Introduction to Electromagnetic Fields; Maxwell's Equations; Electromagnetic Fields in Materials; Electrostatics: Coulomb's Law, Electric Field, Discrete and Continuous Charge Distributions; Electrostatic Potential

#### Lecture 2 Objectives

- To provide an overview of classical electromagnetics, Maxwell's equations, electromagnetic fields in materials, and phasor concepts.
- To begin our study of electrostatics with Coulomb's law; definition of electric field; computation of electric field from discrete and continuous charge distributions; and scalar electric potential.

- Electromagnetics is the study of the effect of charges at rest and charges in motion.
- Some special cases of electromagnetics:
  - Electrostatics: charges at rest
  - Magnetostatics: charges in steady motion (DC)
  - Electromagnetic waves: waves excited by charges in time-varying motion



Lecture 2





• transmitter and receiver are connected by a "field."

High-speed, high-density digital circuits:



• consider an interconnect between points "1" and "2"



 Propagation delay
 Electromagnetic coupling
 Substrate modes

- When an event in one place has an effect on something at a different location, we talk about the events as being connected by a "field".
- A *field* is a spatial distribution of a quantity; in general, it can be either *scalar* or *vector* in nature.

Electric and magnetic fields:

- Are vector fields with three spatial components.
- Vary as a function of position in 3D space as well as time.
- Are governed by partial differential equations derived from Maxwell's equations.

• A *scalar* is a quantity having only an amplitude (and possibly phase).

Examples: voltage, current, charge, energy, temperature

• A *vector* is a quantity having direction in addition to amplitude (and possibly phase).

Examples: velocity, acceleration, force

 Fundamental vector field quantities in electromagnetics:

• Electric field intensity  $(\underline{E})$ units = volts per meter (V/m = kg m/A/s<sup>3</sup>)

Electric flux density (electric displacement) (<u>D</u>)
 units = coulombs per square meter (C/m<sup>2</sup> = A s /m<sup>2</sup>)

Magnetic field intensity (<u>H</u>)
 units = amps per meter (A/m)

 Magnetic flux density (<u>B</u>) units = teslas = webers per square meter (T = Wb/m<sup>2</sup> = kg/A/s<sup>3</sup>)

Universal constants in electromagnetics: Velocity of an electromagnetic wave (e.g., light) in free space (perfect vacuum)  $c \approx 3 \times 10^8$  m/s Permeability of free space  $\mu_0 = 4\pi \times 10^{-7} \text{ H/m}$ Permittivity of free space:  $\varepsilon_0 \approx 8.854 \times 10^{-12}$  F/m Intrinsic impedance of free space:  $\eta_0 \approx 120\pi \Omega$ 

# Relationships involving the universal constants:



In free space:

$$\underline{B} = \mu_0 \underline{H}$$

$$\underline{D} = \varepsilon_0 \underline{E}$$



**Obtained** 

- by assumption
- from solution to IE

Solution to Maxwell's equations

**Observable** quantities

#### Maxwell's Equations

- Maxwell's equations in integral form are the fundamental postulates of classical electromagnetics all classical electromagnetic phenomena are explained by these equations.
- Electromagnetic phenomena include electrostatics, magnetostatics, electromagnetostatics and electromagnetic wave propagation.
- The differential equations and boundary conditions that we use to formulate and solve EM problems are all derived from *Maxwell's equations in integral form*.

#### Maxwell's Equations

Various *equivalence principles* consistent with Maxwell's equations allow us to replace more complicated electric current and charge distributions with *equivalent magnetic sources*.

These equivalent magnetic sources can be treated by a generalization of Maxwell's equations. Maxwell's Equations in Integral Form (Generalized to Include Equivalent Magnetic Sources)

$$\oint_{C} \underline{E} \cdot d\underline{l} = -\frac{d}{dt} \int_{S} \underline{B} \cdot d\underline{S} + \int_{S} \underline{K}_{c} \cdot d\underline{S} + \int_{S} \underline{K}_{i} \cdot d\underline{S}$$

$$\oint_{C} \underline{H} \cdot d\underline{l} = \frac{d}{dt} \int_{S} \underline{D} \cdot d\underline{S} + \int_{S} \underline{J}_{c} \cdot d\underline{S} + \int_{S} \underline{J}_{i} \cdot d\underline{S}$$

$$\oint \underline{D} \cdot d\underline{S} = \int_{V} q_{ev} dv$$

$$\oint \underline{B} \cdot d\underline{S} = \int_{V} q_{mv} dv$$

Adding the fictitious magnetic source terms is equivalent to living in a universe where magnetic monopoles (charges) exist.

Continuity Equation in Integral Form (Generalized to Include Equivalent Magnetic Sources)

$$\oint_{S} \underline{J} \cdot d\underline{s} = -\frac{\partial}{\partial t} \int_{V} q_{ev} dv$$

$$\oint_{S} \underline{K} \cdot d\underline{s} = -\frac{\partial}{\partial t} \int_{V} q_{mv} dv$$

• The *continuity equations* are <u>implicit</u> in Maxwell's equations.

## Contour, Surface and Volume Conventions



open surface S bounded by closed contour C
dS in direction given by RH rule



volume V bounded by closed surface S
dS in direction outward from V

## Electric Current and Charge Densities

- $J_c$  = (electric) conduction current density (A/m<sup>2</sup>)
- $J_i$  = (electric) impressed current density (A/m<sup>2</sup>)
- $q_{\rm ev} =$  (electric) charge density (C/m<sup>3</sup>)

## Magnetic Current and Charge Densities

- $K_c$  = magnetic conduction current density (V/m<sup>2</sup>)
- $K_i$  = magnetic impressed current density (V/m<sup>2</sup>)
- $q_{\rm mv} =$  magnetic charge density (Wb/m<sup>3</sup>)

## Maxwell's Equations - Sources and Responses

Sources of EM field:

 $\blacksquare K_i, J_i, q_{ev}, q_{mv}$ 

Responses to EM field:
 *E*, *H*, *D*, *B*, *J*<sub>c</sub>, *K*<sub>c</sub>

Maxwell's Equations in Differential Form (Generalized to Include Equivalent Magnetic Sources)

$$\nabla \times \underline{E} = -\frac{\partial \underline{B}}{\partial t} - \underline{K}_c - \underline{K}_i$$
$$\nabla \times \underline{H} = \frac{\partial \underline{D}}{\partial t} + \underline{J}_c + \underline{J}_i$$
$$\nabla \cdot \underline{D} = q_{ev}$$
$$\nabla \cdot \underline{B} = q_{mv}$$

Continuity Equation in Differential Form (Generalized to Include Equivalent Magnetic Sources)

 $\nabla \cdot \underline{J} = -\frac{\partial q_{ev}}{\partial t}$  $\nabla \cdot \underline{K} = -\frac{\partial q_{mv}}{\partial t}$  $\frac{\partial q_{mv}}{\partial t}$ 

• The *continuity equations* are <u>implicit</u> in Maxwell's equations.

#### Electromagnetic Boundary Conditions



### Electromagnetic Boundary Conditions

 $\widehat{n} \times (\underline{E}_1 - \underline{E}_2) = -\underline{K}_S$  $\widehat{n} \times (\underline{H}_1 - \underline{H}_2) = \underline{J}_S$  $\widehat{n} \cdot \left(\underline{D}_1 - \underline{D}_2\right) = q_{es}$  $\widehat{n} \cdot (\underline{B}_1 - \underline{B}_2) = q_{ms}$ 

## Surface Current and Charge Densities

Can be either sources of or responses to EM field.

Units:

 $K_{s} - V/m$  $J_{s} - A/m$  $q_{es} - C/m^{2}$  $q_{ms} - W/m^{2}$ 

- In time-varying electromagnetics, we consider *E* and *H* to be the "primary" responses, and attempt to write the "secondary" responses *D*, *B*, *J<sub>c</sub>*, and *K<sub>c</sub>* in terms of *E* and *H*.
- The relationships between the "primary" and "secondary" responses depends on the *medium* in which the field exists.
- The relationships between the "primary" and "secondary" responses are called *constitutive relationships*.

Most general constitutive relationships:

 $\underline{D} = \underline{D}(\underline{E}, \underline{H})$  $\underline{B} = \underline{B}(\underline{E}, \underline{H})$  $\underline{J}_{c} = \underline{J}_{c}(\underline{E}, \underline{H})$  $\underline{K}_{c} = \underline{K}_{c}(\underline{E}, \underline{H})$ 

In free space, we have:

 $\underline{D} = \mathcal{E}_0 \underline{E}$  $\underline{B} = \mu_0 \underline{H}$  $\underline{J}_c = 0$  $\underline{K}_c = 0$ 

In a *simple medium*, we have:

 $\underline{D} = \varepsilon \underline{E}$  $\underline{B} = \mu \underline{H}$  $\underline{J}_{c} = \sigma \underline{E}$  $\underline{K}_{c} = \sigma_{m} \underline{H}$ 

• *linear* (independent of field strength)

• *isotropic* (independent of position within the medium)

• *homogeneous* (independent of direction)

• time-invariant (independent of

time)

• *non-dispersive* (independent of frequency)

ε = permittivity = ε<sub>r</sub>ε<sub>0</sub> (F/m)
 μ = permeability = μ<sub>r</sub>μ<sub>0</sub> (H/m)
 σ = electric conductivity = ε<sub>r</sub>ε<sub>0</sub> (S/m)
 σ<sub>m</sub> = magnetic conductivity = ε<sub>r</sub>ε<sub>0</sub> (Ω/m)

A *phasor* is a complex number representing the amplitude and phase of a sinusoid of known frequency.

phasor

 $A\cos(\omega t + \theta) \Leftrightarrow Ae^{j\theta}$ 

time domain

frequency domain

- Phasors are an extremely important concept in the study of classical electromagnetics, circuit theory, and communications systems.
- Maxwell's equations in simple media, circuits comprising linear devices, and many components of communications systems can all be represented as *linear time-invariant (LTI)* systems. (Formal definition of these later in the course ...)
- The eigenfunctions of any LTI system are the complex exponentials of the form:

 $e^{j\omega t}$ 

$$e^{j\omega t} \rightarrow LTI \rightarrow H(j\omega)e^{j\omega t}$$

If the input to an LTI system is a sinusoid of frequency ω, then the output is also a sinusoid of frequency ω (with different amplitude and phase).

A complex constant (for fixed  $\omega$ ); as a function of  $\omega$  gives the frequency response of the LTI system.

The amplitude and phase of a sinusoidal function can also depend on position, and the sinusoid can also be a vector function:

 $\hat{a}_A(\underline{r}) \cos(\omega t - \theta(\underline{r})) \Leftrightarrow \hat{a}_A(\underline{r}) e^{j\theta(\underline{r})}$
# Phasor Representation of a Time-Harmonic Field

 Given the phasor (frequency-domain) representation of a time-harmonic vector field, the time-domain representation of the vector field is obtained using the recipe:

 $\underline{E}(\underline{r},t) = \operatorname{Re}\left\{\underline{E}(\underline{r}) e^{j\omega t}\right\}$ 

# Phasor Representation of a Time-Harmonic Field

- Phasors can be used provided all of the media in the problem are *linear* ⇒ no frequency conversion.
- When phasors are used, integro-differential operators in time become algebraic operations in frequency, e.g.:

$$\frac{\partial \underline{E}(\underline{r},t)}{\partial t} \Leftrightarrow j\omega \underline{E}(\underline{r})$$

# Time-Harmonic Maxwell's Equations

- If the sources are time-harmonic (sinusoidal), and all media are linear, then the electromagnetic fields are sinusoids of the same frequency as the sources.
- In this case, we can simplify matters by using Maxwell's equations in the *frequency-domain*.
- Maxwell's equations in the frequency-domain are relationships between the phasor representations of the fields.

### Maxwell's Equations in Differential Form for Time-Harmonic Fields

 $\nabla \times \underline{E} = -j\omega \underline{B} - \underline{K}_c - \underline{K}_i$  $\nabla \times \underline{H} = j\omega \underline{D} + \underline{J}_c + \underline{J}_i$  $\nabla \cdot \underline{D} = q_{ev}$  $\nabla \cdot \underline{B} = q_{mv}$ 

Maxwell's Equations in Differential Form for Time-Harmonic Fields in Simple Medium

$$\nabla \times \underline{E} = -(j\omega\mu + \sigma_m)\underline{H} - \underline{K}_i$$
$$\nabla \times \underline{H} = (j\omega\varepsilon + \sigma)\underline{E} + \underline{J}_i$$

$$\nabla \cdot \underline{E} = \frac{q_{ev}}{\varepsilon}$$

$$\nabla \cdot \underline{H} = \frac{q_{mv}}{\mu}$$

#### Electrostatics as a Special Case of Electromagnetics



### **Electrostatics**

*Electrostatics* is the branch of electromagnetics dealing with the effects of electric charges at rest.
The fundamental law of *electrostatics* is *Coulomb's law*.

# **Electric Charge**

- Electrical phenomena caused by friction are part of our everyday lives, and can be understood in terms of *electrical charge*.
- The effects of *electrical charge* can be observed in the attraction/repulsion of various objects when "charged."
- Charge comes in two varieties called "positive" and "negative."

# **Electric Charge**

- Objects carrying a net positive charge attract those carrying a net negative charge and repel those carrying a net positive charge.
- Objects carrying a net negative charge attract those carrying a net positive charge and repel those carrying a net negative charge.
- On an atomic scale, electrons are negatively charged and nuclei are positively charged.

# **Electric Charge**

- Electric charge is inherently quantized such that the charge on any object is an integer multiple of the smallest unit of charge which is the magnitude of the electron charge  $e = 1.602 \times 10^{-19}$  C.
- On the macroscopic level, we can assume that charge is "continuous."

### **Coulomb's Law**

- Coulomb's law is the "law of action" between charged bodies.
- Coulomb's law gives the electric force between two point charges in an otherwise empty universe.
- A *point charge* is a charge that occupies a region of space which is negligibly small compared to the distance between the point charge and any other object.



### **Coulomb's Law**

The force on Q<sub>1</sub> due to Q<sub>2</sub> is equal in magnitude but opposite in direction to the force on Q<sub>2</sub> due to Q<sub>1</sub>.



Consider a point charge *Q* placed at the <u>origin</u> of a coordinate system in an otherwise empty universe.
A test charge *Q*<sub>t</sub> brought near *Q* experiences a force:

$$\underline{F}_{\mathcal{Q}_t} = \hat{a}_r \frac{QQ_t}{4\pi\varepsilon_0 r^2}$$



The existence of the force on Q<sub>t</sub> can be attributed to an *electric field* produced by Q.
The *electric field* produced by Q at a point in space can be defined as the force per unit charge acting on a test charge Q<sub>t</sub> placed at that point.

$$\overline{E} = \lim_{\mathcal{Q}_t \to 0} \frac{\overline{F}_{\mathcal{Q}_t}}{\mathcal{Q}_t}$$

The electric field describes the effect of a stationary charge on other charges and is an abstract "action-at-a-distance" concept, very similar to the concept of a gravity field.

The basic units of electric field are *newtons* per coulomb.

In practice, we usually use volts per meter.

For a point charge at the <u>origin</u>, the electric field at any point is given by

 $\overline{E}(r) = \hat{a}_r \frac{Q}{4\pi\varepsilon_0 r^2} = \frac{Q\underline{r}}{4\pi\varepsilon_0 r^3}$ 

For a point charge located at a point P' described by a position vector <u>r'</u>
 the electric field at P is given by



In electromagnetics, it is very popular to describe the source in terms of primed coordinates, and the observation point in terms of unprimed coordinates. As we shall see, for continuous source distributions we shall need to integrate over the source coordinates.

Using the principal of *superposition*, the electric field at a point arising from multiple point charges may be evaluated as

$$\underline{E}(\underline{r}) = \sum_{k=1}^{n} \frac{Q_k \underline{R}_k}{4\pi \varepsilon_0 R_k^3}$$

Charge can occur as *point charges* (C) *volume charges* (C/m<sup>3</sup>) ⇐ most general *surface charges* (C/m<sup>2</sup>) *line charges* (C/m)

#### Volume charge density



 $P \longrightarrow Q_{encl} V$ ,  $P \longrightarrow P$ 

# Electric field due to volume charge density

Lecture 2

 $d\underline{E}(\underline{r}) = \frac{q_{ev}(\underline{r'})dv'\underline{R}}{4\pi\varepsilon_0 R^3}$ 

# Electric Field Due to Volume Charge Density



#### Surface charge density



# Electric field due to surface charge

 $\frac{dS'}{Q_{encl}} \frac{l'}{S'}$ 

density

 $d\underline{E}(\underline{r}) = \frac{q_{es}(\underline{r'})ds'\underline{R}}{4\pi\varepsilon_0 R^3}$ 

# Electric Field Due to Surface Charge Density



Line charge density



#### Electric field due to line charge density



# Electric Field Due to Line Charge Density



- An electric field is a *force field*.
- If a body being acted on by a force is moved from one point to another, then work is done.
- The concept of scalar electric potential provides a measure of the work done in moving charged bodies in an electrostatic field.

The work done in moving a test charge from one point to another in a region of electric field:



In evaluating line integrals, it is customary to take the *dl* in the direction of increasing coordinate value so that the manner in which the path of integration is traversed is unambiguously determined by the limits of integration.



- The electrostatic field is *conservative*:
  - The value of the line integral depends only on the end points and is independent of the path taken.
  - The value of the line integral around any closed path is zero.



 $\oint \underline{E} \cdot d\underline{l} = 0$ 

The work done per unit charge in moving a test charge from point *a* to point *b* is the *electrostatic potential difference* between the two points:

$$V_{ab} \equiv \frac{W_{a \to b}}{q} = -\int_{a}^{b} \underline{E} \cdot d\underline{l}$$

*electrostatic potential difference* Units are volts.

Since the electrostatic field is conservative we can write

$$V_{ab} = -\int_{a}^{b} \underline{E} \bullet d\underline{l} = -\int_{a}^{P_{0}} \underline{E} \bullet d\underline{l} - \int_{P_{0}}^{b} \underline{E} \bullet d\underline{l}$$
$$= -\int_{P_{0}}^{b} \underline{E} \bullet d\underline{l} - \left(-\int_{P_{0}}^{a} \underline{E} \bullet d\underline{l}\right)$$
$$= V(b) - V(a)$$
#### **Electrostatic Potential**

- Thus the *electrostatic potential* V is a scalar field that is defined at every point in space.
- In particular the value of the *electrostatic potential* at any point *P* is given by  $V(\underline{r}) = -\int_{P_0}^{P} \underline{E} \bullet d\underline{l}$   $P_0 \leftarrow \text{reference point}$

#### **Electrostatic Potential**

The *reference point* (P<sub>0</sub>) is where the potential is zero (analogous to *ground* in a circuit).
Often the reference is taken to be at infinity so that the potential of a point in space is defined as

$$V(\underline{r}) = -\int_{\infty}^{P} \underline{E} \bullet d\underline{l}$$

The work done in moving a point charge from point *a* to point *b* can be written as

$$W_{a \to b} = QV_{ab} = Q\{V(b) - V(a)\}$$
$$= -Q\int_{a}^{b} \underline{E} \bullet dl$$

Along a short path of length  $\Delta l$  we have

# $\Delta W = Q\Delta V = -Q\underline{E} \cdot \Delta \underline{l}$ or $\Delta V = -\underline{E} \cdot \Delta l$

Along an incremental path of length dl we have  $dV = -E \cdot dl$ 

Recall from the definition of *directional derivative*:

$$dV = \nabla V \cdot d\underline{l}$$





the "del" or "nabla" operator