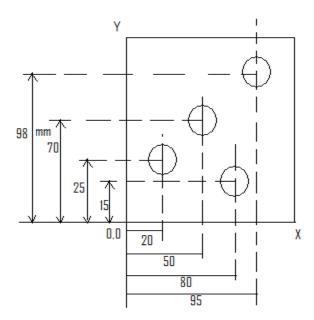
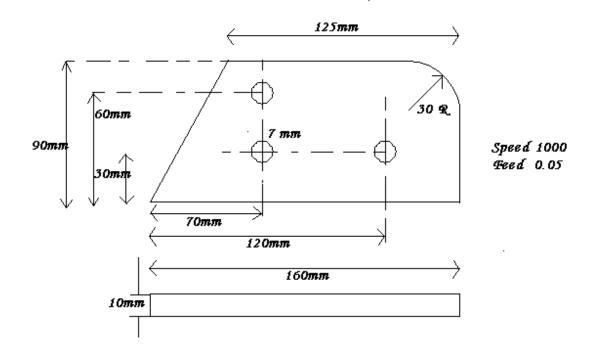
Computer Aided Manufacturing (EME031)

- 1. What is the need to automation for growing the country like India? Explain briefly.
- 2. Define a system? Make neat sketches and explain open and close loop systems.
- 3. What are the manufacturing systems and how are they distinguishing from production systems?
- 4. List out the advantages and disadvantages of NC systems. Under what circumstances use of NC would be preferred?
- 5. What is the difference between absolute positioning and incremental positioning?
- To prepare the program for 4holes on a part as shown in the figure. Complete the sequence and coordinates to represent the movement of an NC drilling machine table. The drill diameter is 10mm and the Z position is zero at 90 mm above the table surface.(F= 150,S= 1000)



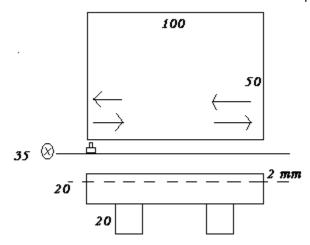
- 7. What is the principle of interpolators and explain briefly?
- 8.how is CNC distinguished from conventional NC?
- 9. What is a system? The difference between a closed loop control system and an open control system?
- 10. What is the difference between point-to-point and continuous path control in a motion control system?
- 11. What do you mean by word format? Explain briefly.
- 12. Explain the basic differences between NC and CNC machines?

- 13.List out the advantages and disadvantages of NC systems. Under what circumstances use of NC would be preferred?
- 14.List the advantages of computer aided part programming. What factors must be consider in the selection of a programming systems? Discuss.
- 15. Write the NC part programming in word address format for drilling the three holes in the given figure?

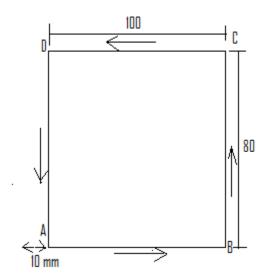


OR 16.What is APT ? Explain four basic types of statements in the APT language?

17. For plain milling operation, a workpiece of $100 \text{mm} \times 50 \times 20$ has to be machined, on the top surfaces with an end cutter of 20 mm dia. Take depth of cut 5 mm. Feed = 100



- 18. Write a short note on the following:
 - (a) Lean production
 - (b) Macro statement
 - (c) Improving accuracy
- 19. Explain about digital differential analyzers'?
- 20. Write a short note on
 - A.DC Motor
 - **B.Stepping Motor**
 - C.Adaptive control
- 21. Briefly describe the three phases of the analog-to-digital conversion process?
- **22.** Define what is group —Technology. Enumerate its benefits and disadvantages.
- 23. Differentiate between cellular manufacturing and flexible manufacturing. Indicate their areas of application
- 24. Write a short note on
 - 1. Linear interpolator
 - 2. Counting devices
- 25. Briefly describe about the digital to analog conversion process?
- 1.Part programme of milling operation (straight line) tool position = 10mm above the job in z direction and (-) 10 mm in the X direction. F = 200



- 26. Briefly explains about part programming with APT and what are the basic types of statement in the APT language?
- 27. Write short notes on
 - 1. APT Geometry statements.
 - 2. APT Motion commands.
- 28. Briefly explain about the contouring motions?
- 29. Make the difference between postprocessor and auxiliary statement?

- 30. Write the APT motion commands to profile mill the outside edges of our (any) sample work part?
- **31.** Define what is group –Technology. Enumerate its benefits and disadvantages. 32.Differentiate between cellular manufacturing and flexible manufacturing. Indicate their areas of application.
- 33. Briefly explains about the concept of Mechatronics and MEMS.