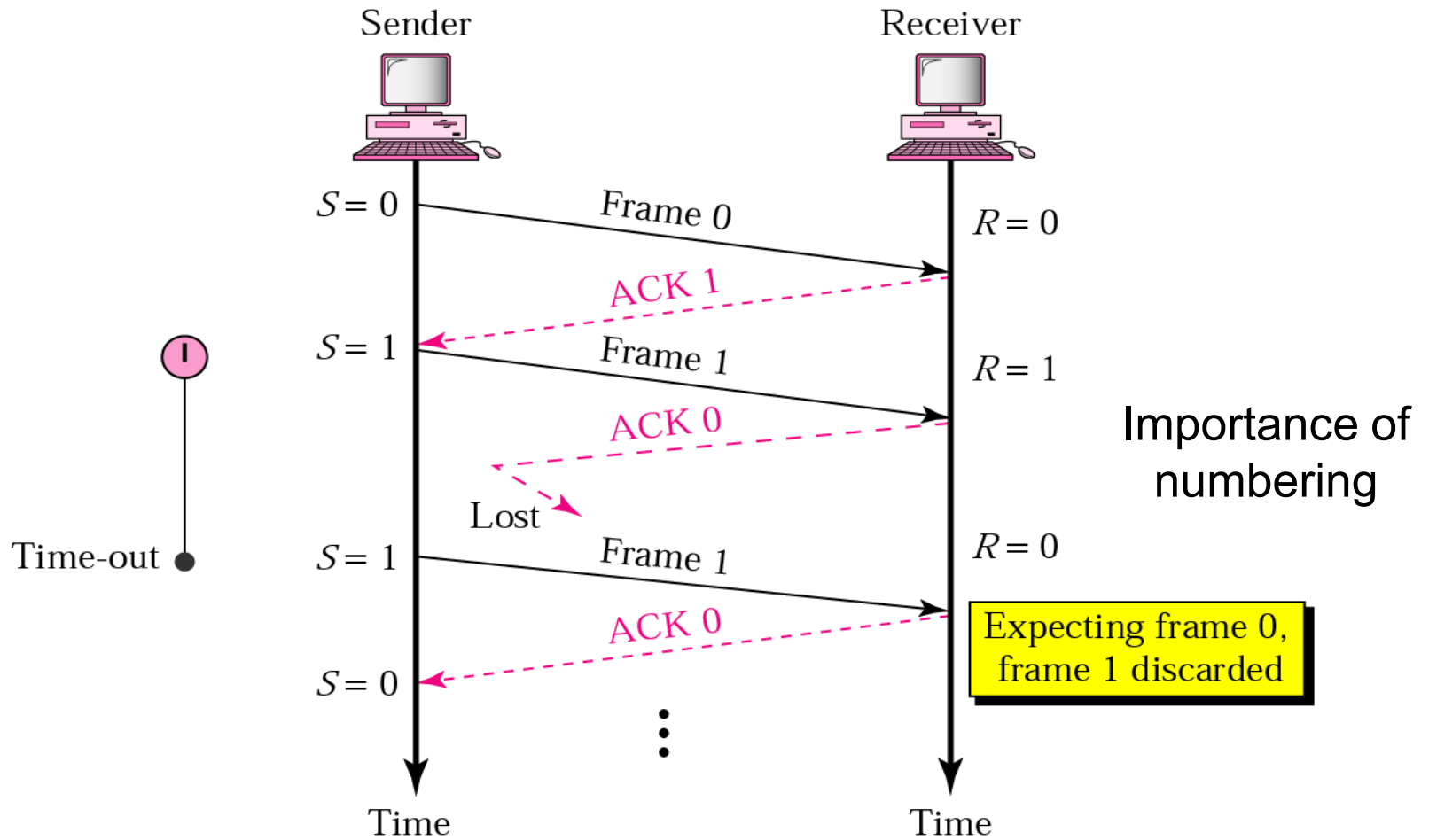
## -Lost or damaged frame-



roundtrip delay  
+  
processing in the  
receiver

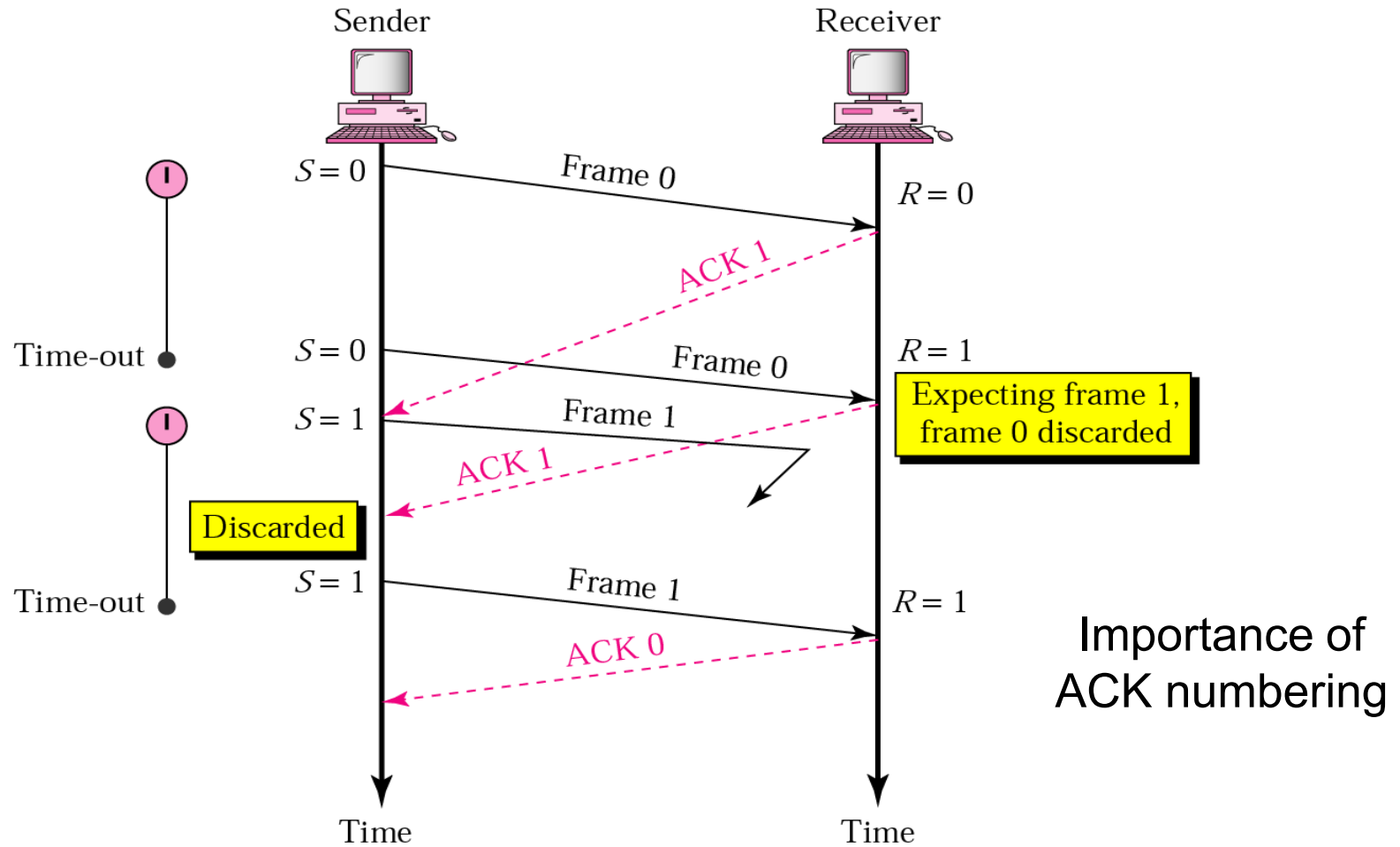
# Stop-and-Wait ARQ

## -Lost ACK-



# Stop-and-Wait ARQ

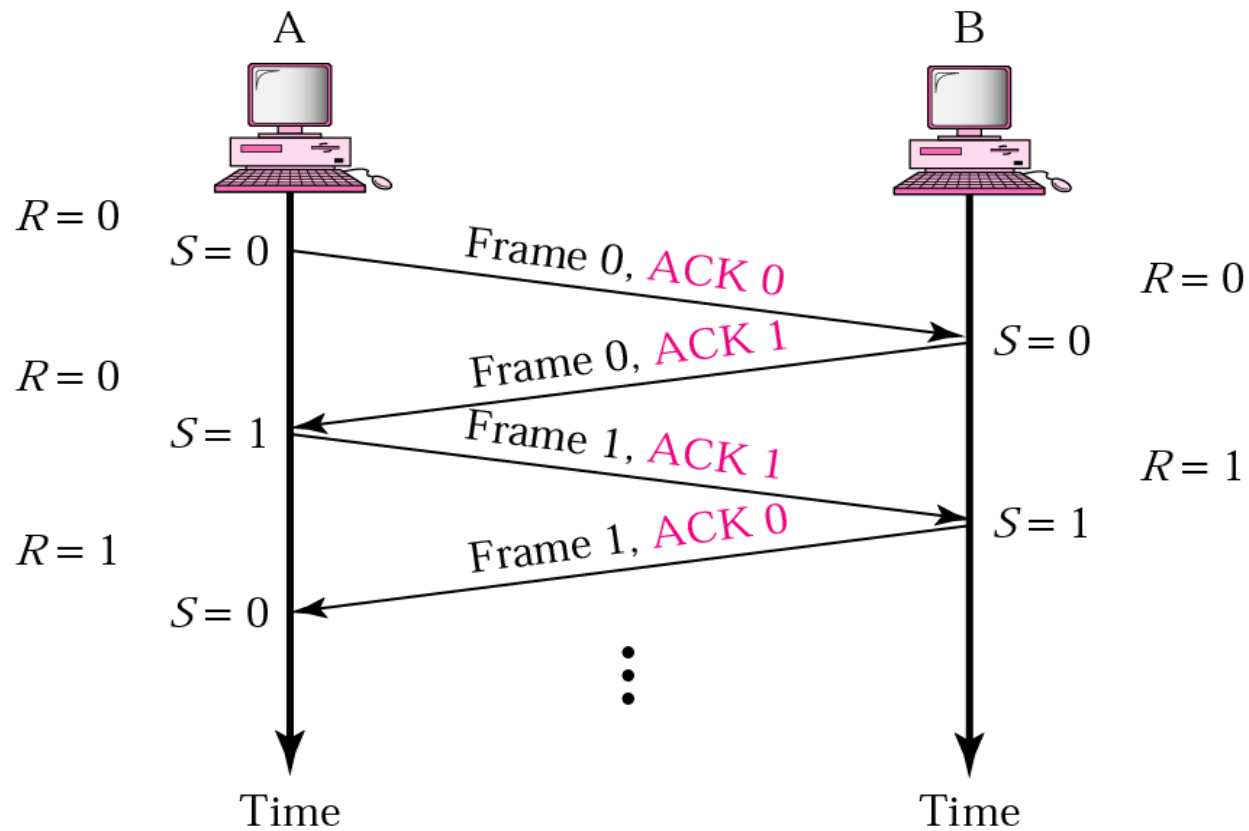
## -Delayed ACK-





# Duplex Stop-and-Wait ARQ

- Piggybacking
  - combine data with ACK (less overhead saves bandwidth)



# Drawbacks of Stop-and-Wait ARQ

- After each frame sent the host must wait for an ACK
  - inefficient use of bandwidth
- To improve efficiency ACK should be sent after multiple frames
- Alternatives: Sliding Window protocols
  1. Go-back- $N$  ARQ
  2. Selective Repeat ARQ

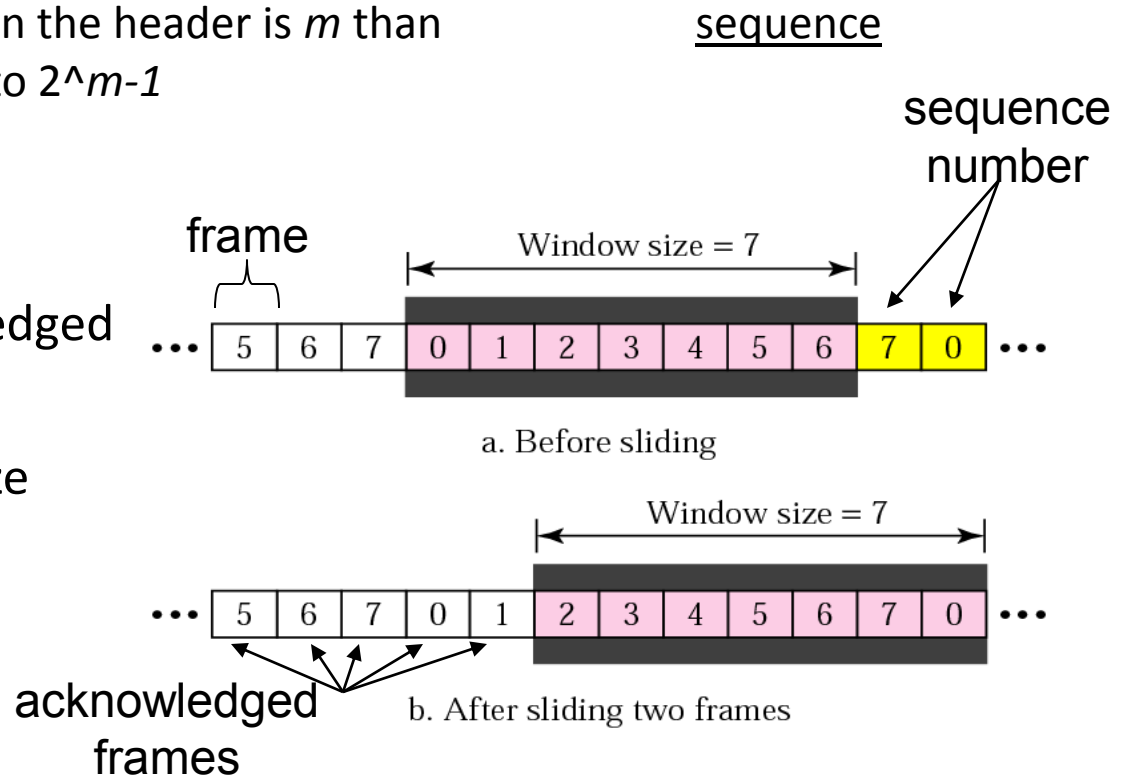
# Pipelining

- One task begins before the other one ends
  - increases efficiency in transmission
- There is no pipelining in Stop-and-Wait ARQ

# Sliding Window Protocols

- Sequence numbers
  - sent frames are numbered sequentially
  - number of frames stored in the header
    - if the number of bits in the header is  $m$  than number goes from 0 to  $2^m - 1$

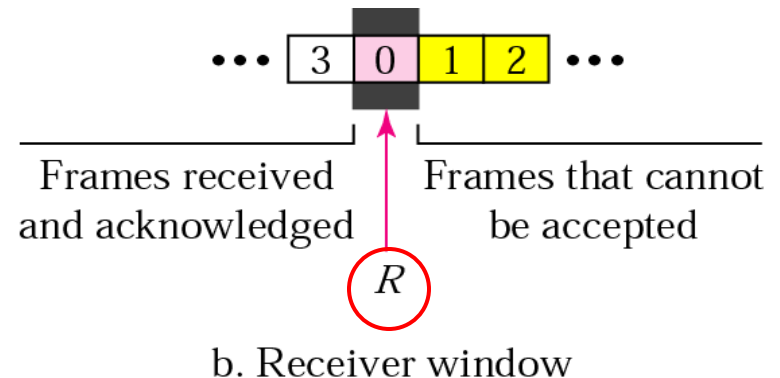
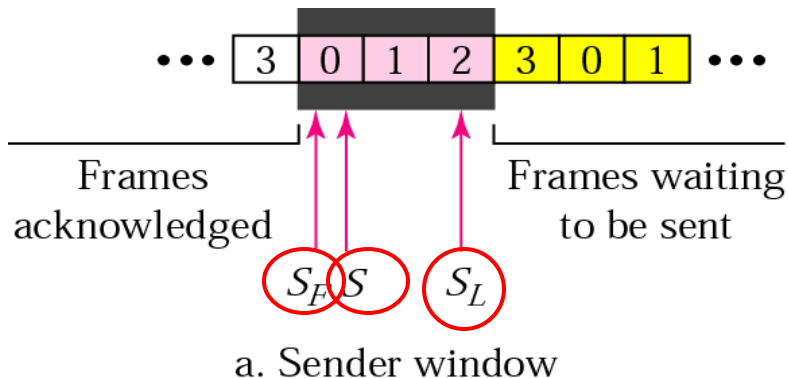
- Sliding window
  - to hold the unacknowledged outstanding frames
  - the receiver window size always 1



# Go-back-N

## -Control variables-

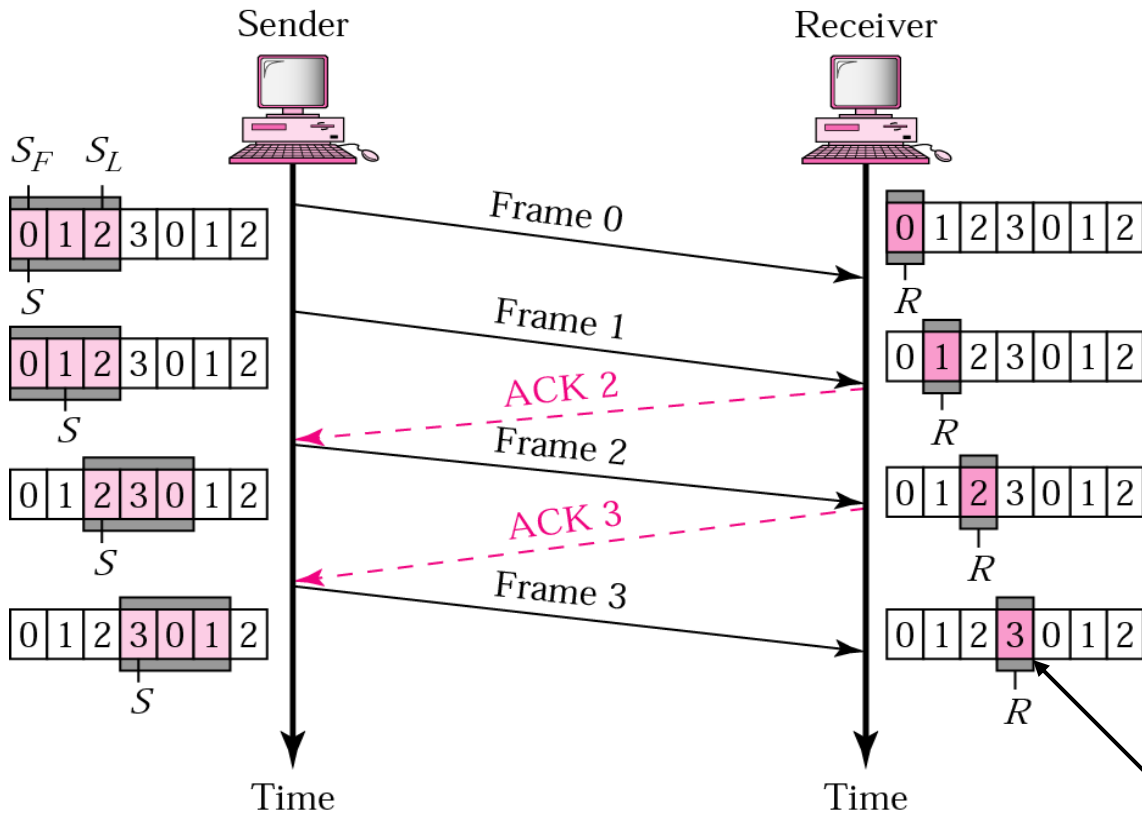
- $S$ - holds the sequence number of the recently sent frame
- $SF$  – holds sequence number of the first frame in the window
- $SL$  – holds the sequence number of the last frame
- $R$  – sequence number of the frame expected to be received



# The name of Go-back- $N$ : why?

- Re-sending frame
  - when the frame is damaged the sender goes back and sends a set of frames starting from the last one ACKn'd
  - the number of retransmitted frames is  $N$
- Example:
- The window size is 4.
- A sender has sent frame 6 and the timer expires for frame 3 (frame 3 not ACKn'd). The sender goes back and re-sends the frames 3, 4, 5 and 6.

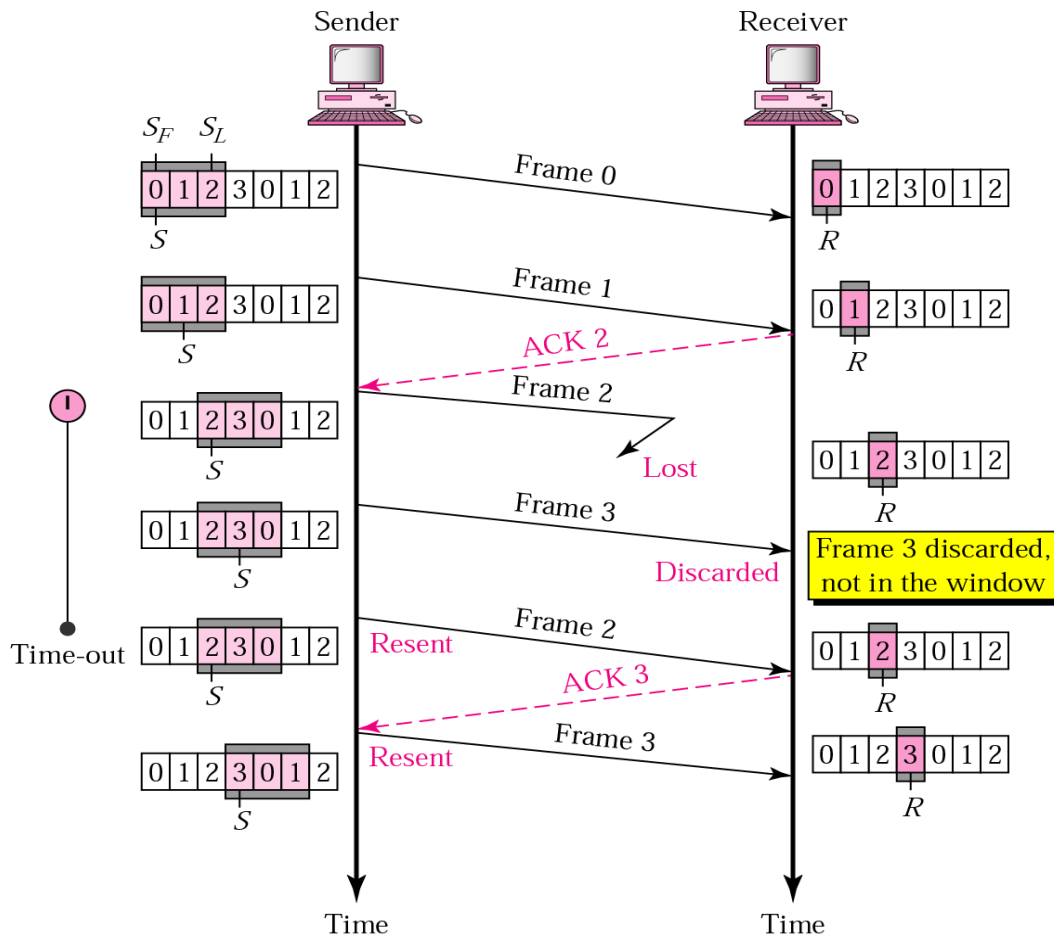
# Go-back-N -normal operation-



- How many frames can be transmitted without acknowledgment?
- ACK1 – not necessary if ACK2 is sent
- Cumulative ACK

expected sequence number

# Go-back-N -damaged or lost frame-



damaged frames  
are discarded!

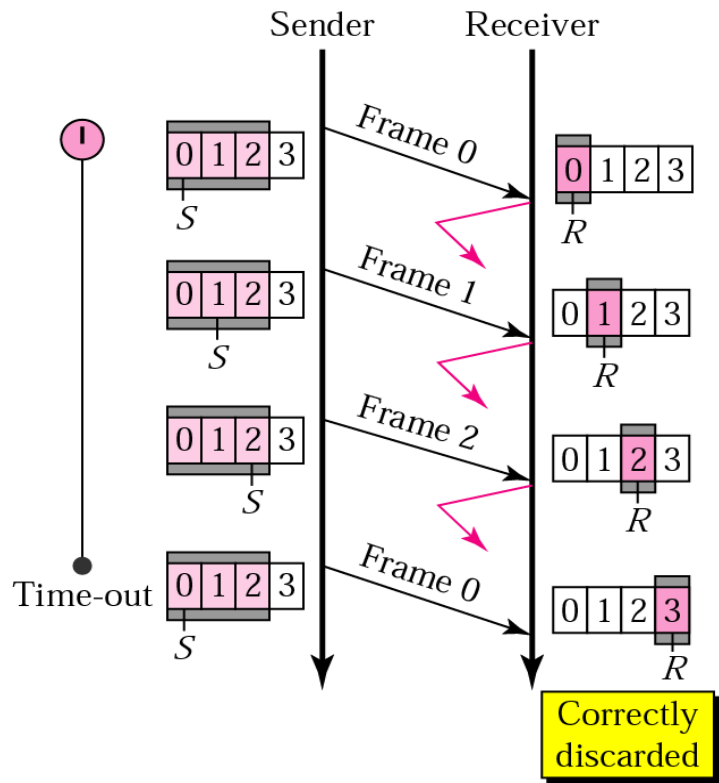
Why are correctly  
received packets  
not buffered?

What is the  
disadvantage of  
this?



# Go-back-N

## -sender window size-



a. Window size  $< 2^m$  ← sequence number

# Go-back-N

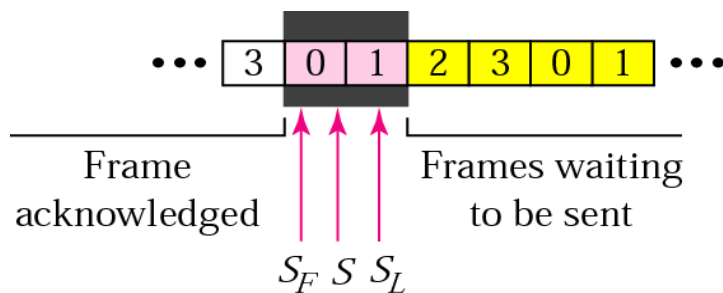
- Inefficient
  - all out of order received packets are discarded
- This is a problem in a noisy link
  - many frames must be retransmitted -> bandwidth consuming
- Solution
  - re-send only the damaged frames
- Selective Repeat ARQ
  - avoid unnecessary retransmissions

*Note*

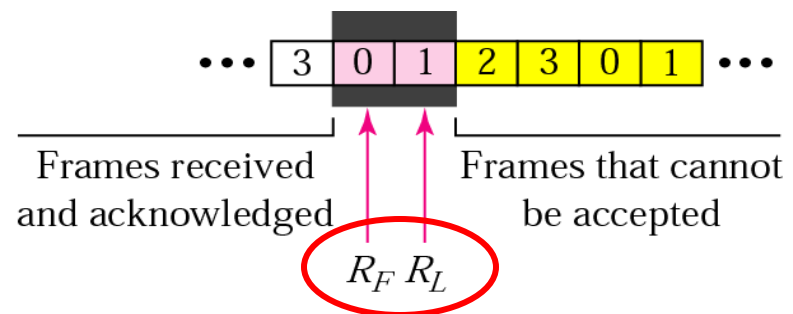
**Stop-and-Wait ARQ is a special case of Go-Back-N ARQ in which the size of the send window is 1.**

# Selective Repeat ARQ

- Processing at the receiver more complex
- The window size is reduced to one half of  $2^m$
- Both the transmitter and the receiver have the same window size
- Receiver expects frames within the range of the sequence numbers



a. Sender window

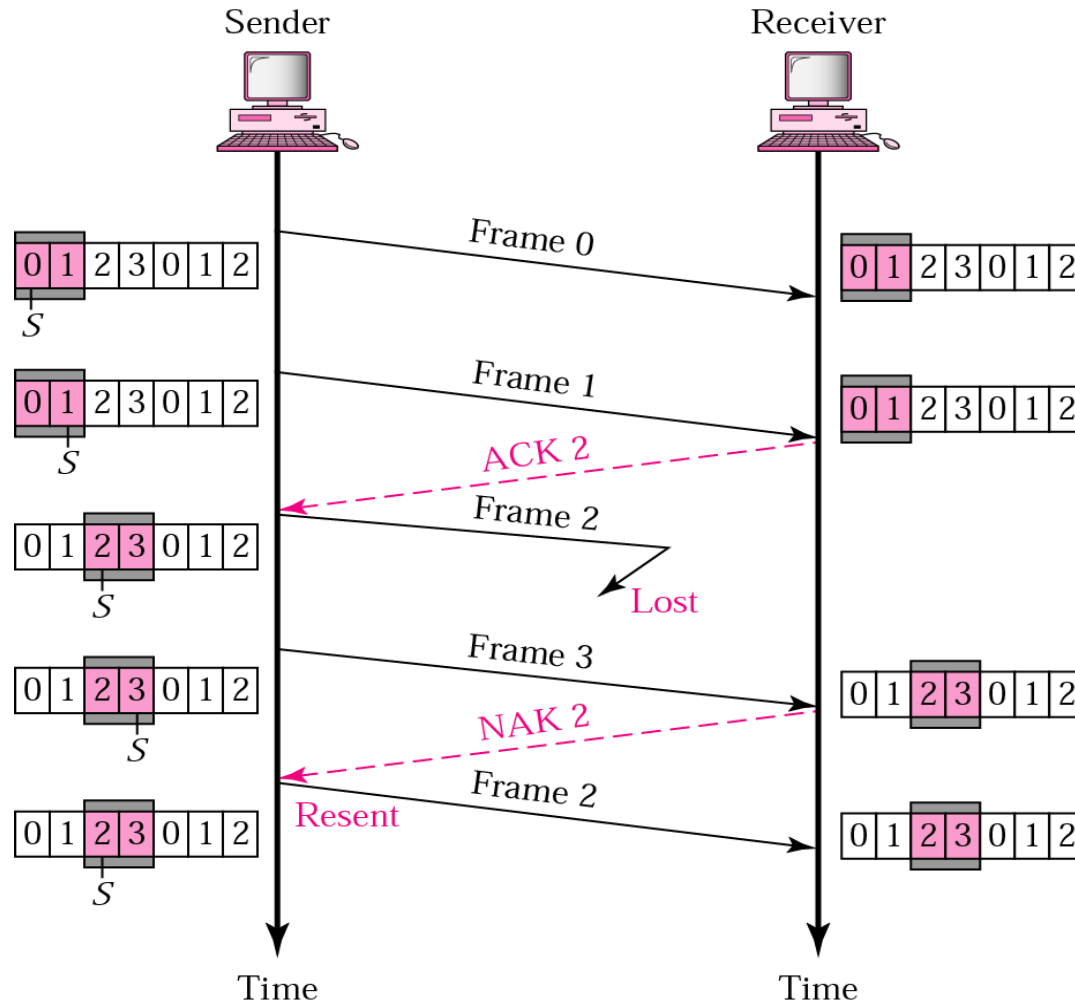


b. Receiver window

# Selective Repeat ARQ

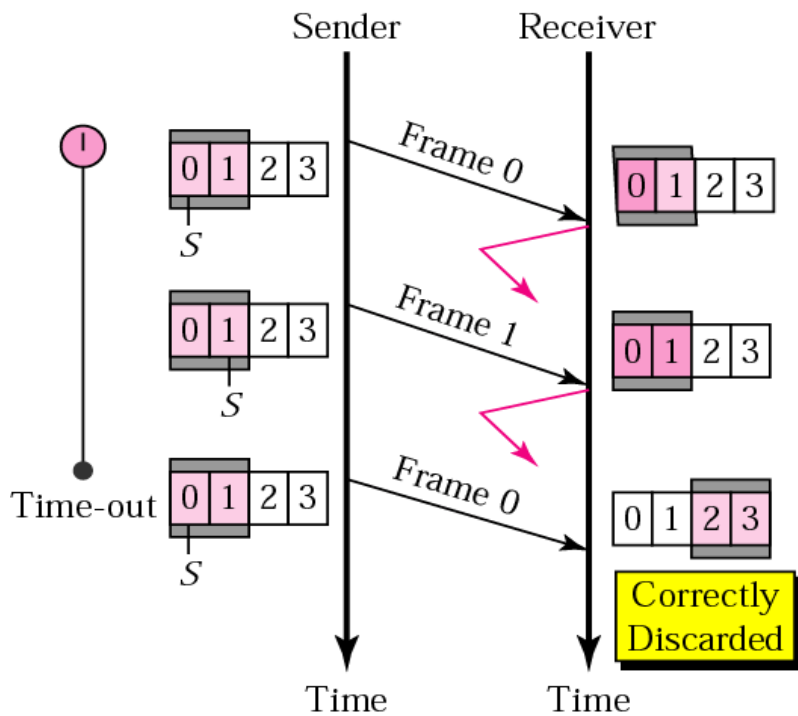
## -lost frame-

Note:  
retransmission  
triggered with NACK  
and not with  
expired timer



# Selective Repeat ARQ

-sender window size-



a. Window size =  $2^{m-1}$

# HDLC

- High-level Data Link Control (HDLC) is a bit-oriented protocol for communication over point-to-point and multipoint links.
- HDLC provides two common transfer modes that can be used in different configurations:
  - Normal response mode (NRM)
  - Asynchronous balanced mode (ABM)

# Normal Response Mode

- In normal response mode (NRM), the station configuration is unbalanced.
- We have one primary station and multiple secondary stations. A primary station can send commands; a secondary station can only respond.
- The NRM is used for both point-to-point and multiple-point links.



# Asynchronous Balanced Mode

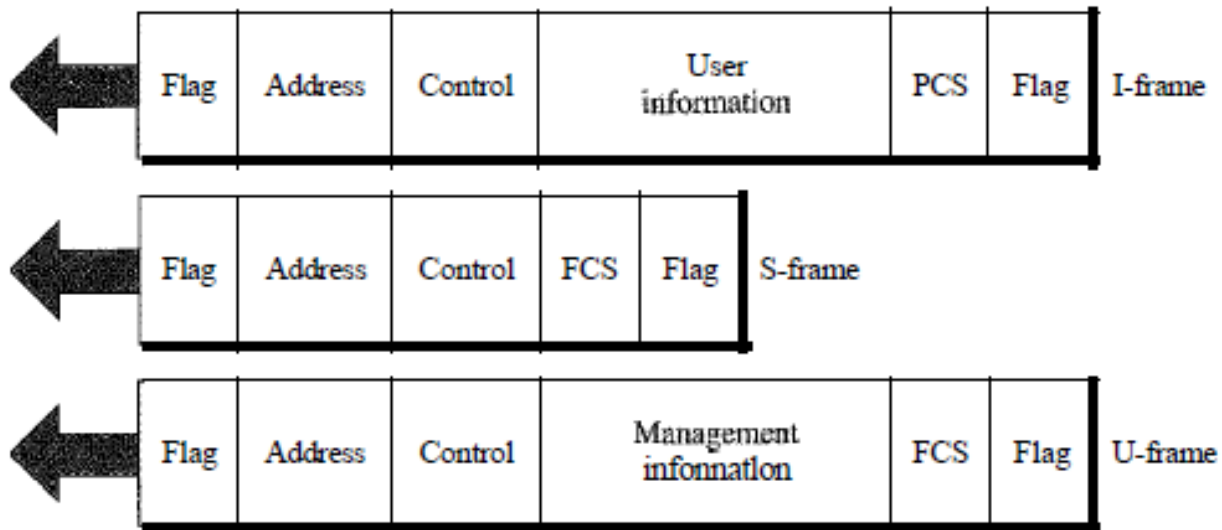
- In asynchronous balanced mode (ABM), the configuration is balanced. The link is point-to-point, and each station can function as a primary and a secondary

# Frames

- HDLC defines three types of frames: information frames (I-frames), supervisory frames (S-frames), and unnumbered frames (V-frames).
- I-frames are used to transport user data and control information relating to user data .
- S-frames are used only to transport control information.
- V-frames are reserved for system management.

# Frame Format

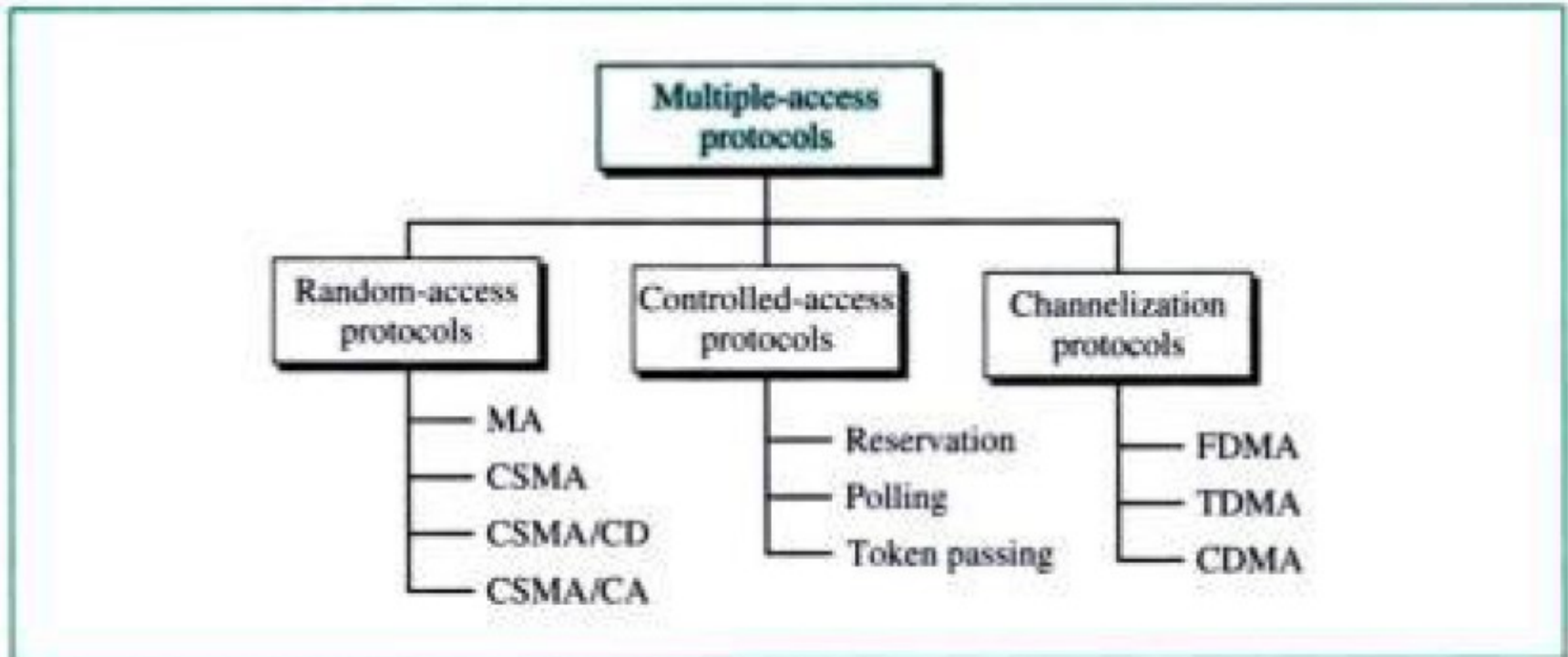
Figure 11.27 HDLC frames



# Multiple Access (Chapter 12)

- In the protocols we described, we assumed that there is an available dedicated link (or channel) between the sender and the receiver.
- This assumption may or may not be true.

# Multiple Access



# RANDOM ACCESS

- In random access no station is superior to another station and none is assigned the control over another.
- At each instance, a station that has data to send uses a procedure defined by the protocol to make a decision on whether or not to send.
- This decision depends on the state of the medium (idle or busy)
- if more than one station tries to send, there is an access conflict-collision-and the frames will be either destroyed or modified.

# ALOHA

- ALOHA, the earliest random access method
- The idea is that each station sends a frame whenever it has a frame to send. However, since there is only one channel to share, there is the possibility of collision.
- The pure ALOHA protocol relies on acknowledgments from the receiver. When a station sends a frame, it expects the receiver to send an acknowledgment. If the
- acknowledgment does not arrive after a time-out period, the station assumes that the frame has been destroyed and resends the frame.

# ALOHA

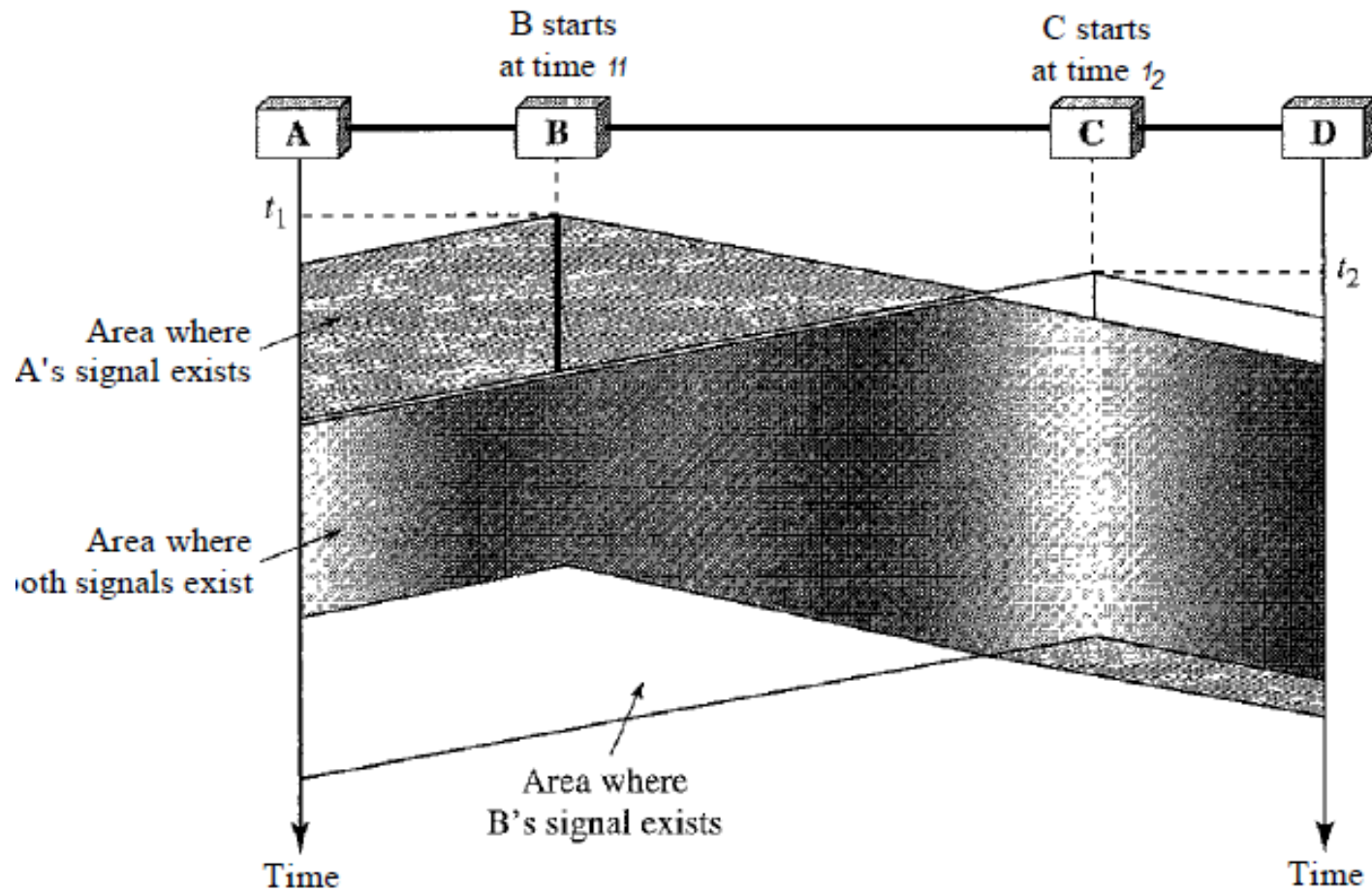
- Pure ALOHA dictates that when the time-out period passes, each station waits a random amount of time before resending its frame.
- The randomness will help avoid more collisions. We call this time the back-off time



# Carrier Sense Multiple Access (CSMA)

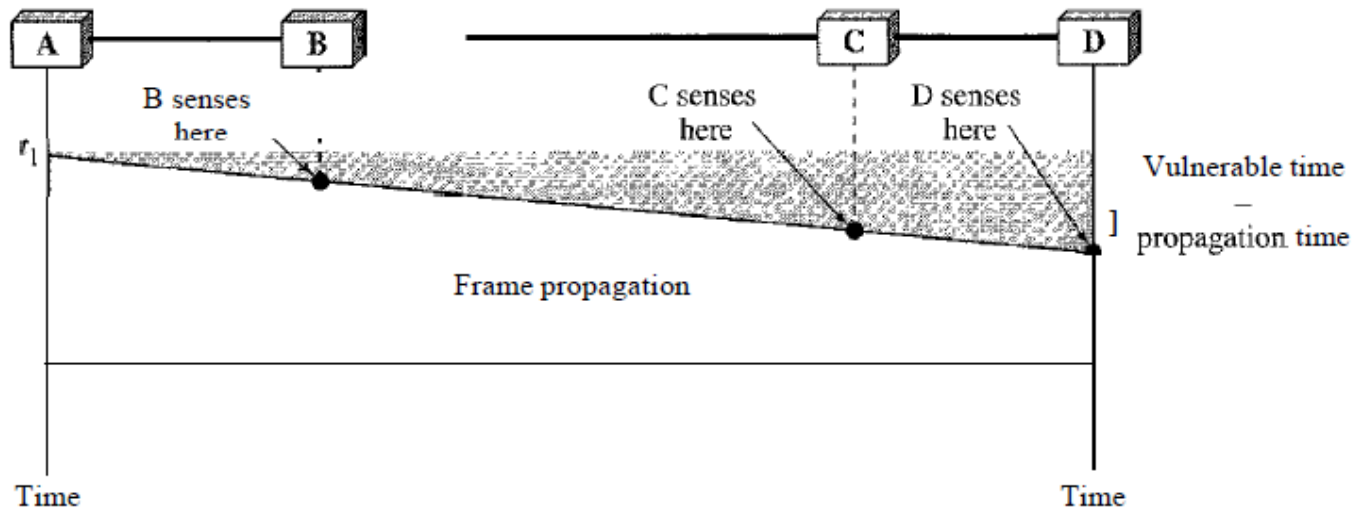
- To minimize the chance of collision and, therefore, increase the performance, the CSMA method was developed.
- The chance of collision can be reduced if a station senses the medium before trying to use it.
- CSMA can reduce the possibility of collision, but it cannot eliminate it.

# Carrier Sense Multiple Access (CSMA)



# Vulnerable Time for CSMA

- The vulnerable time for CSMA is the propagation time  $T_p$
- This is the time needed for a signal to propagate from one end of the medium to the other



# Carrier Sense Multiple Access with Collision Detection (CSMA/CD)

- The CSMA method does not specify the procedure following a collision.
- Carrier sense multiple access with collision detection (CSMA/CD) augments the algorithm to handle the collision.

# CONTROLLED ACCESS

- In controlled access, the stations consult one another to find which station has the right to send.
- A station cannot send unless it has been authorized by other stations
- Reservation
  - a station needs to make a reservation before sending data.
- Polling
  - its works with topologies in which one device is designated as a primary station.
  - All data exchanges must be made through the primary device even when the ultimate destination is a secondary device

# CONTROLLED ACCESS

- Token Passing
  - The stations in a network are organized in a logical ring.
  - a special packet called a token circulates through the ring. The possession of the token gives the station the right to access the channel and send its data.

# CHANNELIZATION

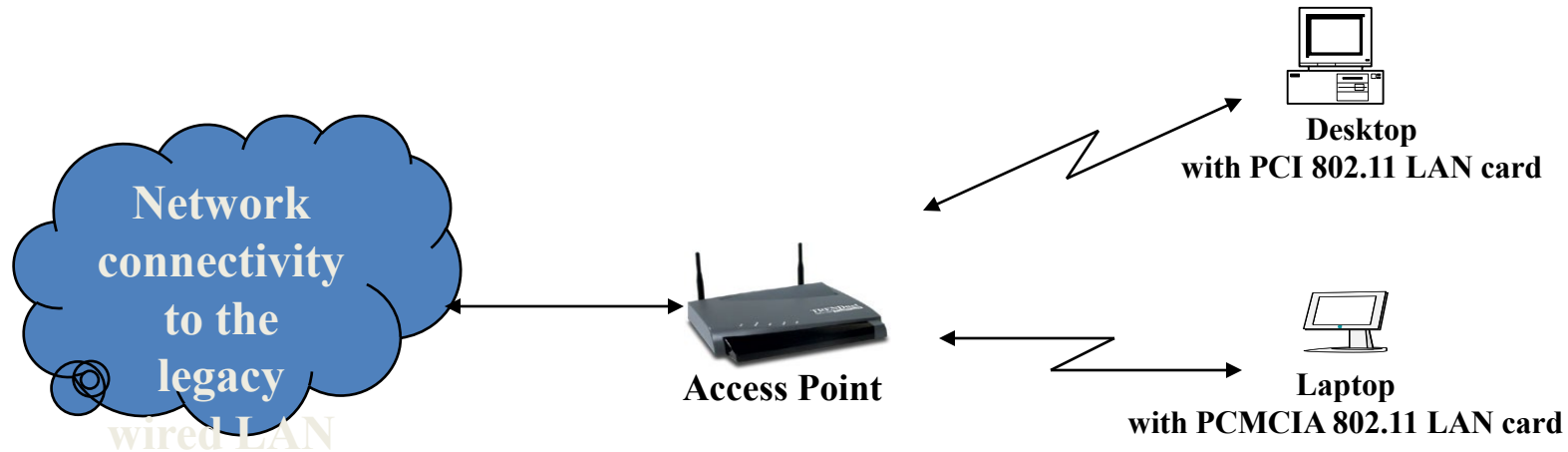
- Channelization is a multiple-access method in which the available bandwidth of a link is shared in time, frequency, or through code, between different stations.
- Frequency-Division Multiple Access (FDMA)
  - Each station is allocated a band to send its data.
- Time-Division Multiple Access (TDMA)
  - Each station is allocated a time slot during which it can send data.

# CHANNELIZATION

- Code-Division Multiple Access (CDMA)
  - It differs from TDMA because all stations can send data simultaneously; there is no timesharing.
  - CDMA simply means communication with different codes



# 802.11 Wireless LAN



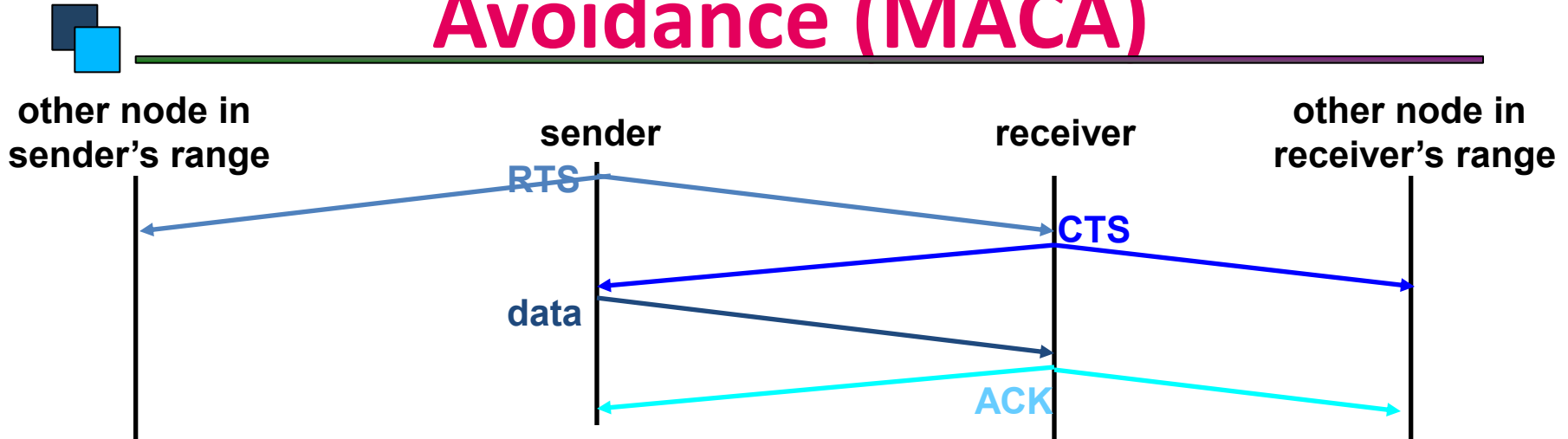
- ❑ Provides network connectivity over wireless media
- ❑ An Access Point (AP) is installed to act as Bridge between Wireless and Wired Network
- ❑ The AP is connected to wired network and is equipped with antennae to provide wireless connectivity

## 802.11 Wireless LAN

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- ❑ Range ( Distance between Access Point and WLAN client) depends on structural hindrances and RF gain of the antenna at the Access Point
- ❑ To service larger areas, multiple APs may be installed with a 20-30% overlap
- ❑ A client is always associated with one AP and when the client moves closer to another AP, it associates with the new AP (Hand-Off)
- ❑ Three flavors:
  - ❑ 802.11b
  - ❑ 802.11a
  - ❑ 802.11g

# Multiple Access with Collision Avoidance (MACA)



## Before every data transmission

- Sender sends a Request to Send (RTS) frame containing the length of the transmission
- Receiver respond with a Clear to Send (CTS) frame
- Sender sends data
- Receiver sends an ACK; now another sender can send data

## When sender doesn't get a CTS back, it assumes collision

## WLAN : 802.11b

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- The most popular 802.11 standard currently in deployment.
- Supports 1, 2, 5.5 and 11 Mbps data rates in the 2.4 GHz ISM (Industrial-Scientific-Medical) band

## WLAN : 802.11a

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- ❑ Operates in the 5 GHz UNII (Unlicensed National Information Infrastructure) band
- ❑ Incompatible with devices operating in 2.4GHz
- ❑ Supports Data rates up to 54 Mbps.

## WLAN : 802.11g

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- Supports data rates as high as 54 Mbps on the 2.4 GHz band
- Provides backward compatibility with 802.11b equipment